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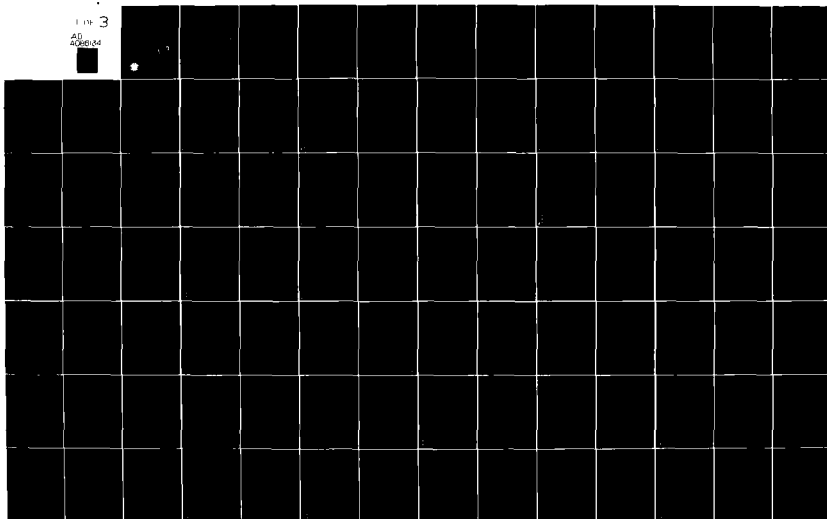
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DESIGN AND IMPLEMENTATION OF A SPEECH CODING ALGORITHM AT 9600 --ETC (11)  
APR 80 J L MELSA, D L COHN, A ARORA DCA100-79-C-0005

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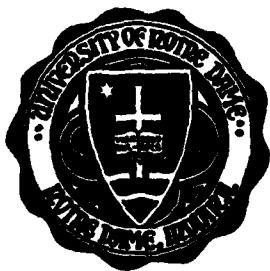
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FINAL REPORT  
VOLUME 2

DESIGN AND IMPLEMENTATION  
OF A SPEECH CODING ALGORITHM  
AT 9600 B/S

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**ELECTRICAL ENGINEERING**

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VOLUME 2  
DESIGN AND IMPLEMENTATION  
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Prepared for

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<p>→ This report describes a speech coding algorithm for digital transmission of speech at a rate of 9600 bits per second and the implementation of this algorithm on a speech processing system. The algorithm combines:</p> <p>Pitch extraction loop, Pitch compensating adaptive quantizer, Sequentially adaptive linear predictor, Adaptive source coding,</p>		

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✓ to generate very high quality speech output. Although each of these elements has been previously applied to speech coding, the combination of all four of these elements has not been studied before. The speech coding algorithm has been implemented on a pair of CSPI MAP 300 Array Processors in real-time in the full-duplex mode.

This report has been bound in two volumes. The first volume contains the narrative description of the algorithm and its development and includes Chapters 1 through 11 and Appendices A through D of the report. The second volume describes the real-time MAP implementation and includes Chapters 12 and Appendices E through G. ✓

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## ABSTRACT

This report describes a speech coding algorithm for digital transmission of speech at a rate of 9600 bits per second and the implementation of this algorithm on a speech processing system.

The algorithm combines

- Pitch extraction loop
- Pitch compensating adaptive quantizer
- Sequentially adaptive linear predictor
- Adaptive source coding

to generate very high quality speech output. Although each of these elements has been previously applied to speech coding, the combination of all four of these elements has not been studied before. The speech coding algorithm has been implemented on a pair of CSPI MAP 300 Array Processors in real-time in the full-duplex mode.

This report has been bound in two volumes. The first volume contains the narrative description of the algorithm and its development and includes Chapters 1 through 11 and Appendices A through D of the report. The second volume describes the real-time MAP implementation and includes Chapters 12 and Appendices E through G.

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## CHAPTER 12

### THE REAL-TIME IMPLEMENTATION

#### 12.1 Introduction

In this chapter, the final form of the real-time implementation of the PARC algorithm in a full duplex mode will be presented. The whole implementation will be decomposed into four parts. Each part is described in detail in the following sections. Block diagrams, flow charts and timing diagrams are given to help reader understand the implementation. The program listings are in Appendix G.

Before presenting the implementation, the system components used will be described. A MAP-300 (Macro Arithmetic Processor) produced by Computer Signal Processing, Inc. is used to implement the speech coding algorithm (see Table 12.1). A host computer and MAP-300 system block diagram is shown in Fig. 12.1. The MAP-300 consists of six programmable processing elements as well as memory and peripherals:

- A. A Central Processing Unit (CSPU) functions as the executive controller by interpreting commands from the host computer, setting up and scheduling the other processors, and performing arithmetic and logic operations.
- B. An Arithmetic Processor (AP) consists of two subprocessors. An Arithmetic Processing Unit (APU) carries out the floating point arithmetic calculations. An Arithmetic Processing Scroll (APS) is a data addressing device for the APU.
- C. An Input/Output Scroll (IOS-2) transfers bit streams into or out of a modem.
- D. An Analog Data Acquisition Module (ADAM) samples and quantizes input analog signals into digital signals and stores them into main memory.

Table 12.1  
MAP-300 Speech Processing System

Item No.	Qty.	Model Number	Description
1	1	1030	MAP-300 Processor
2	1	2030	8K x 32 MOS Memory
3	1	2050	16K x 32 MOS Memory
4	1	2203	8K x 32 MOS Memory
5	1	2120	2K x 32 Bipolar Memory
6	1	3100	PDP-11 Interface
7	1	4020	Model 2SM/ I/O Scroll
8	2	4040	Bus Switch
9	1	5120	Analog Data Acquisition Module
10	1	5130	Analog Output Module
11	1	6100	Expansion Chassis
12	1	6200	Auxiliary Power Supply
13	1	03-1360585	GTE Speech Processing Interface

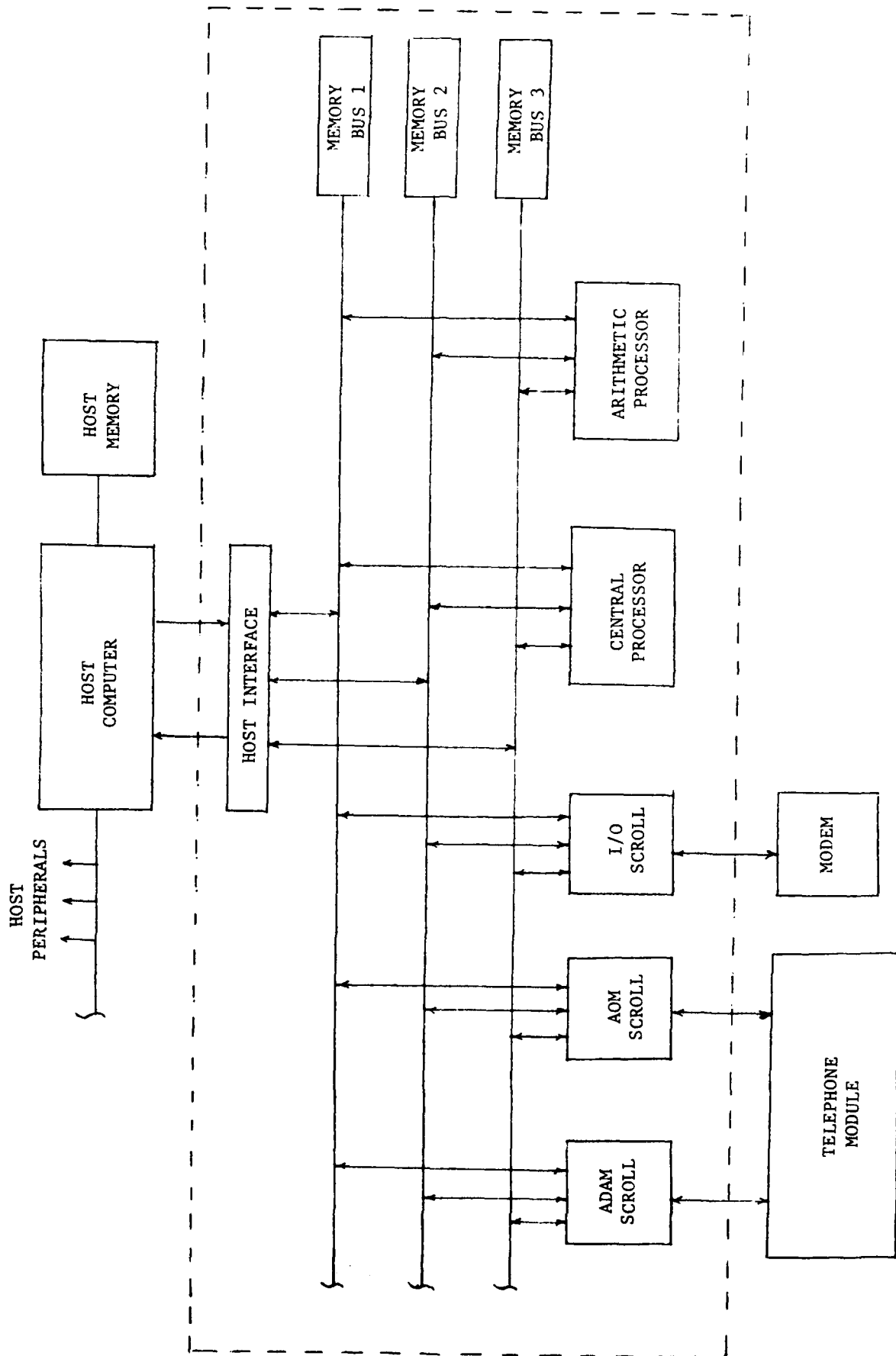


Fig. 12.1 MAP-300 System Block Diagram

- E. An Analog Output Module (AOM) converts input digital signals into analog signals and outputs them to a telephone module.
- F. A Host Interface Scroll (HIS) acts as a communication and data transfer medium between the host computer and the MAP-300 system.

This array processor system provides two classes of software. The first class is the software designed specifically for array processing. It is an executive-driver-subroutine package resident in the MAP-300 and in the host computer which permits direct calling of routines to perform arithmetic operation, to manage MAP memory, to define even higher level routines. A MAP user can execute array processing operations with simple Fortran calls in the host computer. The sophisticated programmer even can implement his own processing algorithms in MAP assembly languages. To implement the PARC digitization system, some new array and non-array functions, which are described later, are employed. The second class consists of utility programs including a cross-assembler and a cross-simulator. These may be used to add new routines to the array processing library.

The array processor can be used as a peripheral to a host computer, using host peripherals for data storage and interface for data and commands transfer between them. However, after initialization, it can stand alone by using proper control functions in the host.

The underlying design principles of the real-time implementation are as follows: First, in order to study system performance, the flexibility of changing system parameters such as speech algorithm parameters, buffer sizes and buffer starting locations must be provided. Second, in order to be in the real-time mode, the arithmetic execution time and the overhead time have to be reduced. The arithmetic execution time can be

decreased by efficiently utilizing the arithmetic processors. The overhead time can be decreased by utilizing all processors as asynchronously and as simultaneously as possible. However, the necessary synchronization between processors has to be carefully considered.

After several months of study, the final real-time PARC communication system consists of the following programs:

1. Host programs: Fortran PARC main program  
Fortran PARC host support program
2. AP programs: PARC-transmitter pitch computation program  
PARC-transmitter speech digitization program  
PARC-receiver
3. CSPU programs: Encoder program  
Decoder program  
Synchronization program  
Transmitter buffer pointers update program  
Receiver buffer pointers update program
4. IOS programs: ADAM program  
ADM program  
IOS-2 program

The main function of the host Fortran programs is to initialize the MAP-300 system with the real-time PARC algorithm, to set up the proper command sequences and to initiate them. After that, the MAP-300 system can execute the PARC without any further commands from the host computer. The two PARC-transmitter programs and the PARC-receiver program require sophisticated arithmetic operations and will be executed in the AP. Those programs requiring logic and bit operations include encoder, decoder, synchronizer and address pointers update programs. These will

be executed in the CSPU. A/D converting, D/A converting and bit-transfer will be executed in the ADAM, the AOM and the IOS-2 respectively. These five processors operate in parallel. The host Fortran modules will be described below; they present the whole picture of the PARC. The rest of the programs will be presented in the following sections.

The flow chart of the real-time PARC main program is shown in the Fig. 12.2. The module can be divided into two steps: An initialization step and a processing step. In each step, each processor has its own role.

1. The initialization step:

In this step, the host computer will initialize the whole algorithm by reading in system parameters, configuring logical buffers, initializing logical buffers, loading ADAM and AOM, and creating appropriate command sequences called function lists. The logical buffers and the function lists, which are fairly complicated, will be described later. In this step, only three processors in the MAP-300 system have been used as follows:

- A. The CSPU acts as the resource controller. Responding to a host command, it loads an A/D program to the ADAM, loads a D/A program to the AOM, configures the logical buffers, and loads appropriate arithmetic functions into the AP.
- B. The AP executes these arithmetic functions which will reset the logical buffers.
- C. The HIS acts as an interface between the host computer and the MAP-300.

The Fortran host support program, which is the host support module for those new array and non-array functions in the real-time PARC



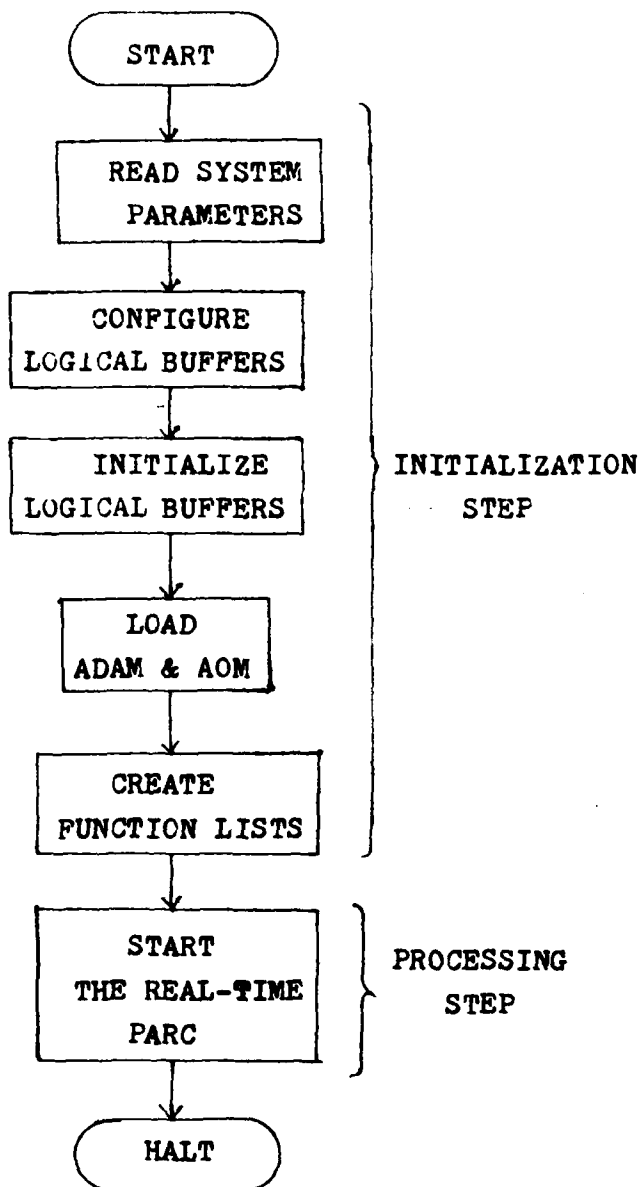


Fig. 12.2 The Flow Chart of the Main Program

algorithm, interfaces the main program to the host/MAP driver module.

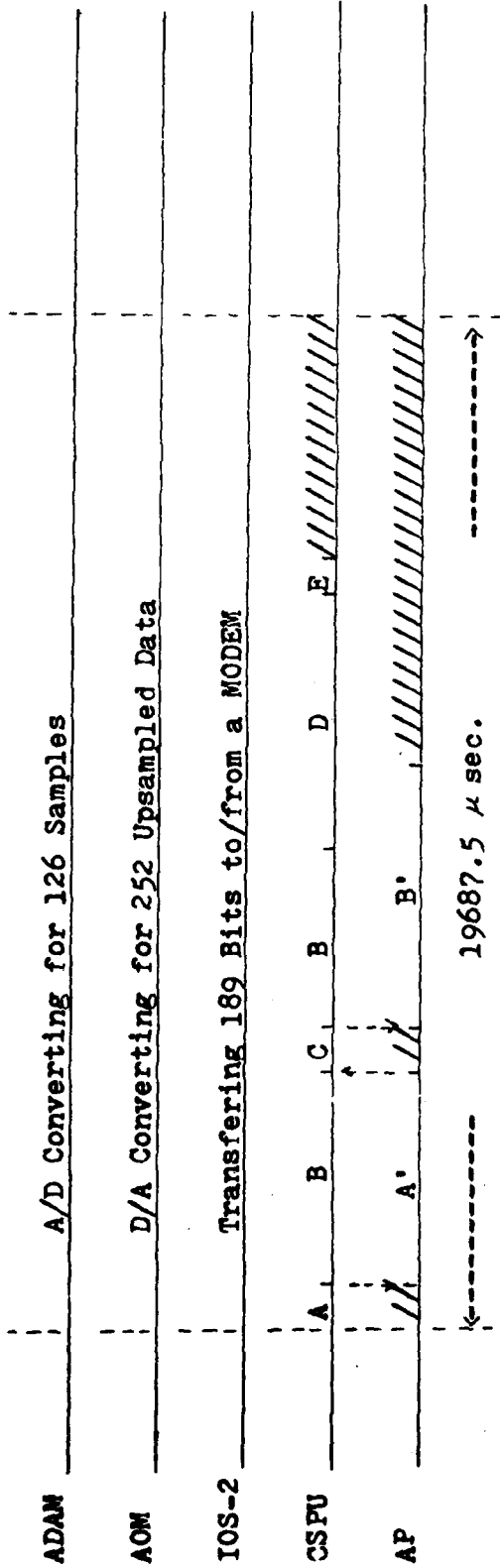
The main functions of this support program are as follows:

- 1) Check each argument for the proper range and return error code.
- 2) Pack arguments for the MAP in a Function Control Block (FCB)
- 3) Determine any host absolute addresses that must be evaluated while constructing the Data Control Block (DCB).
- 4) Pass DCB to the host/MAP driver.

2. The processing step:

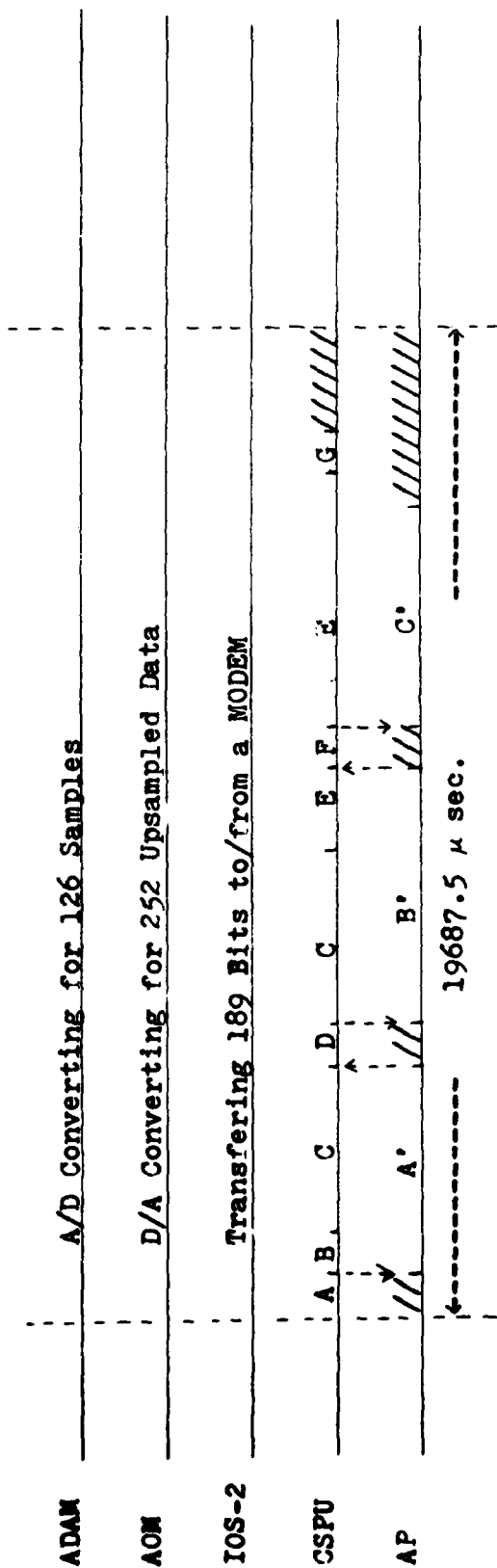
After initialization, the MAP-300 can execute the real time PARC algorithm without any further commands from the host computer. Because of the fixed delay for the whole system (refer to Section 2.2), a fixed time slot has been chosen as a main parameter to synchronize all the processors in the MAP-300 system as shown in Fig. 12.3 and Fig. 12.4. In each time slot, a particular function list, which is described below, will be executed. This fixed time slot is set to be 19687.5 microseconds which is precisely the period for ADAM to process 126 samples, the period for AOM to process 252 upsampled data, and the period for IOS-2 to process 189 bits.

The function lists, whose relationships are shown in Fig. 12.5, are eight sets of command sequences. When the real-time PARC is initiated, the first function list, which starts the ADAM, the AOM and the IOS-2, is executed. Afterward, the main control function list (the second function list) is executed by the CSPU. This function list assures the synchronization of the receiver. The execution of the list is as follows:



- A: Load the APU and the APS with the Pitch Computation Program  
 B: Encoder  
 C: Load the APU and the APS with the Speech Digitization Program  
 D: The Channel Synchronization Program  
 E: Update the PARC-Transmitter Address Pointers  
 A': The Pitch Computation Program  
 B': The Speech Digitization Program

Fig. 12.3 The Timing Diagram for the Synchronization Operation



- A: Load the APU and the APS with the Pitch Computation Program
- B: Update the PARC-Receiver Address Pointers
- C: Encoder
- D: Load the APU and the APS with the Speech Digitization Program
- E: Decoder
- F: Load the APU and the APS with the PARC-Receiver Program
- G: Update the PARC-transmitter Address Pointers
- A': The Pitch Computation Program
- B': The Speech Digitization Program
- C': The PARC-Receiver Program

Fig. 12.4 The Timing Diagram for the Normal PARC Operation

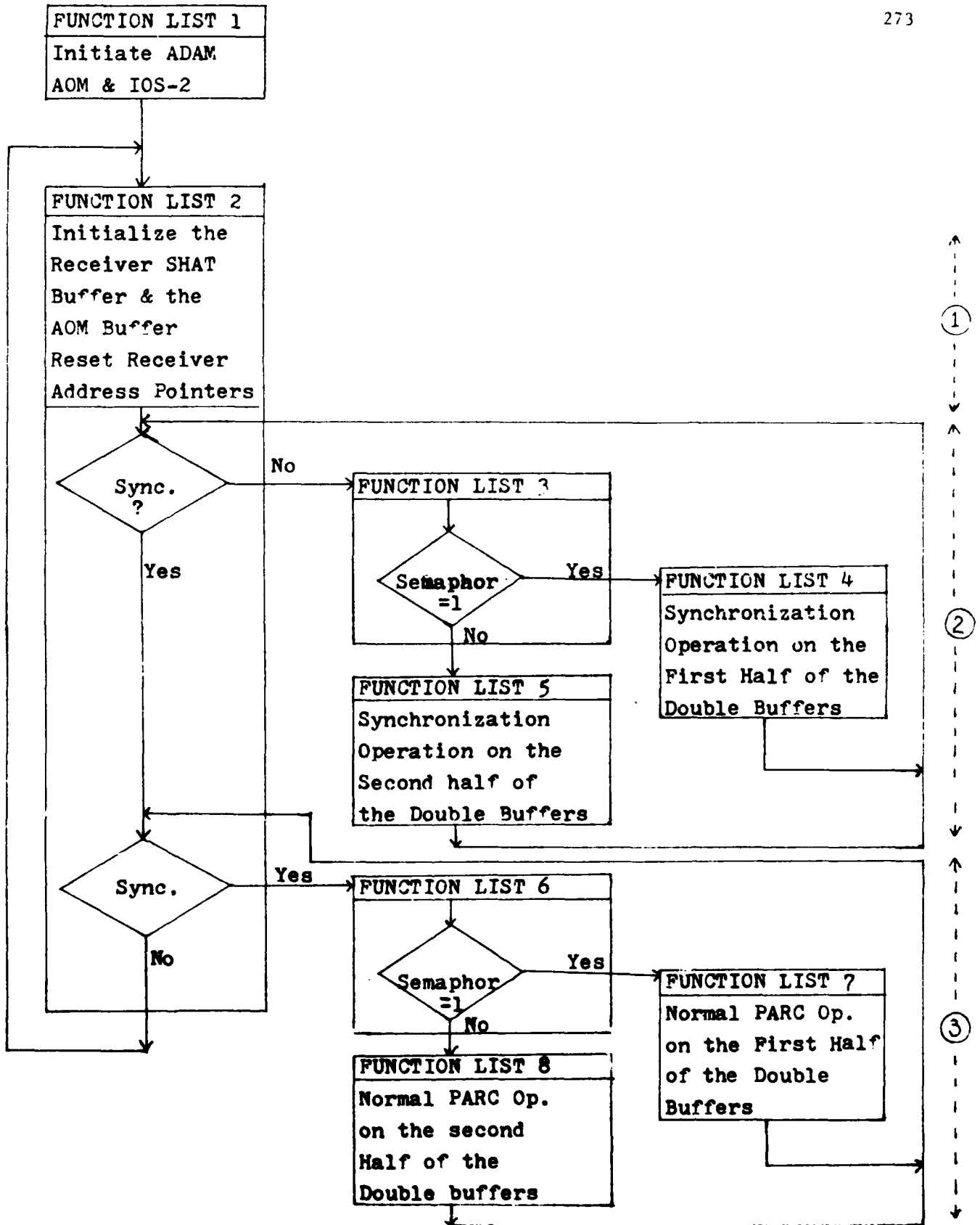


Fig. 12.5

The Flow Chart of Function Lists

1. It initializes the receiver SHAT buffer and the AOM buffer.  
Also, it resets the receiver address pointers.
2. If the channel synchronization does not exist, it keeps executing the synchronization operation until a channel synchronization is set. The synchronization operation consists of the PARC-transmitter, the encoder and the synchronizer.
3. If the channel synchronization exists, it keeps executing the normal PARC operation until a channel synchronization is lost.  
The normal PARC operation consists of the PARC-transmitter, the encoder, the decoder and the PARC-receiver.
4. Go to 1.

Because of parallel data processing which speeds up the whole system (refer to the Section 2.2), the double buffering technique is employed. Therefore, the synchronization operation and the normal PARC operation each consists of three function lists: A control function list, a function list which operates on the first half of the double buffers and a function list which operates on the second half of the double buffers. The control function list checks a semaphore which resides in the MAP memory and then executes a function list which will operate on the proper buffers. The reason for this is to have a continuity of data flow for the PARC-transmitter. For instance, suppose the receiver loses the channel synchronization after the normal PARC operation on the first half of the double buffers. Then the main control function list executes the synchronization operation. The control function of the synchronization operation checks the semaphore and then executes the synchronization operation on the second half of the double buffers. So, the transmitter

gets a continuous data flow. The main control function list will keep executing until the MAP-300 system is terminated.

In the synchronization operation, which consists of the function lists 3, 4 and 5 (shown in Fig. 12.3), the role of each processor in a time slot is described as follows:

- 1) The ADAM samples and quantizes the input analog signal from the telephone module and stores these samples into MAP main memory. In a time slot, it produces 126 quantized samples.
- 2) The AOM acts as a D/A converter and outputs 252 silence samples since no information flows into the receiver.
- 3) The IOS-2 acts as an input/output interface between the MAP-300 and the channel modem. In a time slot, it transfers 189 bits out of the encoder bit buffer and reads 189 bits into the decoder bit buffer.
- 4) The CSPU functions as follows in sequence:
  - A: It loads the AP with the pitch computation program.
  - B: It executes the encoder. However, upon request from an APU interrupt, it suspends the current operation and
  - C: Loads the AP with the speech digitization program.  
It restarts the encoder after the loading.
  - D. It executes the channel synchronization program.
  - E. It updates the PARC-transmitter address pointers.
- 5) The AP executes the arithmetic part of the PARC-transmitter. After finishing each program, it will interrupt the CSPU to indicate that it is free for the next operation, if any. In this operation, the AP has two jobs:

A: The pitch computation program.

B: The speech digitization program.

These five processors function in parallel. The ADAM, AOM and IOS-2 operate continuously without any interrupt. However, the CSPU and the AP have to finish their own job inside the time slot in order to be in real-time.

The normal PARC operation (shown in Fig. 12.4) which consists of the function lists 6, 7 and 8, has the same ADAM and IOS-2 operation as the synchronization operation. However, the CSPU, the AOM and the AP have different operations as follows:

- 1) The ADAM samples and quantizes the input analog signal from telephone module and stores these samples into MAP main memory. In a time slot, it produces 126 quantized samples.
- 2) The AOM acts as a D/A converter and outputs 252 unsampled reconstructed speech samples to the telephone module.
- 3) The IOS-2 acts as an input/output interface between the MAP-300 and the channel modem. In a time slot, it transfers 189 bits out of the encoder bit buffer and reads 189 bits into the decoder bit buffer.
- 4) The CSPU functions as follows in sequence:
  - A: It loads the AP with the pitch computation program.
  - B: It updates the receiver address pointers.
  - C: It executes the encoder. However, upon request from an APU interrupt, it suspends the current operation and
  - D: Loads the AP with the speech digitization program. It restarts the encoder after the loading.



- E. It executes the decoder. Upon request from an APU interrupt, it suspends the current operation and
  - F. Loads the AP with the PARC-receiver program. It restarts the decoder after the loading.
  - G. It updates the transmitter address pointers.
- 5) The AP executes the PARC-transmitter and the PARC-receiver. After finishing each program, it will interrupt the CSPU to indicate that it is free for the next processing, if any. In this operation, the AP has three jobs:
- A: The pitch computation program.
  - B: The speech digitization program.
  - C: The PARC-receiver program.

In this operation, the timing control is very important which will be discussed in the next section.

The subsequent sections will describe each of the subsystems in the real-time PARC system. The next section explains the design of the PARC-transmitter. The complicated buffer system, buffer control and the speech digitization will also be described. The corresponding noiseless source encoder will be explained in Section 12.4.

Section 12.3 describes the design of the PARC-receiver. Although some parts of the system are the same as in the transmitter, the different design of the buffering and upsampling will be depicted. The corresponding noiseless source decoder will be explained in Section 3.5.

## 12.2 The PARC-Transmitter

In this section, the main line of the real-time PARC-Transmitter, which resides in the AP, will be presented. The corresponding encoder will be discussed in Section 12.4. The block diagram of the PARC algorithm is shown in Fig. 2.2 and discussed in Chapter 2.

Because of the limit on the size of the AP memory, the whole PARC-Transmitter algorithm cannot be implemented as a single AP program. So, the PARC-Transmitter has to be cut into two subprograms, namely, the pitch computation program and the speech digitization program, as shown in Fig. 12.6. Those portions of the algorithm which operate on blocks of speech samples will be put in the pitch computation program. Those portions include: input gain factor calculation, system noise reducer, adaptive filter and pitch extractor. These elements of the algorithm which process speech sample-by-sample will be combined into the speech digitization program. These elements are the adaptive quantizer, the inverse quantizer, the adaptive predictor and the pitch extraction.

Before any further description of the design of this PARC-Transmitter, the buffer system has to be depicted. There are seven buffers employed by the PARC-Transmitter as shown in Table 12.2.

Among them, ADAM, LEVEL and BIT buffers are double buffers which allow one processor to fill one half of the buffer while another processor processes on the other half. The SAMPLE, VHAT and SHAT buffers are circular buffers which allow continuous access. However, the additional address pointers, which indicate the starting locations of those circular buffers at the beginning of a time slot, have to be considered. The PARAMETER buffer is a single buffer which stores of system parameters such as predictor coefficients, quantizer output

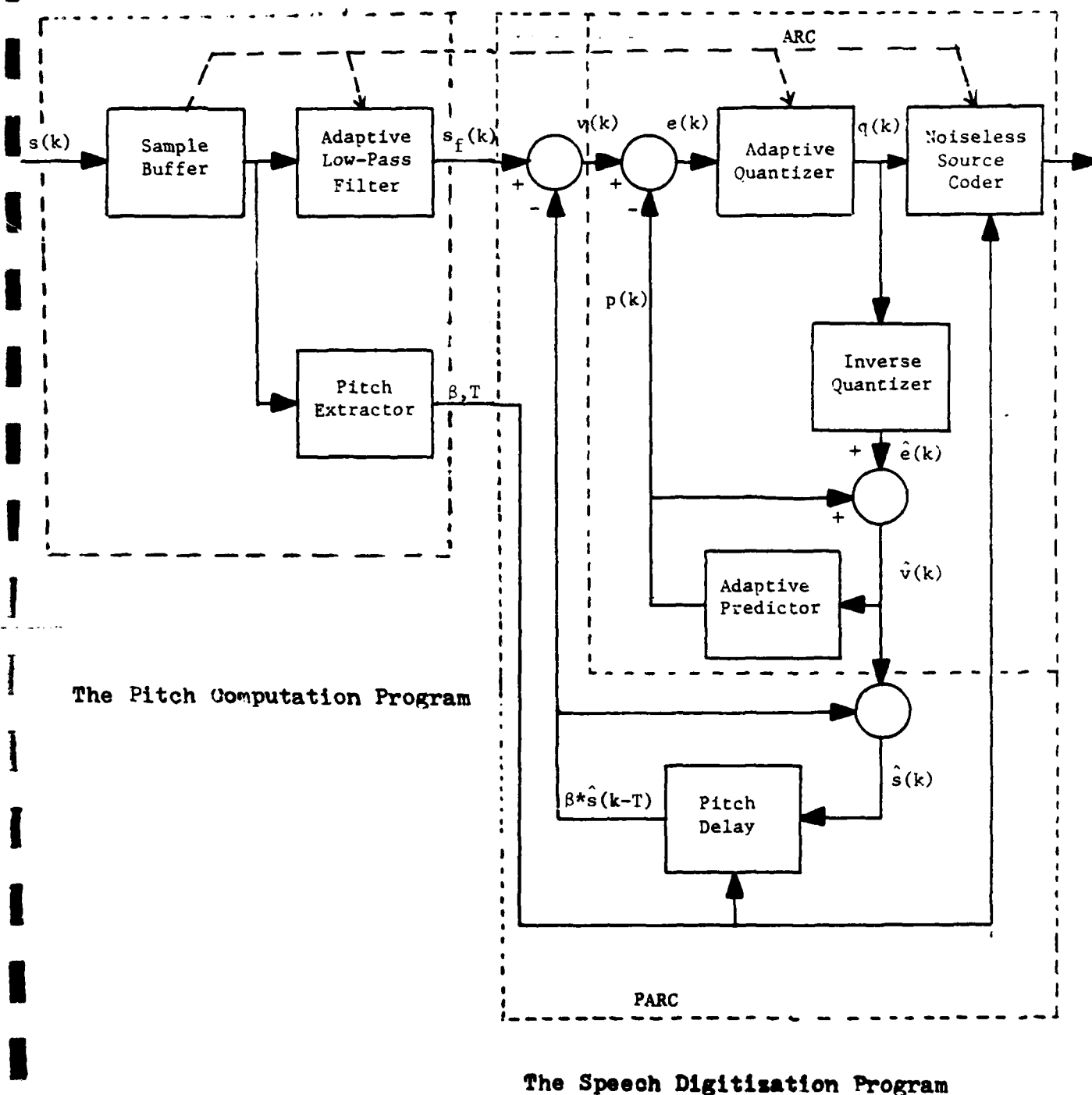


Fig. 12.6 THE BLOCK DIAGRAM OF THE PARC

Table 12.2 Buffer Configuration in the PARC-Transmitter

Name	Bus #	Starting Location	Ending Location	Buffer Size	Buffer Type
ADA1	3	3072 3198	3197 3323	126 126	Double Buffers, Short Floating Point
SAMPLE	3	0	1023	1024	Circular Buffer, Short Floating Point
VHAT	2	0	1023	1024	Circular Buffer, Short Floating Point
SHAT	3	1024	2047	1024	Circular Buffer, Short Floating Point
PARAMETER	2	3072	3231	20	Single Buffer, Long Floating Point
LEVEL	1	25000 27000	25599 27599	600 600	Double Buffer, Long Fixed Point
BIT	1	25700 27700	25899 27899	200 200	Double Buffers, Long Fixed Point

scaling factors, quantizer expansion factors, and the number of bits associated to each quantizer level.

The PARC-Transmitter employs four processors: The ADAM, the AP, the CSPU and the IOS-2. In order to achieve parallel processing, the double buffering technique is used. The function of these buffers associated to the processors at a time slot is shown in Fig. 12.7. At a time slot, the following processes are executed in parallel:

1. While the ADAM is filling a half of the ADAM buffer, the AP is accessing the other half.
2. While the AP is filling a half of LEVEL buffer, the CSPU is accessing the other half.
3. While the CSPU is filling a half of the BIT buffer, the IOS-2 is accessing the other half.

In the next two subsections, the pitch computation program and the speech digitization program will be described. The complicated buffer controller will also be presented.

#### 12.2.1 The Pitch Computation Program

The pitch computation program contains the gain controller, a noise reducer, a buffer controller, the adaptive filter and the pitch extractor. The APU flow chart and the corresponding APS flow chart, including the controlling flows are depicted in Figs. 12.8 & 12.9. The detail functions are described as follows and the parallel processing is shown:

1. In response to the function list, the CSPU loads the APU and the APS modules of the pitch computation program into the APU and the APS respectively.
2. The CSPU then sets flag RI which will initiate the APS module.

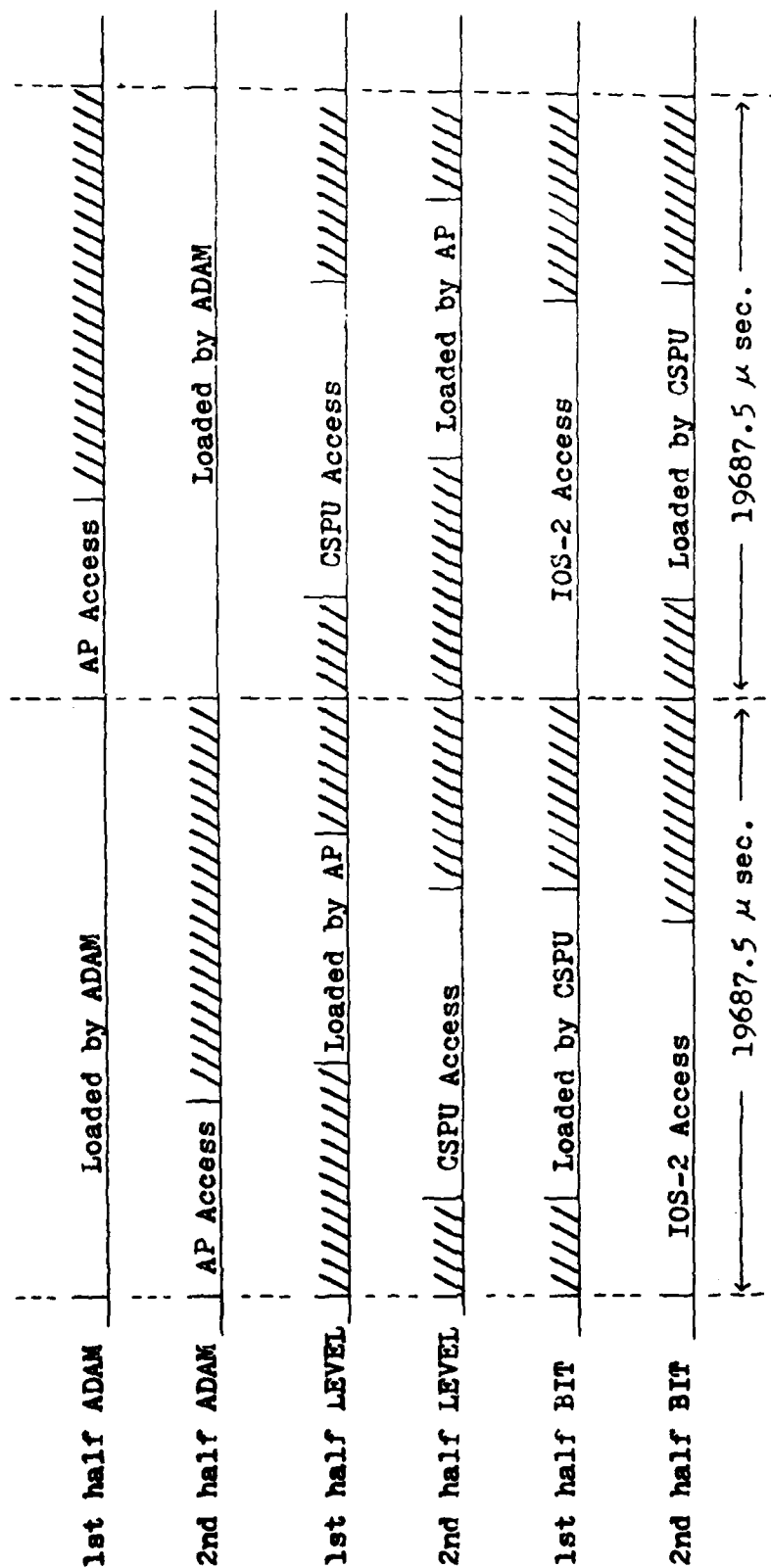


Fig. 12.7 The Double Buffering in the PARC-transmitter

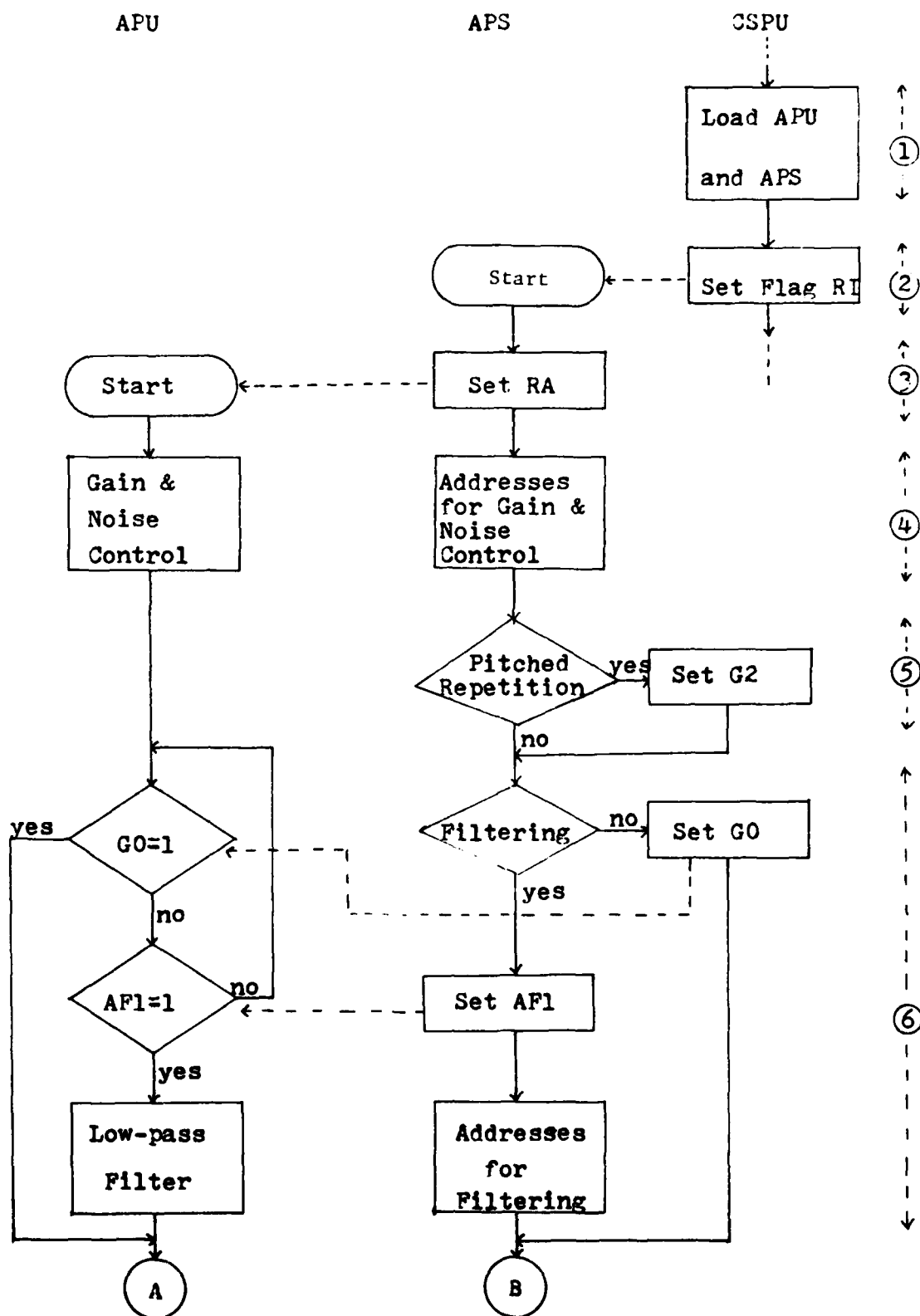


Fig. 12.8a The Flow Chart of the Pitch Computation Program

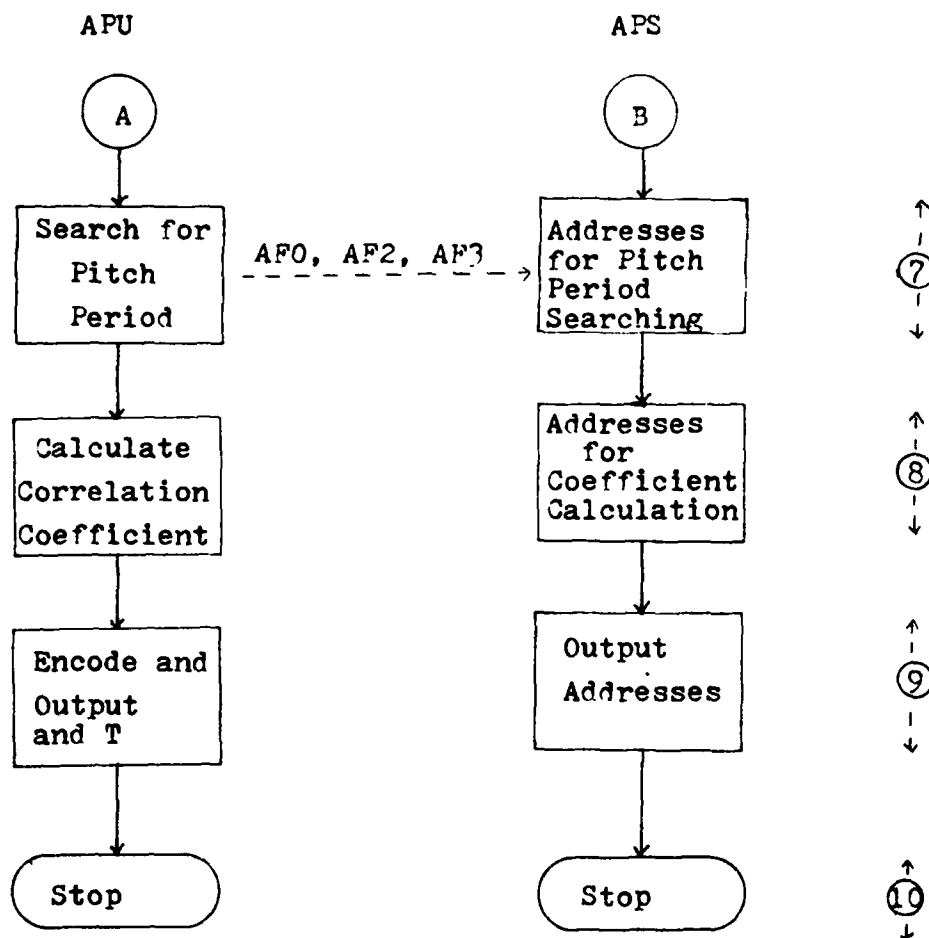


Fig. 12.8b The Flow Chart of the Pitch Computation Program



3. The APS module sets flag RA which will start the APU module.
4. The APS produces the addresses of the noise reducing parameter, the gain factor, 126 input data addresses from the ADAM buffer and 126 output data addresses to the SAMPLE buffer.

The APU reads 126 input samples whose addresses are given by the APS, reduces their noise, multiplies by the gain factor and outputs to the SAMPLE buffer. The input samples from the ADAM are 11-bit precision plus a sign bit in a range of  $[-2047/2048, 2048/2048]$ . After being read by the AP, these are converted into 32-bit floating point numbers.

5. The APS checks the fullness of the SAMPLE buffer, sets the flag G2 if it is over the pitch repetition threshold.
6. The APS again checks the fullness of the SAMPLE buffer. If it is under the filtering threshold, the APS sets the flag GO and jumps to Step 7. If it is over the threshold, the APS sets the flag AF1 and produces addresses for the filtering. The APU waits for the signals from the APS. If the flag GO is set, it goes to Step 7. Otherwise, it executes the filtering process which is described in Section 2.3.

7. The APS produces addresses for the data used to compute the pitch period. The APU computes the pitch period using the AMDF technique (refer to Section 2.4). In order to speed up the whole real-time system, all processors have to be utilized as asynchronously and as simultaneously as possible., i.e., the minimum use of the communication flags between the APU and the APS. However, because of the limit on the number of the registers in the APS, three flags are used in this portion to search for the pitch period as shown in Fig. 3.9. In this block, the APU determines how many iterations are left to be executed. The APS has to wait for the information, the flags AFO and AF1, at the end of each iteration.
8. The APS produces addresses for the data used to calculate the pitch correlation coefficient. If the flag G2, which indicates the pitched repetition, is set, it produces addresses starting a pitched repetition block behind. The APU calculates the pitch correlation coefficient.
9. The APS produces output addresses. The APU encodes the pitch period and the pitch correlation coefficient and outputs them to the MAP memory.
10. The AP interrupts the CSPU to indicate that it is finished.

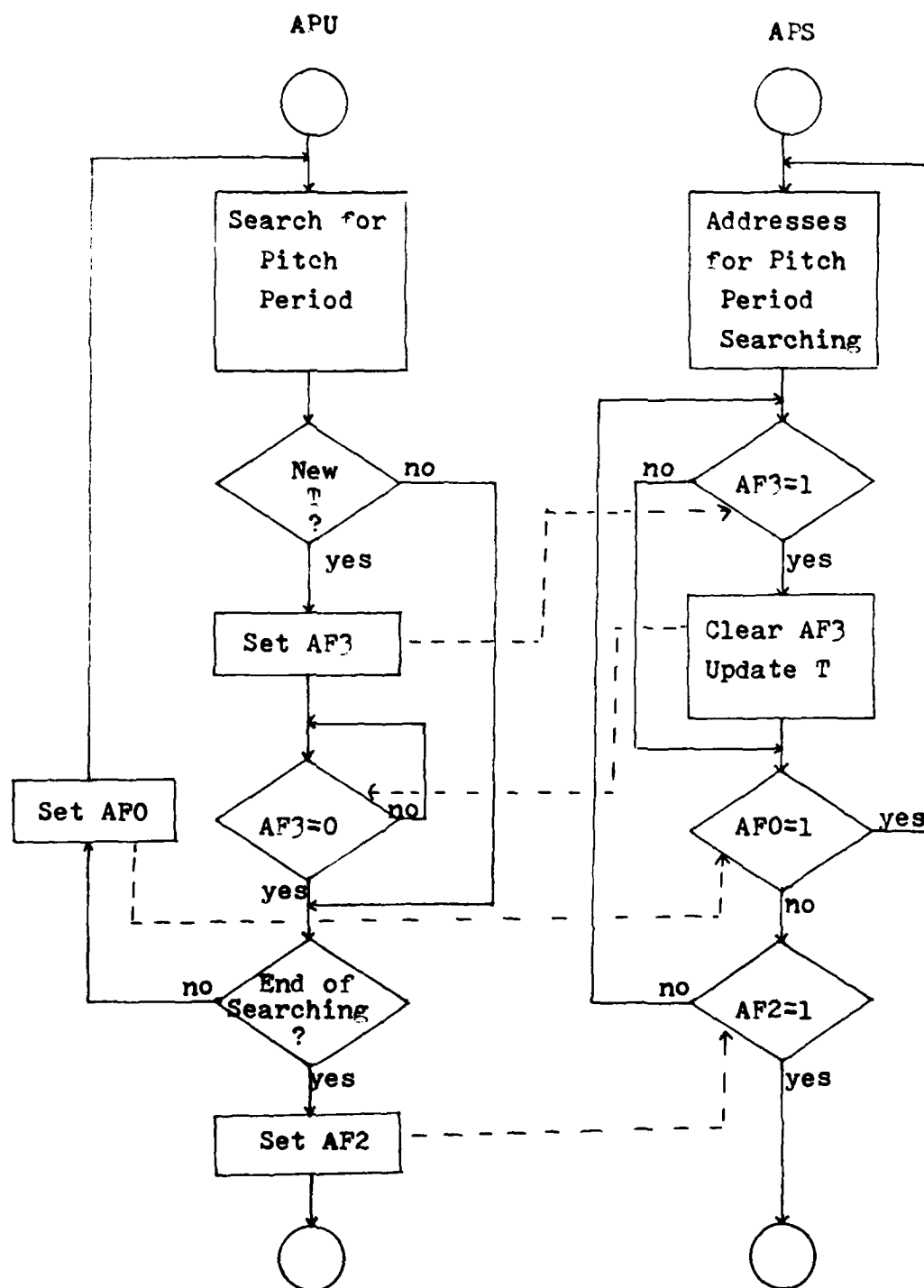


Fig. 12.9 The Flow Chart of the Pitch Period Searching Loop

### 12.2.2 The Speech Digitization Program

The speech digitization program contains the pitched repetition, the adaptive predictor, a maximum number of processed samples controller, a reciprocal function, the pitch extraction, the adaptive quantizer, the inverse adaptive quantizer, the bit buffer controller, the underflow controller, and a parameter update. The APU and the APS flow chart including the control flows are depicted in the Fig. 12.10 because the number of samples which are processed by the transmitter varies in each time slot, the flags APO, AF3 and G1 are used to communicate between the APU and the APS. The flag APO, which is controlled by the APU, is used to indicate the beginning of the digitization loop. The flag G1, which is controlled by the APU and the APS, is used to indicate an underflow of the sample biffer or reaching the maximum number of samples permitted in the time slot. The flag AF3, which is controlled by the APU, is used to indicate that at least 157 information bits have been generated.

The detail functions are as follows:

1. In response to the function list, the CSPU loads the APU and the APS modules of the speech digitization program into the APU and the APS respectively.
2. The CSPU then sets the flag RI which will initiate the APS module.
3. The APS module sets the flag RA which will start the APU module.
4. The APS produces the addresses of the system counters. The APU reads in the system counters. The system counters are the BIT counter, SAMPLE counter and the LEVEL counter. Because the fixed time slot is used as the main parameter for the

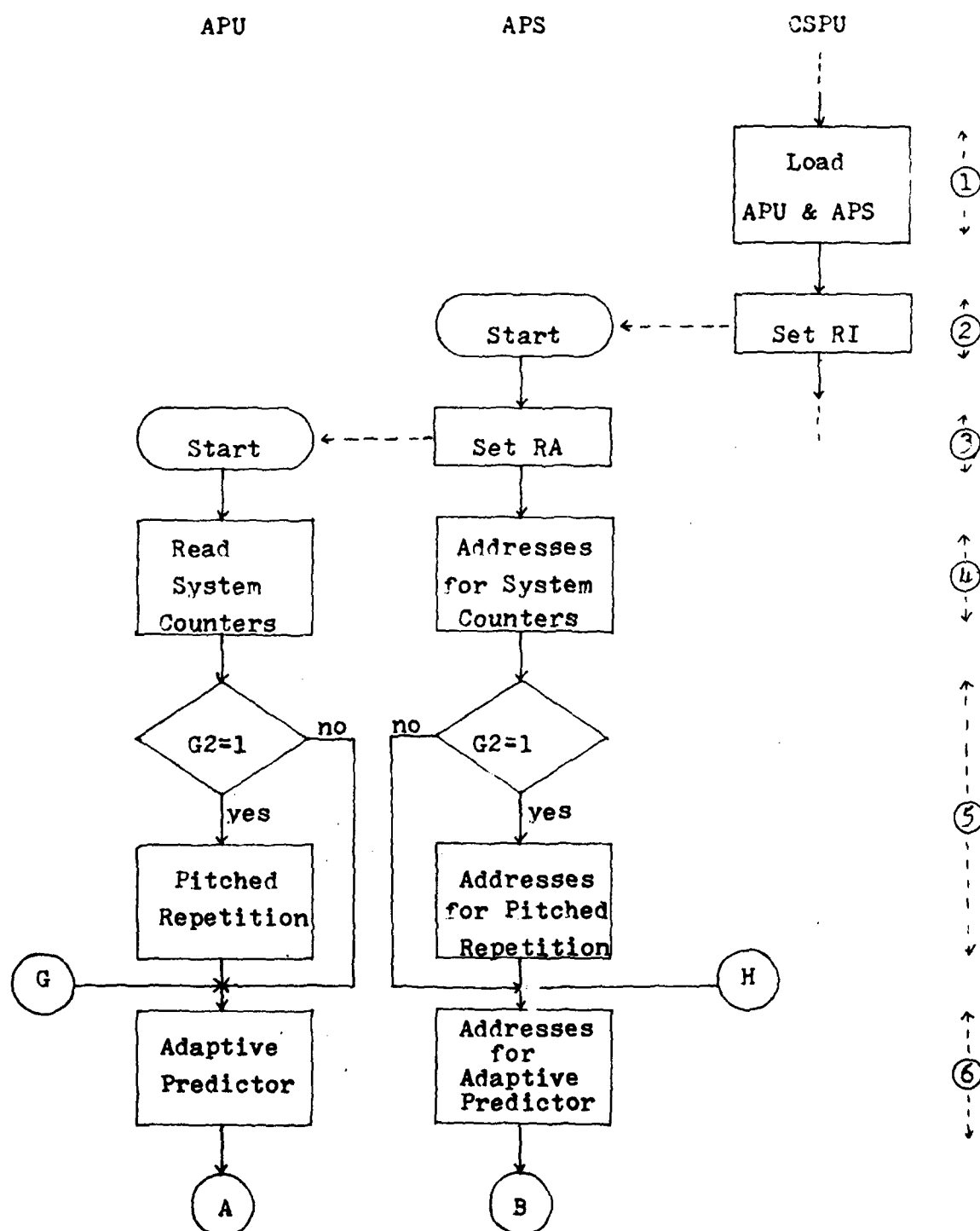


Fig. 12.10a The Flow Chart of the Speech Digitization Program

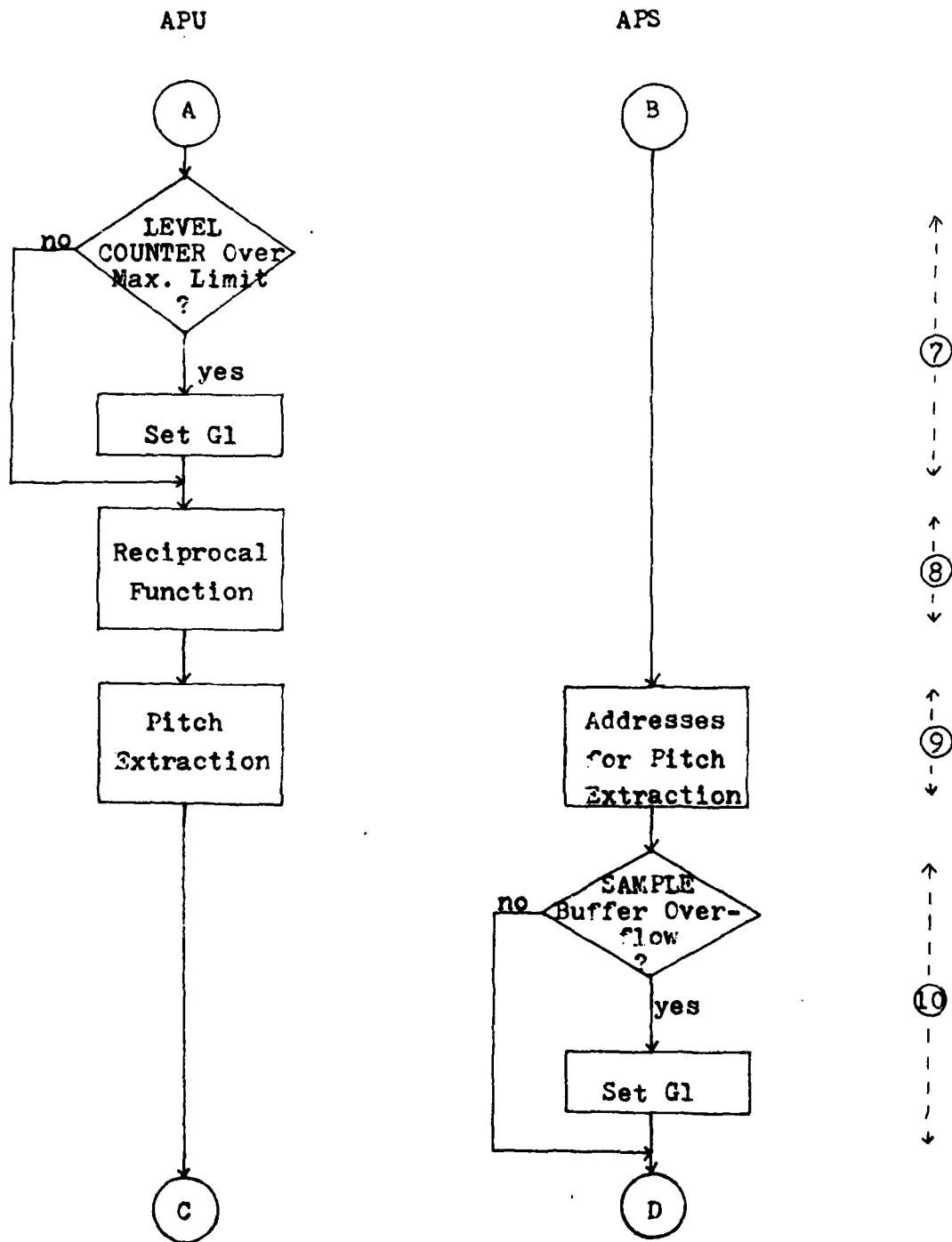


Fig. 12.10b The Flow Chart of the Speech Digitization Program

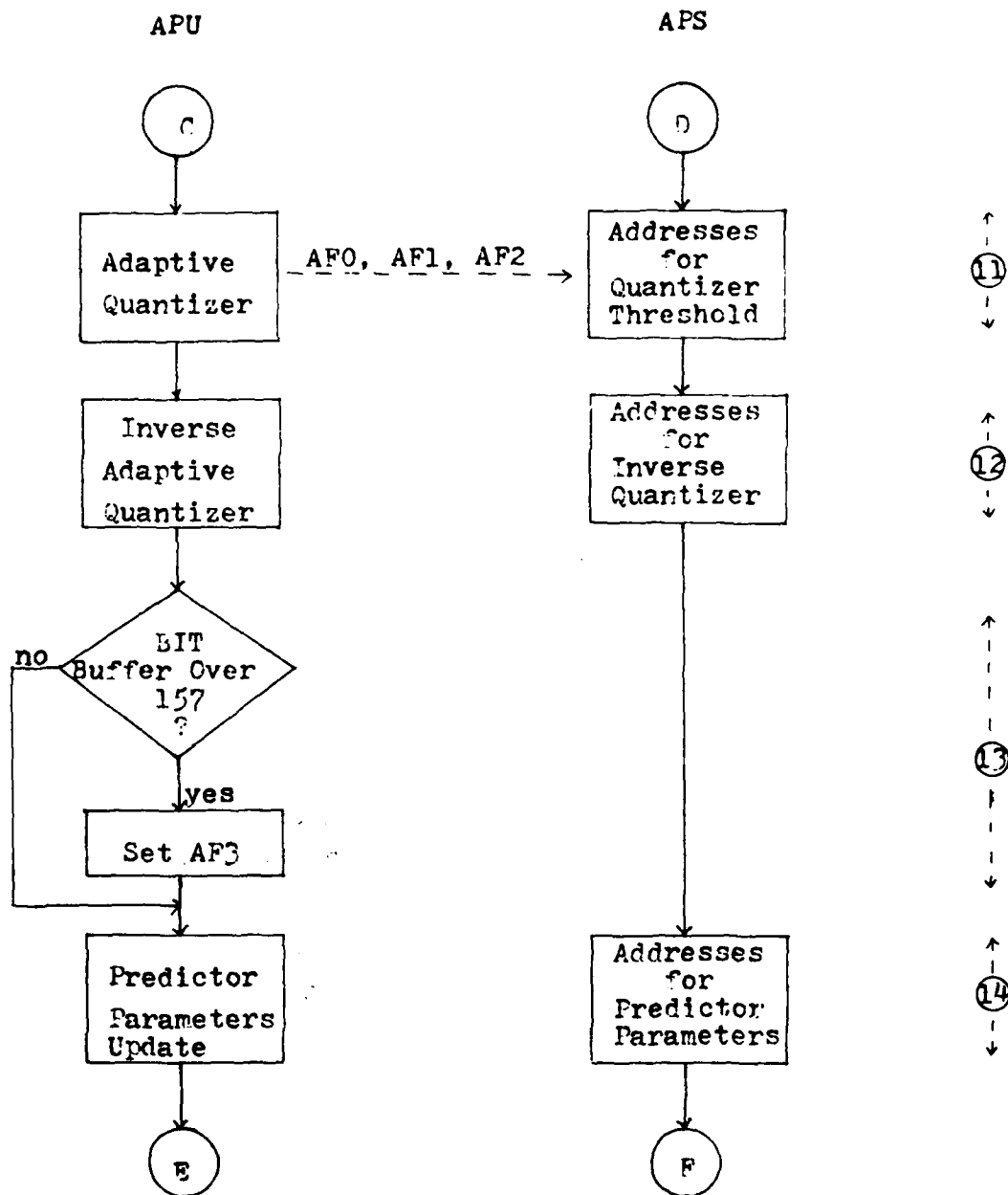


Fig. 12.10c The Flow Chart of the Speech Digitization Program

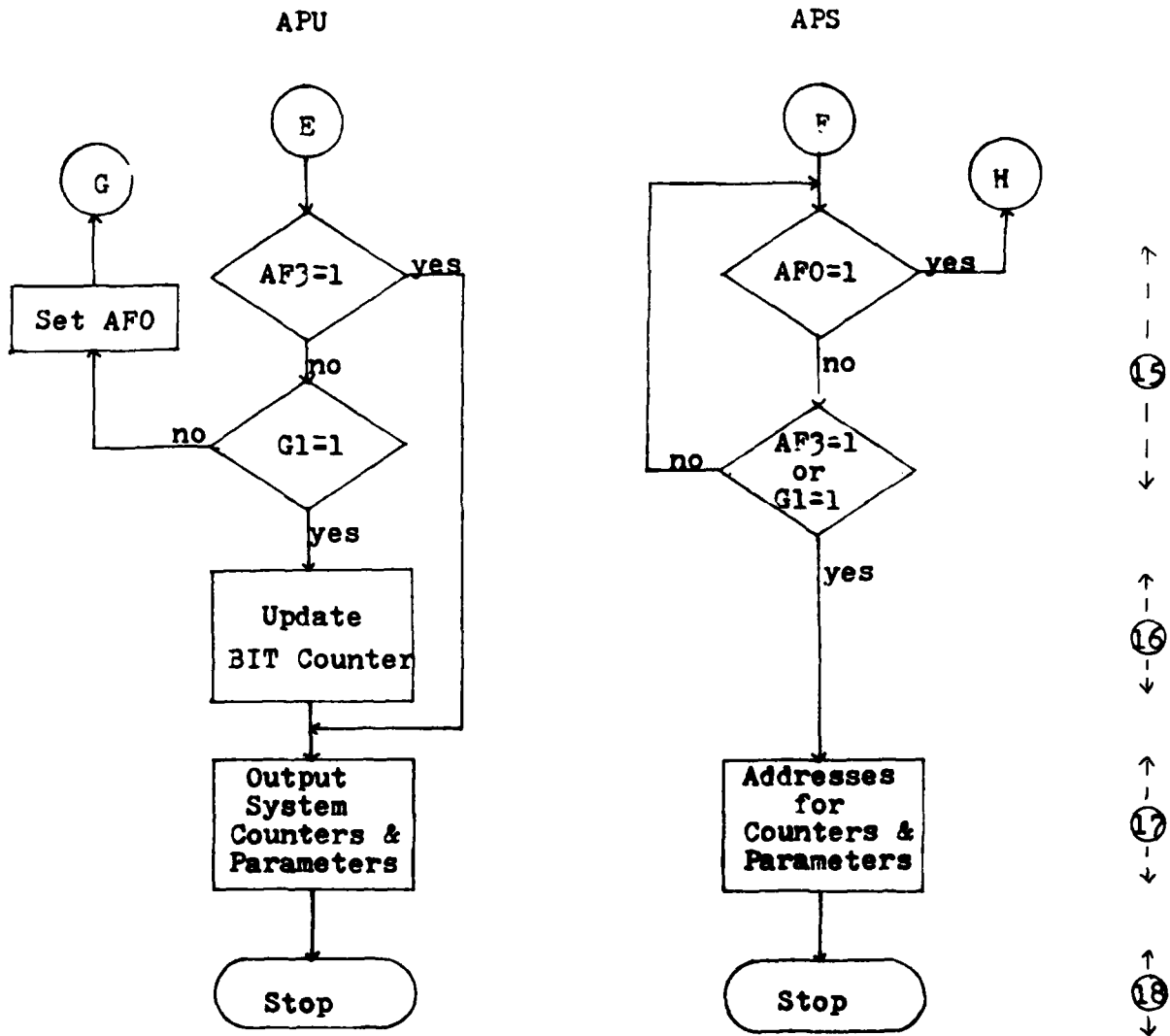


Fig. 12.10d The Flow Chart of the Speech Digitization Program



real-time system, the IOS-2 transfers 189 bits in a time slot. However, as described in Chapter 2, only 157 bits are available to encode the quantizer levels. the BIT counter is used to control the PARC-Transmitter so as to generate just more than 157 information bits. The SAMPLE counter is used to count the total number of samples processed by the PARC-Transmitter during a time slot. The address pointer update program will use this information to update the address pointers in the transmitter circular buffers. The LEVEL counter is used to limit the maximum number of samples which can be processed in a time slot. This assures real-time operation.

5. The APU and the APS check the flag G2 which is controlled by the pitch computation program to indicate the condition of the pitched repetition. If flag G2 is clear, there is no pitched repetition and the APU and the APS go to Step 6. Otherwise, the APS produces the addresses of SHAT buffer for the pitched repetition. The APU executes the pitched repetition. The size of the pitched repetition is a system parameter which can be input from the main Fortran program. The design of the real-time system assumes that the overflow of the sample buffer can be absolutely controlled by the pitched repetition. Thus, the size of the repetition has to be carefully considered.
6. The APS produces addresses for the predictor. The APU executes the predictor which employs a fourth order prediction.
7. The APU checks the LEVEL counter and sets the flag G1, if the counter is over the maximum number of samples allowed to be executed by the PARC-Transmitter.

8. The APU executes the reciprocal function to compute  $1/(\text{RMS})^2$  and  $1/\sigma$ . To do the reciprocal of a 32-bit floating point number, the APU usually employs an 8 x 256 read only memory which has only 8-bit precision in the mantissa part. Thus, a special subalgorithm is used to increase the precision.
  9. The APS produces addresses for the pitch extraction. The APU executes the pitch extraction.
  10. The APS checks the SAMPLE buffer and sets the flat G1 if the buffer is empty.
  11. The APU and the APS quantize the input sample. Three flags are employed to communicate between the APU and the APS. The way to quantize an input sample is as follows:
    - A. The APU signals the APS to produce the threshold address.
    - B. The APU compares the magnitude of the input sample with the threshold.
    - C. If the threshold is larger than the magnitude, the APU signals the APS to stop the searching and jumps to the inverse quantizer portion. Otherwise, the APU checks whether the threshold is the largest one. If it is, the APU signals the APS and jumps to inverse quantizer portion. If it is not, control is returned to Step A.
- This design allows variable quantizer levels and reduces searching time, because most of the input samples are dropped in the first two levels.
12. The APU and the APS execute the inverse quantizer.
  13. The APU updates and checks the BIT counter and sets the flag AF3 if the 157-bit is reached.

14. The APU and the APS update the predictor parameters.
15. If the flag G1, which indicates an underflow of the SAMPLE buffer or reaching the maximum number of samples permitted in the time slots, is set, the APU goes to Step 16. If the flag AF3, which indicates the condition of BIT counter, is set, the APU goes to Step 17. Otherwise, the APU sets the flag AFO and goes to Step 6. The APS waits for the signals from the APU. If the flag AFO is set, it goes to Step 6. Otherwise, it goes to Step 17.
16. If this step is executed, there has been an underflow in the SAMPLE buffer, i.e., less than 157 bits are generated. The APU updates the BIT counter to account for a NULL code which indicates underflow. If the BIT counter is still less than 157 bits, the BIT counter is reset to synchronize the counters between the PARC-Transmitter and the encoder.
17. The APU and the APS output the contents of the system counters and parameters.
18. The AP interrupts the CSPU to indicate that it is finished.

### 12.3 The PARC Receiver

In this section, the PARC-Receiver, which resides in the AP, will be presented. The corresponding decoder and channel synchronizer will be explained in Section 12.5. The principal elements of the receiver, which is shown in Fig. 2.8, are also part of the transmitter. So, the implementation of receiver is much the same as that of the transmitter.

Before the description of the design of the PARC-Receiver, the buffer system has to be depicted. There are six buffers employed by the receiver as shown in Table 12.3.

Table 12.3 Buffer Configuration in the PARC-Receiver

Name	Bus#	Starting Location	Ending Location	Buffer Size	Buffer Type
AOM	2	3584	3835	252	Double Buffer, Short Floating Point
		3840	4091	252	
VHAT	3	2048	3071	1024	Circular Buffer, Short Floating Point
SHAT	2	2048	3071	1024	Circular Buffer, Short Floating Point
PARAMETER	2	4096	4255	80	Single Buffer, Long Floating Point
LEVEL	1	26000	26599	600	Double Buffer, Long Fixed Point
		28000	28599	600	
BIT	1	29000	30023	1024	Circular Buffer, Long Fixed Point

Among them, the AOM and the LEVEL buffers are double buffers which allow one processor to fill one-half of the buffer while another processor to process on the other half. This increases the parallel ability of the receiver. The VHAT, the SHAT and the BIT buffers are circular buffers which allow continuous access. However, the additional address pointers, which indicate the starting locations of these circular buffers at the beginning of each time slot, have to be considered. The structures of the LEVEL buffer and the BIT buffer will be explained in Section 12.5. The PARAMETER buffer is a single buffer which stores system parameters such as predictor coefficients, quantizer output scaling factors and quantizer expansion factors.

The flow chart of the receiver is shown in Fig. 12.11. The detailed functions are described as follows and the parallel processing is shown:

1. In response to the function list, the CSPU loads the APU and the APS modules of the PARC-Receiver program into the APU and the APS respectively.
2. The CSPU sets the flag RI which will initiate the APS module.
3. The APS then sets the flag RA which will start the APU module.
4. The APS produces 126 input addresses of the SHAT buffer and 252 output addresses of the AOM buffer. The APU processes the upsampling operation on 126 input reconstructed speech samples and produces 252 unsampled data points. The upsampling operation employs the linear interpolation technique which is explained in Section 2.8. The APU also limits the values of output data to be in the range of  $[-2048/2048, 2047/2048]$  which is acceptable for the AOM.

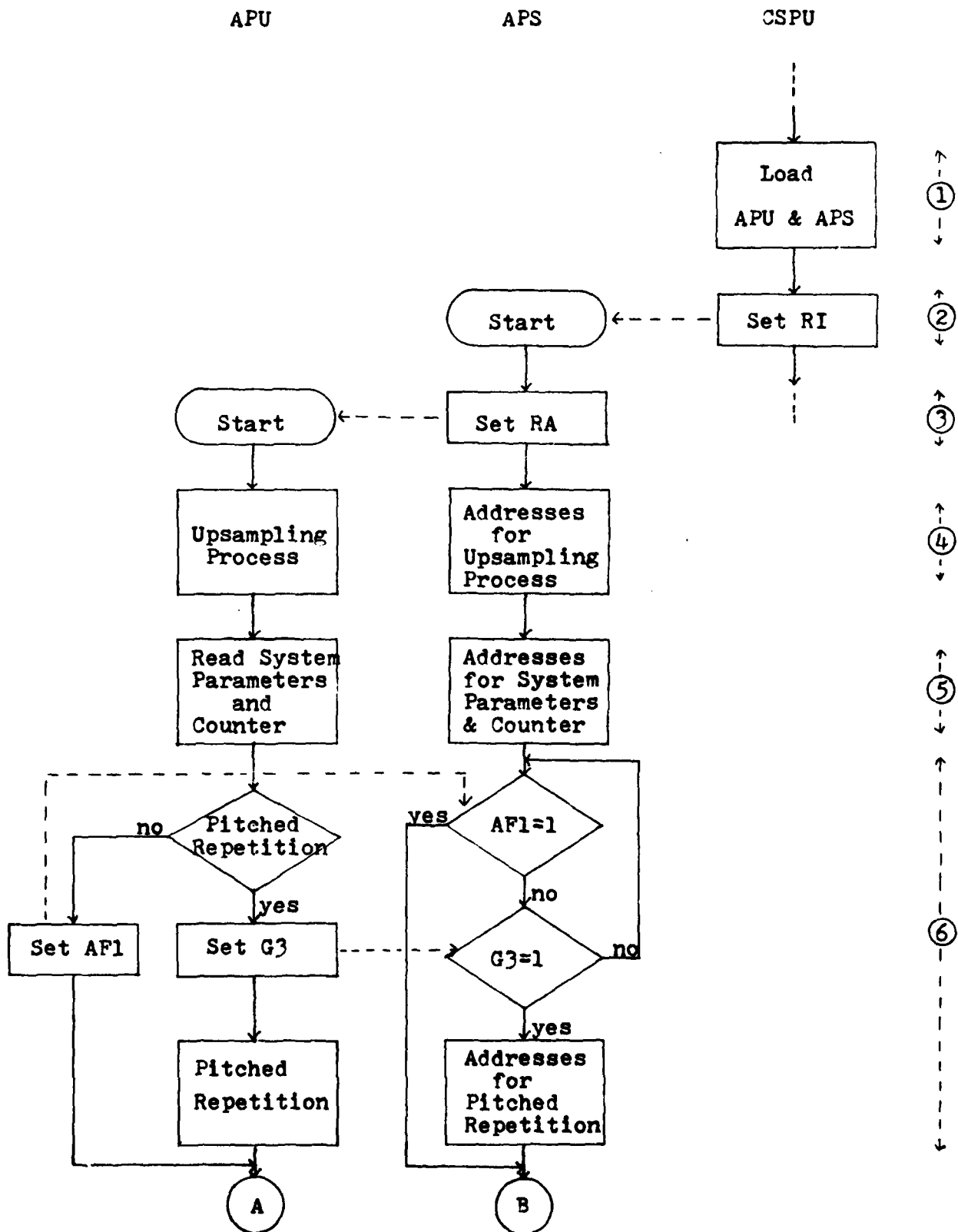


Fig. 12.11 The Flow Chart of the PARC-Receiver Program

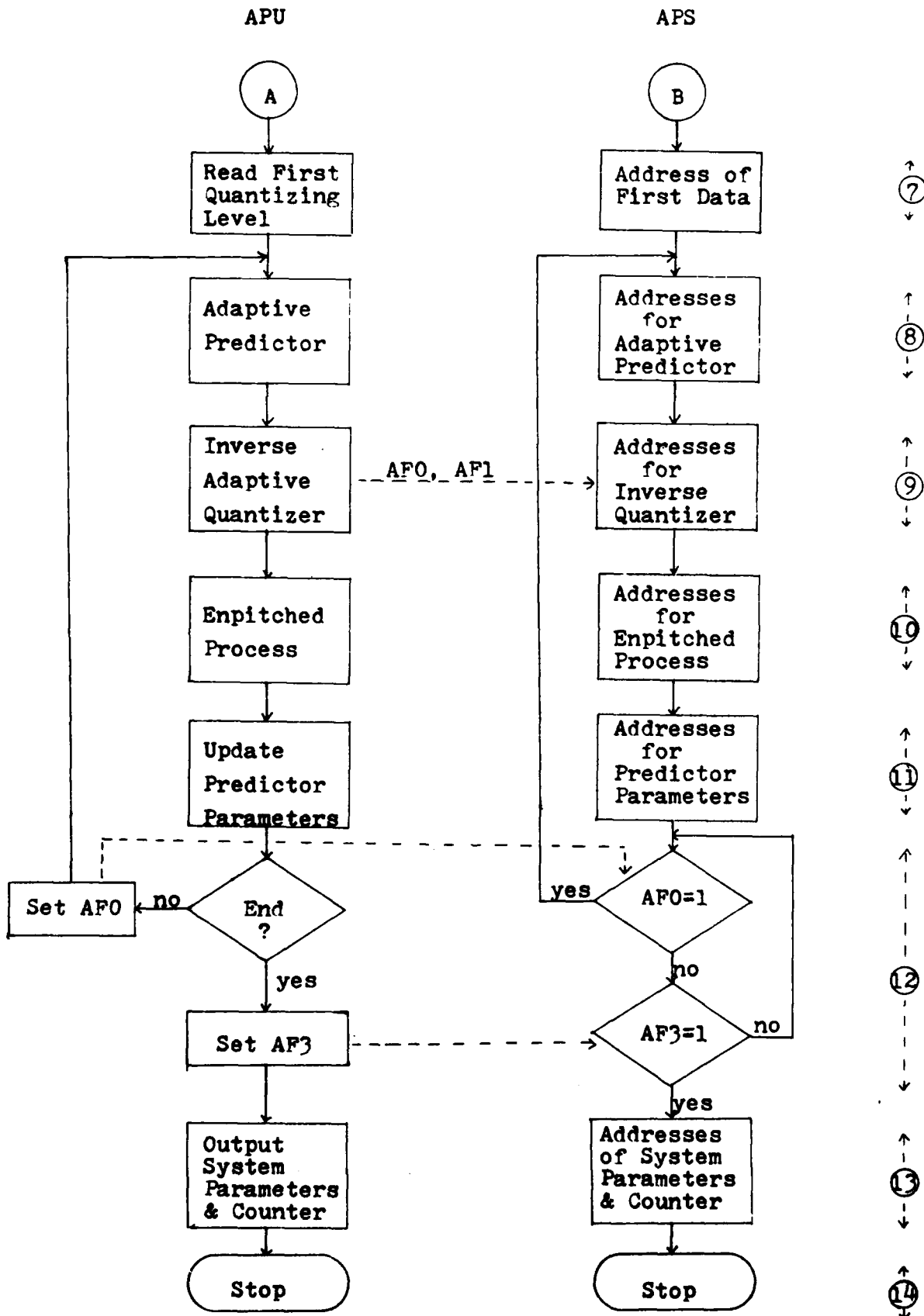


Fig. 12.11 The Flow Chart of the PARC-Receiver Program

5. The APS produces addresses of the system parameters and a counter. The APU reads the system parameters and the counter. There is only one system counter, the SAMPLE counter, which is used to count the total number of samples processed by the PARC-Receiver during a time slot. The receiver address pointer update program will use this information to update the address pointers of the receiver circular buffers.
6. The APU checks the first data in the LEVEL buffer and decides the condition of the pitched repetition. If no pitched repetition is employed, it sets the flag AF1 and goes to Step 7. Otherwise, it sets flag G3 and processes pitched repetition. The APS waits for signals from the APU. If the flag AF1 is set, it goes to Step 7. If the flag G3 is set, it produces addresses for the pitched repetition operation.
7. The APS produces the second data which is the first received quantizing level in the LEVEL buffer. The APU reads the first quantizing level.
8. The APS produces the addresses for the adaptive predictor. The APU processes the adaptive predictor which employs a fourth order prediction.
9. The AP operates the inverse adaptive quantizer. Two flags, AFO and AF1, are used to communicate between the APU and the APS.
10. The APS produces the address of  $\hat{V}(K-T)$ . The APU restores the pitch redundancy as shown in Eq. (2.1).
11. The APS produces addresses of the predictor parameters. The APU updates the predictor coefficients.



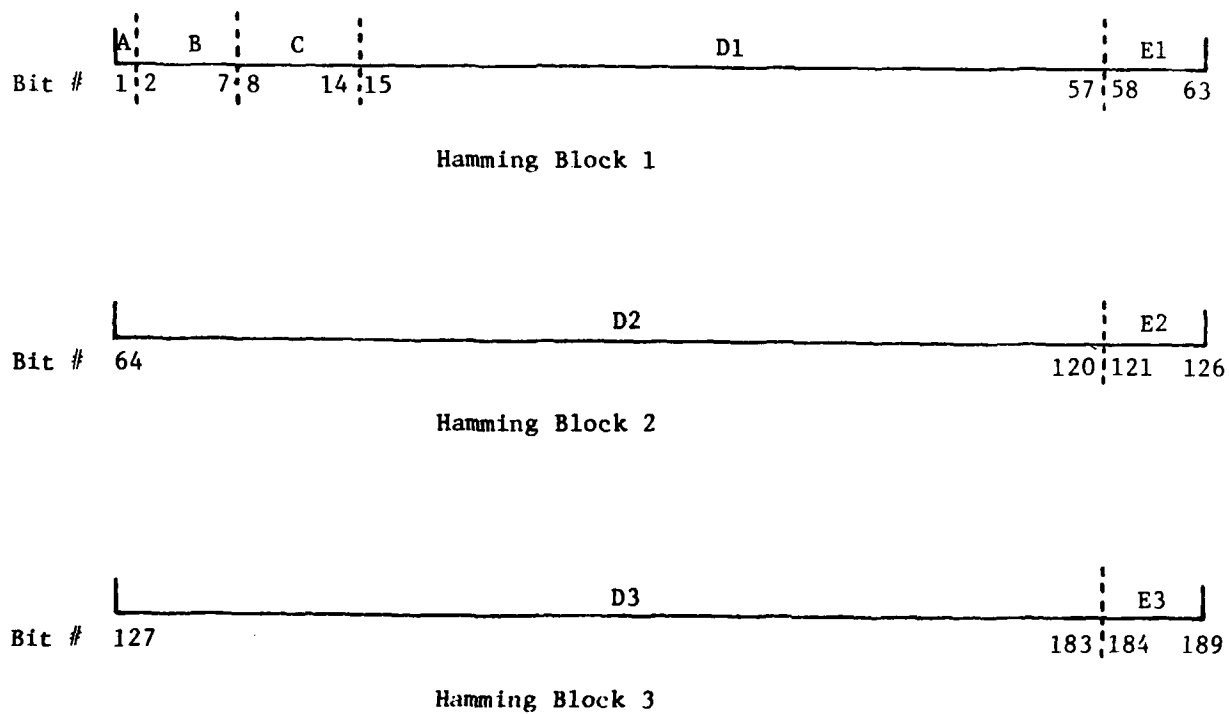
12. The APU reads the next data in the LEVEL buffer and checks whether it has reached the end of the buffer. If it has, the APU sets the flag AF3 and goes to Step 13. Otherwise, it sets the flag AF0 and goes to Step 8. The APS waits for signals from the APU. If the flag AF3 is set, it goes to Step 13. If the flag AF0 is set, it goes to Step 8 to continue the receiver loop.
13. The AP outputs the system parameters and the counter to the MAP memory.
14. The AP interrupts the CSPU to indicate that it is finished with the PARC-Receiver.

#### 12.4 Noiseless Source Coder

This section describes the implementation of the noiseless source coder on the central processor of the MAP 300 called CSPU. As discussed in Section 2.7, the source coder performs several functions. Its primary purpose is encoding the quantizer levels and the side information for each block of  $N_B$  samples processed by the PARC transmitter. In addition, it supplies the bit pattern for frame synchronization and the parity code for channel error control.

At its input, the encoder shares a double buffer containing the pitched repetition indicator and  $N_B$  quantizer levels each with the PARC transmitter. The corresponding pitch reduction parameters  $\beta, T$  are in two sets of locations in the scalar table. At its output, it shares a double buffer containing 189 bits each with the IOS, the processor which interfaces with a digital modem.

The encoder strives to form a frame of 189 bits from the quantizer levels and the side information generated by the transmitter. The frame is subdivided into three Hamming blocks of 63 bits each. A Hamming block contains 57 information bits and 6 parity bits. Each of the 57 information bits in a block is protected against errors. Depending on whether or not pitched repetition is indicated, the output frame assumes one of two formats Figs. 12.12 and 12.13. The encoder proceeds sequentially to build the different fields in the output frame. It handles one Hamming block at a time. The parity codeword for the block is updated each time a bit is output. Immediately after the 57th information bit in a Hamming block is transferred, the parity codeword for that block is output. The codeword is then initialized for the next block, and the encoder continues to output further information bits. This



Field	Contents
A	Synchronization bit
B	Pitch period T
C	Pitch correlation coefficient $\beta$
D1, D2, D3	Quantizer levels
E1, E2, E3	Parity bits for error control

Fig. 12.12 Normal Format for Bit Frame Output of Encoder



Hamming Block 1

Field	Contents
A	Synchronization bit
B	Pitch period $T$
C'	False $\beta$ , for pitched repetition
C	Pitch correlation coefficient $\beta$
D1	Quantizer levels
E1	Parity bits for error control

Fig. 12.13 Format of first Hamming Block during pitched repetition

process is repeated for three Hamming blocks, completing the output frame of 189 bits.

Fig. 12.14 shows the flow chart for the encoder. The program listing is contained in Appendix G. The encoder starts with field A, Fig. 12.12. It fetches the previous sync bit from a location where it was saved and inverts it. This new value is saved for use in the next frame. It is also output to field A. Next the encoded value of T is fetched and transferred to the output buffer, field B. The value of the pitched repetition indicator is then checked. If affirmative, the code 0000000 is transferred to field C', Fig. 12.13. Next the partially encoded value of  $\beta$  is fetched. It must be between 0 and 96 indicating one of 97 possible levels. Using this as an index, a 7-bit code is retrieved from the  $\beta$  encode table and output to field C, Figs. 12.12, 12.13. After this the quantizer levels are fetched one by one. The corresponding code-lengths and code-words are retrieved from the Q-level encode table and transferred to the output buffer until the fields D1, D2, and D3 are filled. This should coincide with the exhausting of the  $N_B$  Q-levels generated by the transmitter.

An exception to this occurs when the sample buffer runs out. The block of quantizer levels do not generate enough bits to fill up the fields D1, D2, and D3. In this case, a null code 11111110 is output to indicate the end of quantizer level information. If there is still more space available, it is padded in with 1's. The null code and the padding bits are error-protected the same as any other information bits.

The source code used here is a variable-length to variable-length mapping, and it is not necessary that fields D1, D2, and D3 are exactly filled by encoding an integer number of quantizer levels. The extra bits after a

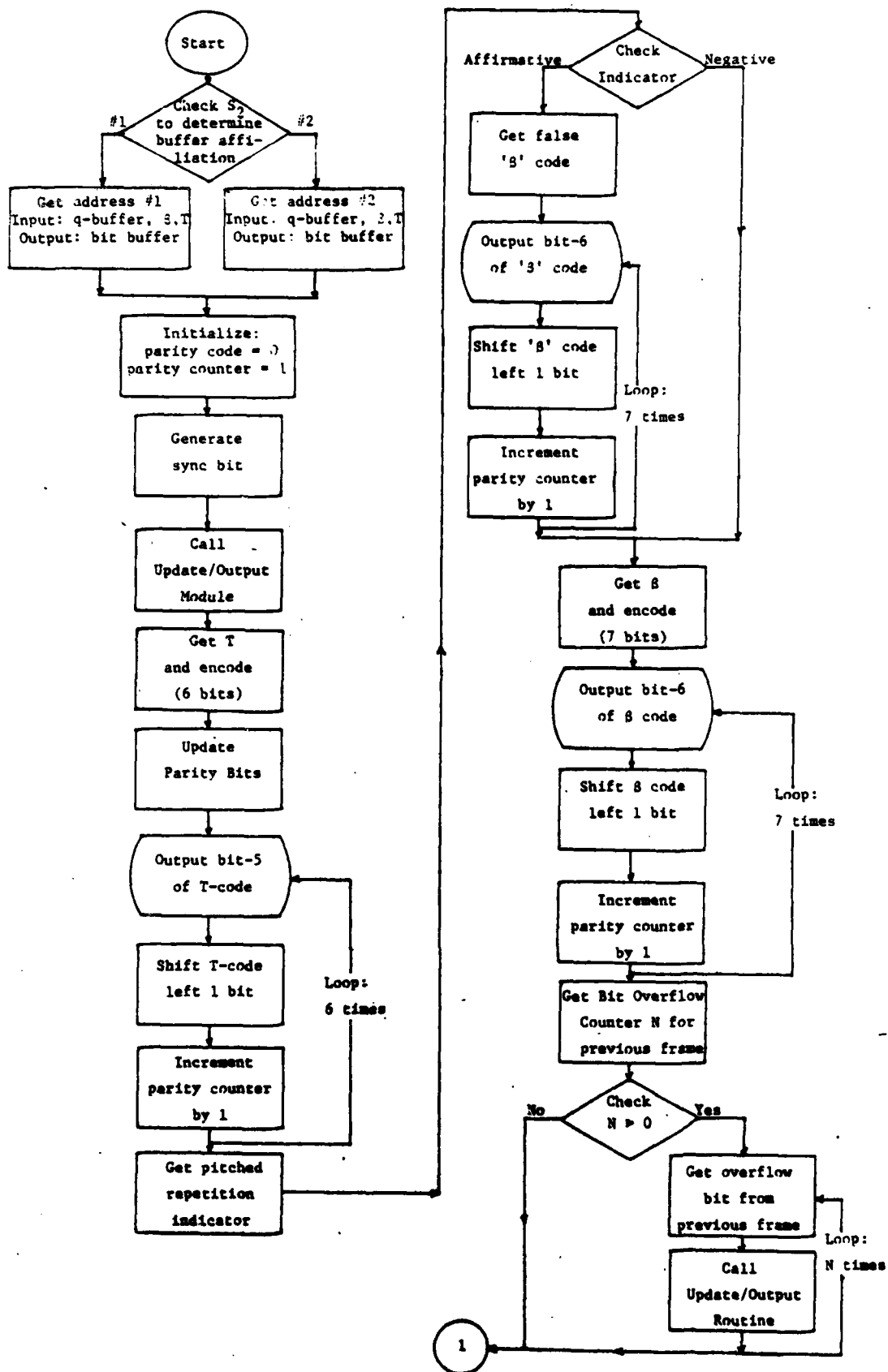


Fig. 12.14a Block Diagram for Encoder

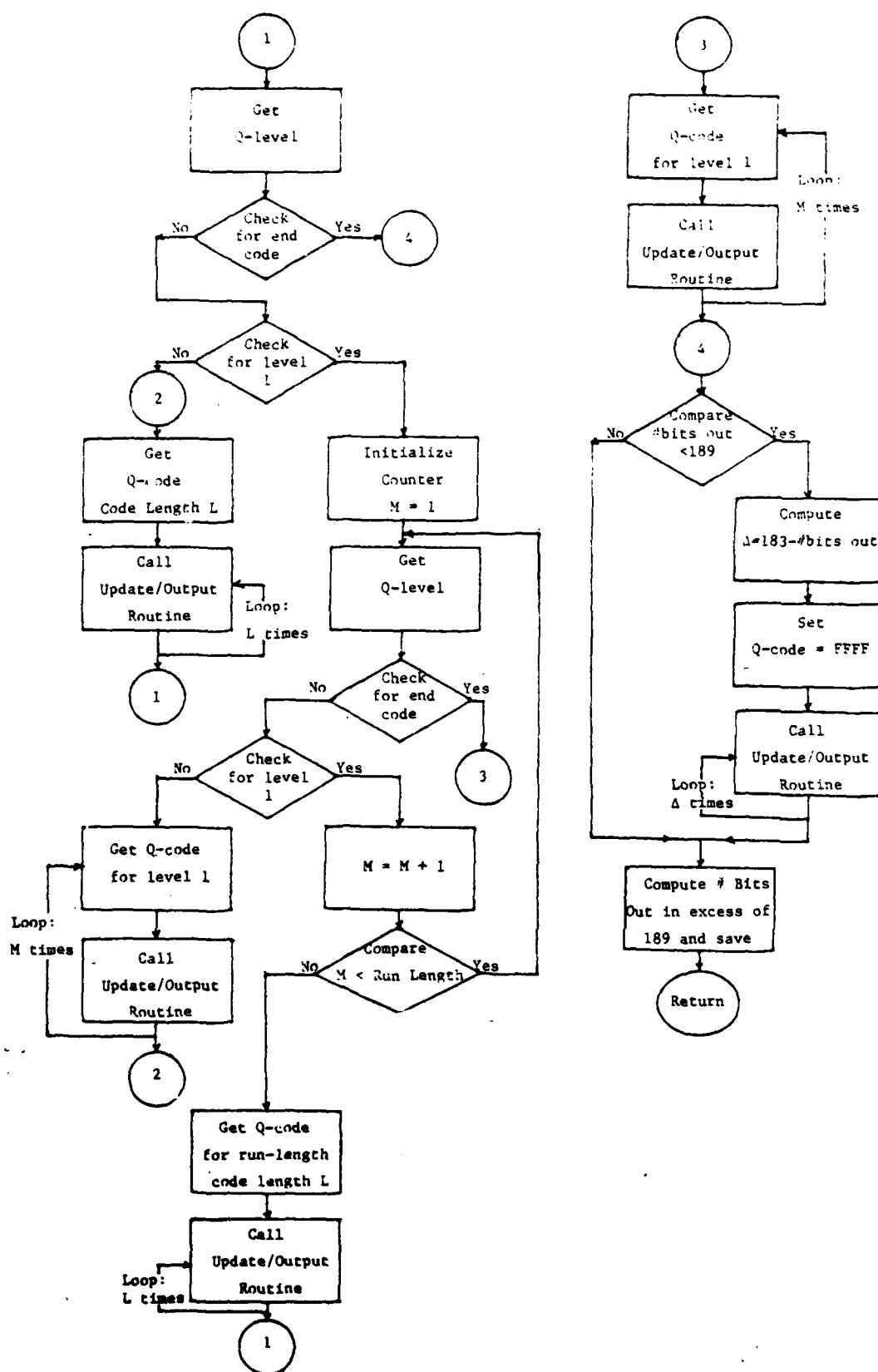
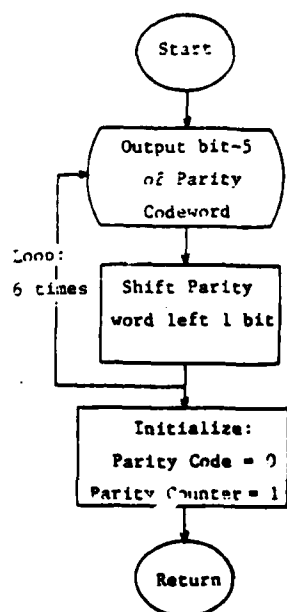


Fig. 12.14b Block Diagram for Encoder

## A) Parity Output Routine



## B) Update/Output Routine

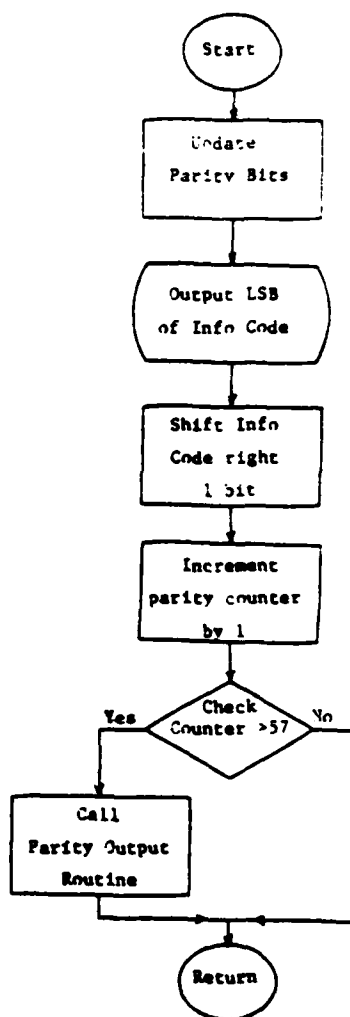


Fig. 12.14c Block Diagram for Encoder



Hamming block is full are passed to the appropriate field in the next Hamming block.

All the programs in each processor need to be able to process a block of information within a time frame of  $19687.5 \mu \text{ sec}$  for the algorithm to keep in real time. This necessitated giving program efficiency priority over flexibility. The following is a list of the constraints on the encoder program as a result of this:

(i) All buffers used by the encoder must be located in Bus 1. They can be relocatable, as long as they do not occupy memory locations above 64K.

(ii) All the inputs to the encoder program must be in the fixed number format. The quantizer levels must be pre-multiplied by 2 to facilitate direct indexing. The values of  $\beta$  and  $T$  must be partially encoded.  $T$  must be limited to 64 values from 0 to 63, and  $\beta$  to 97 values from 0 to 96. Pitched repetition and the end of quantizer levels must be indicated by negative numbers.

(iii) The source code has the following constraints. The code for level 1 is 0. The locations for the run length code and the null code in the  $Q$ -level encoding table are 0 and 24, respectively. The other 11 codes for the quantizer levels  $Q$  are at locations  $2Q$ .

(iv) Because the LSB of a code-word is transmitted first, the code-word received at the decoder is inverted, e.g., 110  $\rightarrow$  011. To compensate for this, the code-words stored in the  $Q$ -encoding table must be inverted and right justified.

(v) The  $Q$ -encoding table must contain  $(L-1)$  for the various code lengths,  $L$ .

(vi) The code to indicate pitched repetition is 0000000. The 97

quantized values of  $\beta$  may not use any pattern with 2 or less 1's in it.

This is to give the pitched repetition indicator additional error protection.

(vii) The run length value can be selected at initialization.

(viii) Finally, the block of  $N_B$  quantizer levels should not generate more than 196 bits. Since the encoder does not monitor the maximum number of bits generated, the transmitter must ensure this limit.

### 12.5 Synchronizer, Decoder

This section describes the implementation of the decoder on the central processor of the MAP 300 called CSPU. The decoder essentially inverts at the receiver the operation performed by the encoder at the transmitter. From each received frame of 189 bits, it generates a block of  $N_B$  quantizer levels, the pitched repetition indicator, and the pitch extraction parameters for use by the PARC receiver. In addition, it performs several other operations. It monitors transmission errors, and corrects up to one error per Hamming block in the received frames. Because the received bit stream is arranged in frames, the decoder acquires the initial frame synchronization using the synchronization bit pattern transmitted by the encoder. Later, it monitors the received sync pattern to ascertain that synchronization is not lost. It monitors the state of the sample buffer in the PARC receiver to make sure the buffer does not overflow or underflow. Finally, it controls the mode of operation of the entire PARC algorithm.

The different operations outlined here are performed in different modules in the decoder. The decoder program is subdivided into three modules: the initialization module; the synchronization acquisition module; and the decoder module. The function to be performed and correspondingly the module to be used is determined by the three values of a function select switch, S1. The first time the program goes in for sync acquisition, several parameters and buffers need to be initialized. This mode is indicated by a value of 0 for S1. Subsequent sync acquisition operations are indicated by a value of -1 for S1. After frame sync has been established, the decoder can perform its task of inverting the bit stream to quantizer levels. This mode is indicated by a value of 1 for S1.

The decoder shares a double buffer with the PARC receiver at its output. A second function select switch, S2, indicates which half of the double buffer the decoder must use in the current time frame.

At its input, the decoder shares a circular buffer 1024 bits long with the IOS. The decoder expects to receive 189 bits in each time frame. However the clock that controls the inflow of the bit stream is at the other end of the communication system. It is different from the clock that measures the time frame at the decoder. On the average, the decoder does receive 189 bits per time frame. However, because of the different clocks, there could be temporary deviations. The large circular buffer which is several times the frame size allows for these deviations without causing a conflict between the decoder and the IOS over the bits being read out of and written into the buffer. The IOS, which receives the bit stream from the digital channel, has its base pointer which indicates the position of the base of the current frame to be entered into the buffer. When the PARC algorithm is initiated, the base pointer of the decoder which indicates the base of the frame of bits it should process in the current time frame is set several blocks behind the input pointer controlled by the IOS. Each processor updates its pointer independently at the end of the time frames. As long as the input and output rates match on the average, no conflict should occur and the two pointers should remain reasonably separated.

On being called, the decoder checks S1 and transfers control to the appropriate module. The module performs its function, and then it sets up the control and updates the relevant parameters and information for the operation in the next time frame. The program listing of the decoder is included in Appendix G. The following subsections describe in detail the operation of the three modules that make up the decoder.

### 12.5.1 Synchronization Acquisition Module

Before the decoder can start inverting the received bit stream, the boundaries of the frames, marked by the sync bit, must be located. This task is achieved by the synchronization module, over several time frames. The sync acquisition algorithm is described in Chapter 3. The implementation here varies slightly from the description in Chapter 3. This is to reduce the amount of computation and memory storage required and to make the program more time efficient. The block diagram of the sync acquisition module is shown in Fig. 12.15.

The encoder inserts an oscillating bit  $S_i$  in field A, Fig. 12.12, for synchronization. The decoder generates a similar pattern of expected sync bit values,  $\hat{S}_i$ . During sync acquisition, the correlation of  $\hat{S}_i$  and each of the 189 bit positions starting from the base pointer is computed. A cumulative correlation tally from one time frame to the next for each of the bit positions is stored separately. Just in case the sync sequence being generated at the decoder is the inverse of the sync pattern being received from the transmitter, a cumulative tally of correlations with  $\bar{\hat{S}}_i$  is also saved for each of the bit positions. The bit position corresponding to the maximum cumulative tally in each time frame is kept. When the correlation tally for a particular bit is maximum for ten consecutive frames, it is assumed the sync bit has been located. That position, marking the beginnings of frames generated by the encoder, is saved.

If at the end of a sync acquisition operation, it is determined that sync has not yet been acquired, the program sets up for one more sync operation in the next time frame. The base pointer in the circular buffer is updated by 189. The current value of  $\hat{S}_i$  is inverted and saved. And the function select switch S2 is changed to indicate opposite buffer affiliations

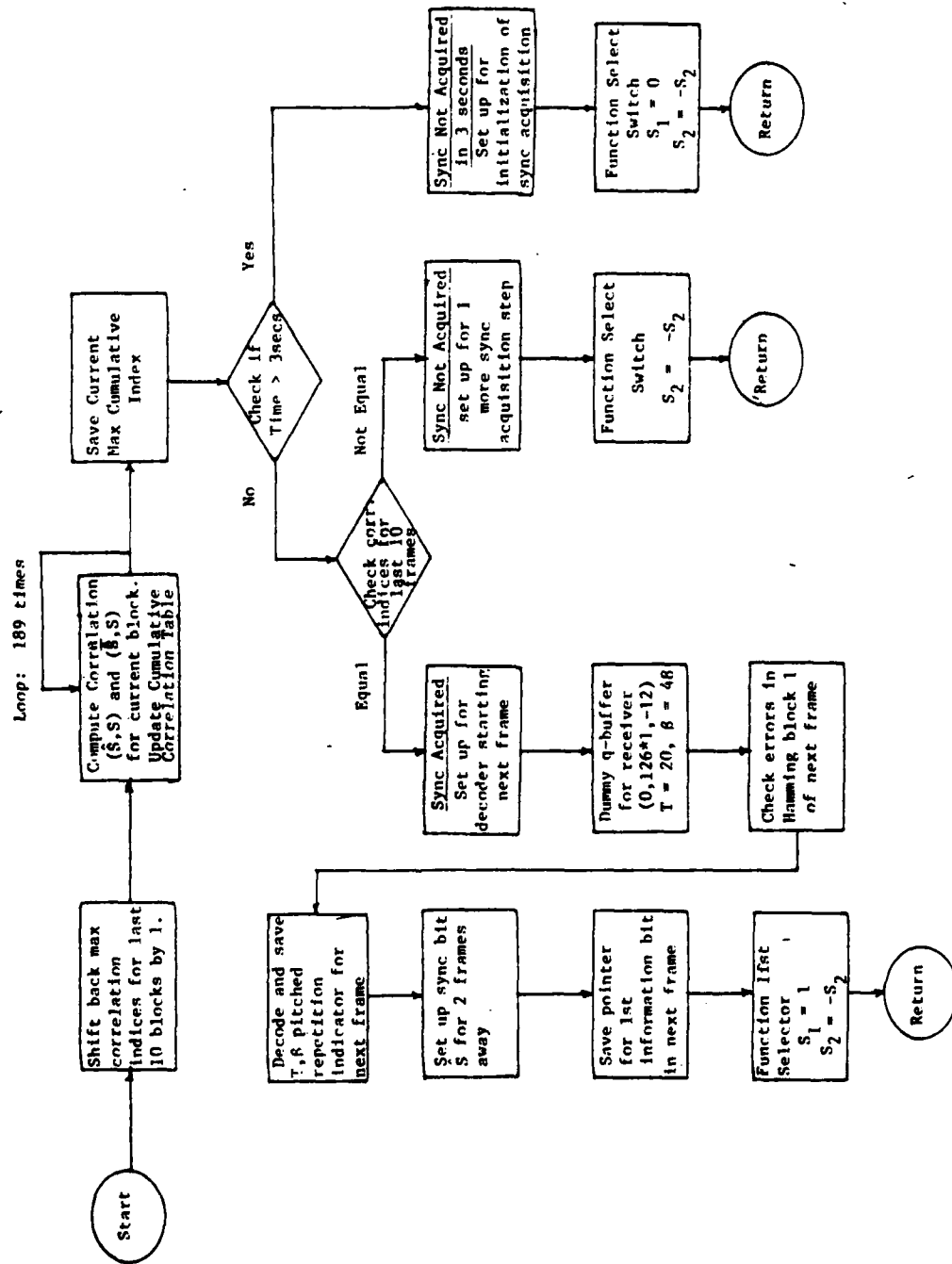


Fig. 12.15 Block Diagram for Sync Acquisition

for the next time frame.

If synchronization is achieved, preparations are made for subsequent decoder operations. In addition to the above controls and parameters, several others are updated. Function select switch S1 is changed to 1 to indicate a decoder operation in the next frame. Although no decoder operation has so far been performed, a dummy buffer consisting of 126 level 1's is prepared for use by the PARC receiver. Error check is conducted on the first Hamming block of the next bit frame; and up to one error is corrected. T,  $\beta$  and the pitched repetition indicator for the next frame are decoded and saved for output later. This leads to the location of the first bit in the field B1, Fig. 3.12, of the next frame. This is called the 1st information bit, information about quantizer levels. Its location is saved for use in the next frame. The cost function for sync monitor is initialized to -1. And the expected sync value  $\hat{S}_{i+1}$  is set to match the next received sync value  $S_{i+1}$ . Finally, the state of the receiver sample buffer is initialized to a buffer-full condition. The control is then returned to the MAP executive.

#### 12.5.2 Decoder Module

This module is the heart of the decoder. It corrects for transmission errors, if possible; monitors frame synchronization; inverts the received bit sequence to information usable by the PARC receiver; and performs buffer control on the receiver sample buffer. Its block diagram is shown in Fig.12.16.

After it decides its buffer affiliation by checking S2, it does error detection and correction on the 2nd and 3rd Hamming blocks of the current bit frame and the 1st Hamming block of the next bit frame. The reason for this offset between the bit frame and the error control frame is to make the extra bits generated during the encoding of the current frame available to the decoder when it performs the decoding. The extra bits reside at the

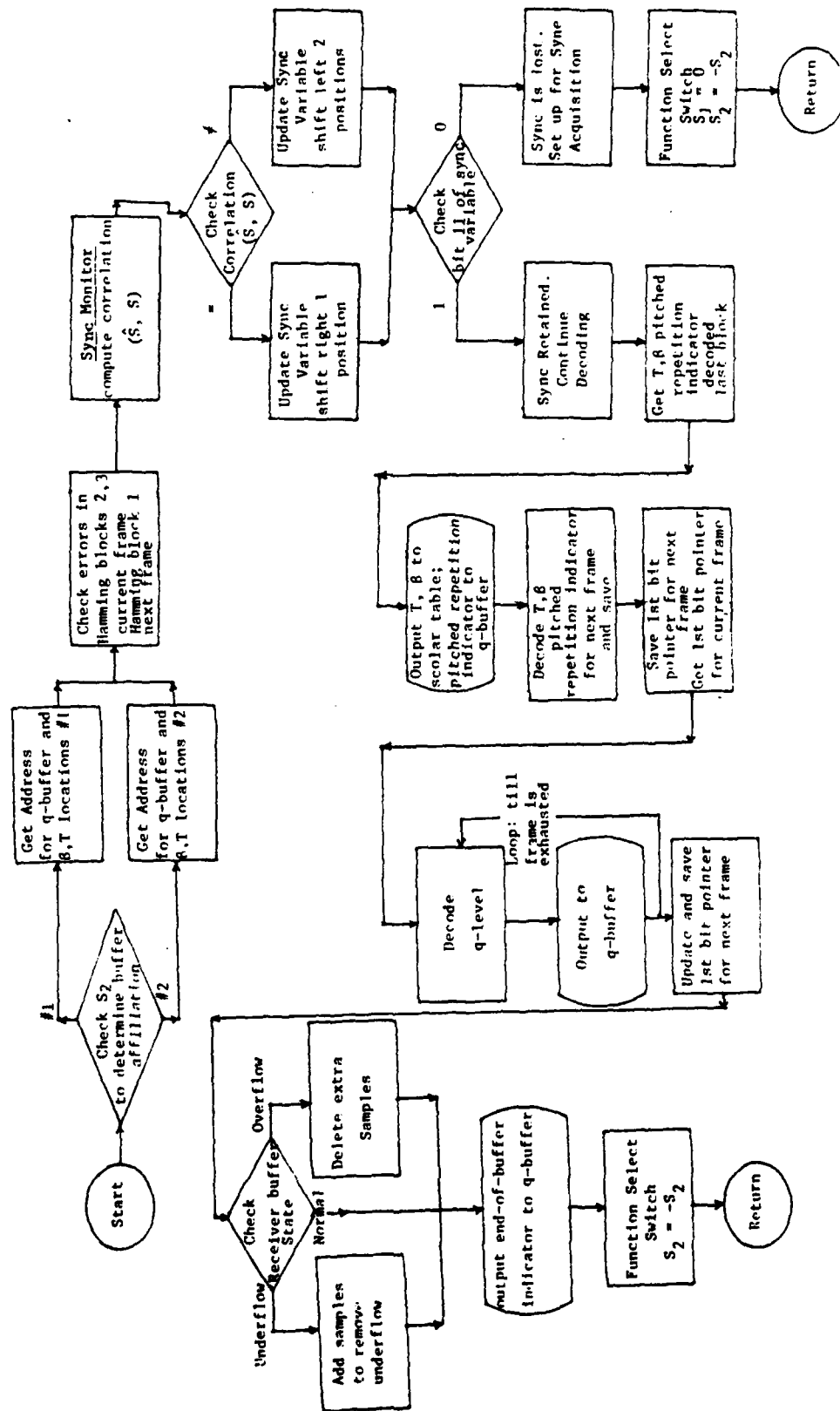


Fig. 12.16 Block Diagram for Decoder



beginning of field B1, Fig. 12.12 of the next frame.

The next step is sync monitor. The basis of the algorithm is explained in Chapter 3. The sync variable starts with an initial value of -1, FFFF in hexadecimal representation. The received sync bit  $S_i$  is compared with its expected value  $\hat{S}_i$  using the logical operation EXOR. If equal, the bits in the sync variable  $v_i$  are shifted right one position. Bit 15, the sign bit is retained 1 in this operation. If not equal, the sync variable is shifted left two positions, causing 0's to be inserted in the least significant bits of  $v_i$ .

Bit 11 of  $v_i$  is monitored. If it is 0, sync is declared lost. The module sets the switch S1 to 0 to indicate a series of sync acquisition operations starting in the next time frame, and returns control to the MAP executive.

As long as bit 11 of  $v_i$  is 1, sync is declared preserved, and the module continues to its next phase of operation, source decoding. The pitch reduction parameters  $\beta$  and  $T$  which were decoded and saved in the previous time frame are output to their appropriate locations in the scaler table. The pitched repetition indicator, also decoded in the previous time frame, is transferred to the output buffer. If affirmative, the receiver buffer pointer is updated by the length of the repetition block.

After this, the pitch reduction parameters and the pitched repetition indicator for the next time frame are decoded and saved. This leads to the position of the 1st information bit in the next frame. If there were any extra bits in the current frame, the decoder will know where to look for them when it needs them.

The source decoding is a tree searching operation along the coding tree. Each successive bit received represents a node in the tree. Starting from the root of the tree, bits are read in, until the last bit received represents the termination of the tree. The corresponding quantizer level(s) are determined

from the decoding table and transferred to the output buffer. This process continues until either a null code is received or all the bits in the current frame are exhausted. At the end of the the decoding operation, the location of the 1st information bit for the next frame is saved.

The decoder can correct transmission errors to a point, after which errors filter through to the received bit stream. Errors have two effects on the decoding procedure. The quantizer levels generated are wrong. And the number of quantizer levels  $N_B$  in the current block can be different from what it should have been. This causes the state of the sample buffers in the transmitter and receiver to lose correspondence. To correct for this, the decoder provides a steady drift in the state of the receiver buffer. When  $N_B$  for a received block is 126, it indicates that the transmitter was processing silence when it generated this block and its sample buffer was empty. Correspondingly, the receiver buffer should be full. A few extra level 1's are added to the q-buffer generated for the receiver; so that if errors have caused the receiver to move away from its buffer-full condition, it should slowly drift back. This alleviates the mismatch between the buffer states at the receiver and the transmitter.

Finally, the state of the receiver sample buffer is checked. If it underflows, extra level 1's are added to remedy it's negative state. If it overflows, the extra samples are deleted.

After this, the module updates various controls and parameters for another decoder operation in the next time frame. It then returns control to the MAP executive.

### 12.5.3 Initialization Module

The initialization module precedes the first of a sequence of sync

acquisition operations. Sync acquisition requires two buffers initialized for its proper operation. This is done by the initialization module. The locations which contain the bit positions with max correlation tallies from the last ten frames are initialized to -1. The buffer where the correlation tallies are stored is initialized to 0. The switch S1 is set to -1 to indicate subsequent sync acquisition operations.

In addition, the length of the pitched repetition block is retrieved from the function control block and saved for later use in the decoder. It also gets the base address of the input buffer. It then transfers control to the sync acquisition module.

#### 12.5.4 Decoder Constraints

As with the other modules in the PARC algorithm, the stress in developing the decoder program is execution efficiency rather than flexibility. This is to try and meet the rather tight limitations of real time operation. The following constraints are imposed on the decoder:

(i) All buffers used by the decoder must reside on Bus 1. They can be relocatable, as long as they do not occupy memory locations above 64K.

(ii) The input for this program is a circular buffer of length 1024. The information bit must be contained in the LSB of each word.

(iii) All the outputs of the decoder are in the fixed point number format. The  $\beta$  and T are partially encoded and are represented by 7 and 6 bits respectively.  $\beta$  is allowed one of 97 codewords, 0 to 96, and T one of 64, 0 to 63. Pitched repetition and end-of-quantizer-levels are indicated by negative numbers.

(iv) The run length value can be selected at initialization.

### 12.6 Program Timing and Speed

The programs in the real time implementation of PARC get executed in parallel on the different processors of the MAP 300. The set of programs on a given processor must be executed once in each time frame. The number of samples processed by these programs is not constant. It varies from about 50 during the voiced regions of speech to about 520 during the transition regions following voiced speech. For the algorithm to operate at its peak performance, the programs should be able to process the maximum number of 520 samples within a time frame. This is, however, limited by processor speeds and program efficiency.

The average number of samples that need to be processed by any program is 126; and it is imperative that the programs be able to process at least a few extra samples if necessary. Currently, the programs do satisfy this minimum requirement. The pitched reduction program, PARC transmitter, and PARC receiver which operate on the AP can process about 150 samples per time frame. The encoder and decoder programs which operate on the CSPU can process about 200 samples per time frame. So currently, the limit on the number of samples processed is set at 150. This exceeds the minimum requirement only marginally, and speeding up the programs would improve the performance of the algorithm considerably. Some ways to achieve this improvement are suggested below, and it is expected that different programs will execute 20% to 50% faster as a result of these modifications.

The pitched reduction program which currently requires about 5 msec can be speeded up 100% by doubling the parallelism in its computation. The transmitter and receiver programs need to be reorganized in terms of their register usage and operation sequencing. This should provide approximately 30% speed

improvement. These changes should increase the number of samples processed on the AP by about 50%.

The encoder can be speeded up 25% by rearranging the encoding table and changing all memory access from indirect to direct addressing. This would require the input quantizer levels to be  $2(q-1)$  instead of  $2q$  as they are now. The decoder can be improved slightly by rearranging its decoding table and operation sequencing.

Two of the three buses on the MAP 300 have slower MOS memories. Changing these to the fast bipolar memory would also help the speed on the various processors because of the large number of memory transfers performed in each time frame. With these modifications, it is expected the algorithm would be able to process 250-300 samples per time frame instead of the 150 it does now. Although this still allows the algorithm to operate well below its peak level of fidelity, this is about the level of performance that can be expected given the current speed of the MAP 300 array processor.

## APPENDIX E

### RESAMPLING PROGRAM

During the course of this project, because of the different sampling rates at which digitized speech was available from various sources and the different rates at which it was utilized, it was found necessary to develop an efficient resampling program to enable us to easily change sampling rates of speech. The following briefly describes the resampling algorithm and the operational details of the program. Fig. E.1 shows the flow chart, and program listings are included at the end of this appendix.

Sampled speech is the pulse amplitude representation of an analog speech signal at a sequence of time points separated by  $T_1$ . At another sampling rate, it is the PAM representation of the same signal at a different set of points separated by  $T_2$ . The new set can be obtained by interpolation from the first set of samples. So as also to limit the bandwidth of signals, interpolation was performed by discrete convolution of the original samples with the truncated impulse response of an ideal low pass filter. A first order Hamming window was used for truncation to reduce the effects of truncation. The impulse response and the Hamming window have the following form:

$$H_F(t-\tau) = 2F \operatorname{sinc}(2F \pi \tau) \quad -\infty < \tau < \infty$$

and

$$W_T(t-\tau) = \alpha + (1-\alpha) \cos(\pi \tau/2T) \quad -T < \tau < T$$

$$\alpha = 0.7$$

The convolution function is the product of these two. The discrete version of the convolution function is scaled down by  $T_1$ , to compensate for the scaling introduced by discrete filtering.

$$C_1(nT_2 - (m-1)T_1) = \frac{2F}{T_1} \{ \alpha + (1-\alpha) \cos [((mT_1 - nT_2) + iT_1)/NT_r] \}$$

$$\{ \operatorname{sinc}[2F\pi((mT_1 - nT_2) + iT_1)] \}, \quad \frac{-NT_r}{T_1} < i < \frac{NT_r}{T_1}$$

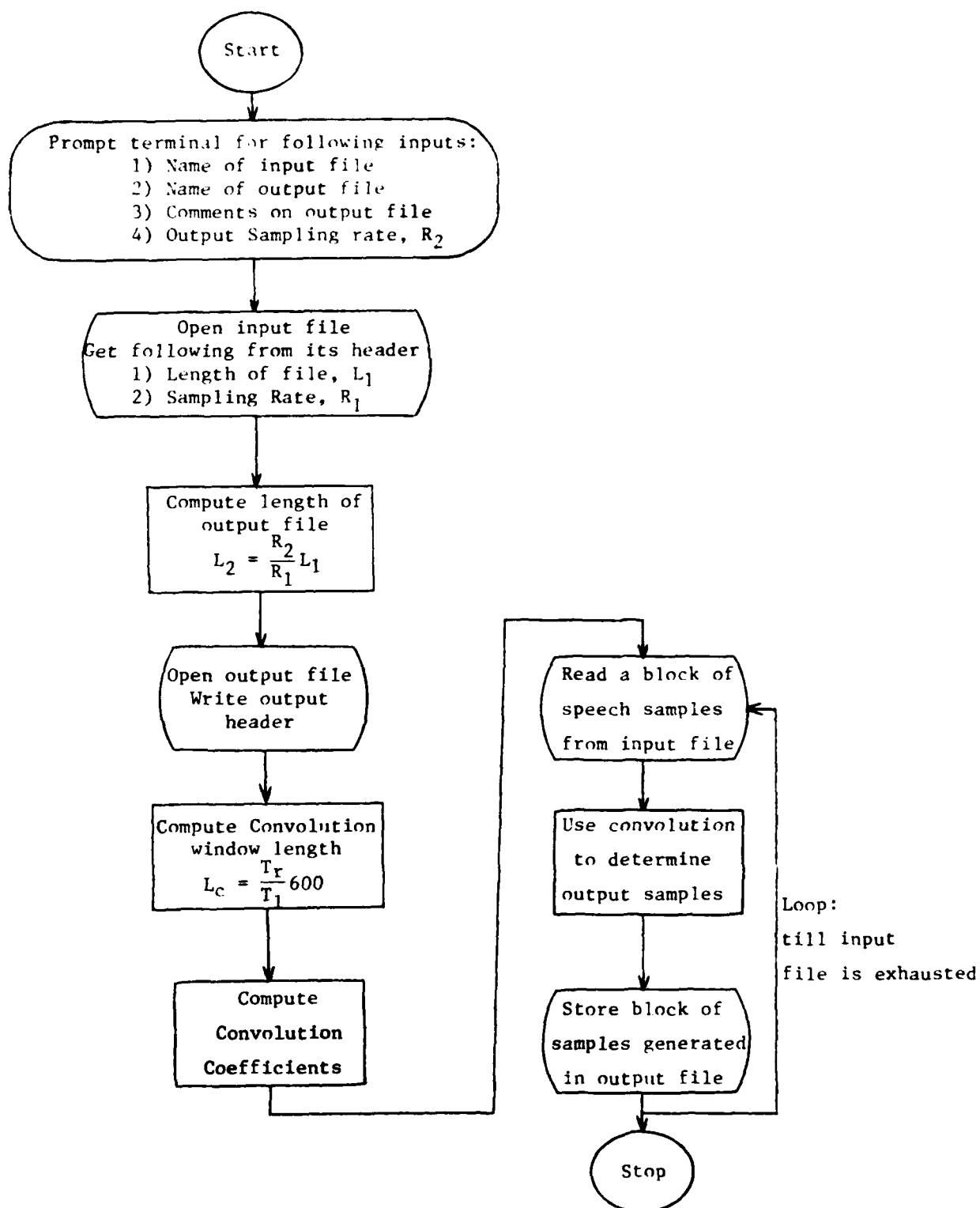


Fig. E.1 Flow Chart for the Resample Program

Here  $nT_2$  identifies the  $n$ th output sample and  $mT_1$  the closest preceding input sample.

Because the phase  $(mT_1 - nT_2)$  changes arbitrarily, the correlation coefficients need to be computed for each output sample. However, if the two sampling rates are integer submultiples of a higher frequency  $1/T_r$  called the reference frequency, the  $C_i$  need to be evaluated only once at the reference frequency. The phase  $(mT_1 - nT_2)$  is always a multiple of  $T_r$ , and a subset of these coefficients can be utilized to perform the convolution. This reduces the computation required in the program by about an order of magnitude. For the different rates required in this project, the frequency 96000 is an integer multiple and was selected as the reference frequency.

Two versions of the resampling program were developed. In the first, all computation, initialization as well as the convolution (which comprises the bulk of the computation in resampling) is done on the PDP 11/60. In the second, the convolution is performed on the MAP 300 array processor using the SNAP-II software package of array functions supplied by CSPI. The PDP 11 does the initialization and handles the I/O interfacing between the disk and the MAP 300. The second version is almost an order of magnitude faster than the first.



### E.1 Operating Details

The program is segmented into four modules. The main program acquires all relevant parameters required for the resampling operation, either from the header record of the input speech file or from the terminal. This program prompts for each input from the terminal, and if requested, gives a brief description, shows an acceptable example, and specifies the bound on the value of the input. The second module performs the convolution for resampling. The other two modules assist in the initialization by computing the convolution coefficients. Between the two versions of the program only the second module is different. The appropriate module is selected during the process of task-building.

To obtain an executable task image, the appropriate modules must be compiled and task-built. The following describes this process for the RSX11M operating system on a PDP 11 computer. The compilation step for each module has the following form.

```
>FOR MODULE = MODULE/I4
```

The task-building step is slightly different for the two versions. The command format for the first version is:

```
>TKB
TKB> QRESAM/CP/FP = MOD1, MOD2, MOD3, MOD4
TKB> /
ENTER OPTIONS:
TKB> UNITS = 7
TKB> ACTFIL = 7
TKB> //
```

---

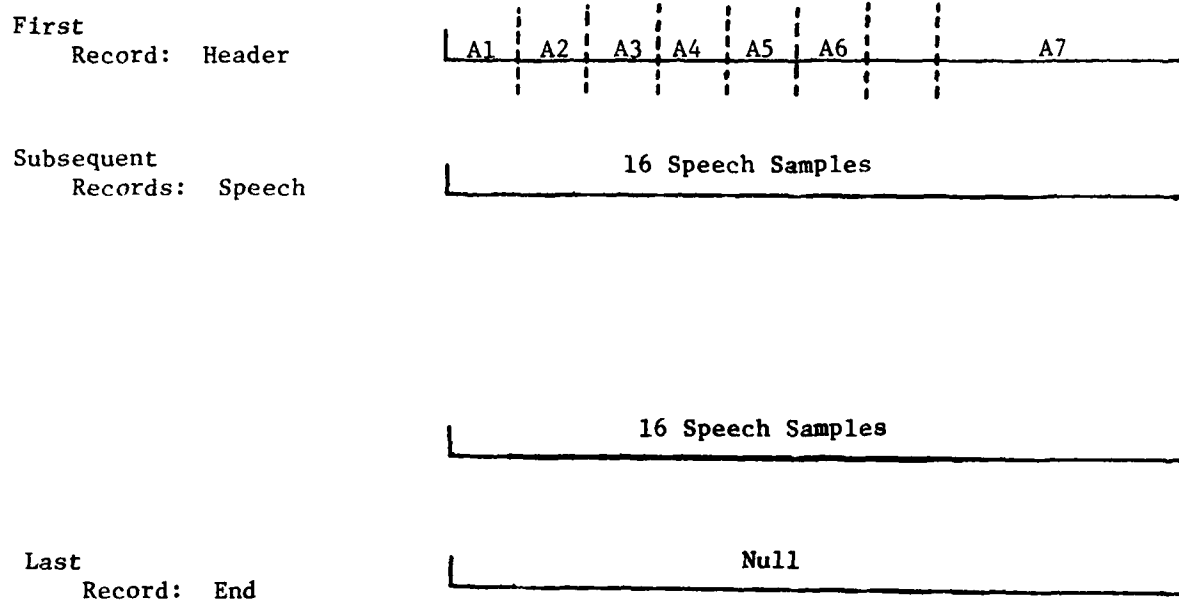
The underlined text is the prompt by the computer. The following text is the response by the user.

For the second version, the SNAP library must also be included in the task-building step.

```
>TKB
TKB> MRESAM/CP/MP = MOD1, MOD2, MOD3, MOD4, SNAPLIB/LB
TKB> /
ENTER OPTIONS:
TKB> UNITS = 10
TKB> ACTFIL = 10
TKB> //
```

The program requires the input speech file to conform to the Notre Dame speech file format. Fig. E.2 illustrates this format. The first record is the header. The seven fields in it are sentence identification number, sampling rate, number of samples in the files, lower and upper cutoff frequencies, truncation number for the convolution window, and comments identifying the speech file. The upper cutoff frequency is not used in this program. The truncation number which specifies the length of the convolution window is internally computed by the program based on the input sampling rate. Each of the subsequent records in the file contain 16 speech samples in the 15 format. The amplitude of speech samples is limited between -2048 and 2047. The speech file must end with a null record.

The output file generated by the resampling program also conforms to this format.



Format for each record of 80 columns

Header: (6I5, 10X, 2042)

Speech: (16I5)

Fig. E.2 Notre Dame Speech File Format

```

*****
*
* MAINLINE INFO QRESAMPLE
*
*****

                ARVIND S ARORA

THIS PROGRAM SEEKS OUT THE INFORMATION NECESSARY TO
RUN THE QRESAMPLE SUBROUTINE. IT THEN OPENS THE INPUT AND OUTPUT
FILES,WRITES THE OUTPUT HEADER AND TRANSFERS CONTROL TO
QRESAMPLE. THE FOLLOWING INFORMATION IS SOUGHT:
1)NAM1      INPUT FILE NAME
2)NAM2      OUTPUT FILE NAME
3)IRATE1    INPUT SAMPLING RATE (FROM INPUT FILE HEADER)
4)IRATE2    OUTPUT SAMPLING RATE
5)NLEN1
5)NLEN1
5)NLEN2
7)IF1      LENGTH OF INPUT FILE (FROM INPUT FILE HEADER)
            LENGTH OF OUTPUT FILE, ONLY IF PARTIAL
            OUTPUT IS DESIRED
            FILTER CORNER FREQ
            (RESTRICTED TO INTEGER SUB-MULTIPLES OF 96000)
            (IGNORE)
8)IF2      TRUNCATION NO. FOR FILTER
9)ITRUN    NO. OF TERMS IN FILTER=2*ITRUN+1
            (THIS IS DETERMINED BY THE PROGRAM DEPENDING ON IF1)
10)HEAD1   INPUT FILE HEADER COMMENTS (FROM INPUT FILE)
11)HEAD2   OUTPUT FILE HEADER COMMENTS

```

```

0001 INTEGER=2 NAM1(16),NAM2(16),HEAD1(20),HEAD2(20)
0002 LOGICAL=1 ANS,CHAR(3)
0003 COMMON /RESAM/NIEN1,NLEN2,IRATE2
0004 COMMON /COFF/IF1,IF2,ITRUN,IRATE1
0005 DATA CHAR/..N..V./
0006 TYPE .., SOLICITING INFORMATION FOR RESAMPLING.
0007 TYPE ..,
0008 TYPE ..,
0009 TYPE 1009 IVANTO TO SEE EXAMPLES?
0010 ACCEPT 1003,ANS
0011 IFL=1
0012 IF(ANS.EQ.CHAR(3)) IFL=2
C ----- BEGIN QUERY
100 CONTINUE
C ----- NAME OF INPUT FILE
0014 IF(IFL.EQ.1) GO TO 110
0015 TYPE .., EXAMPLE OF FILE NAME **
0016 TYPE .., DK:LSB.S01S11564.DAT,1'
0017 TYPE 1010 ENTER INPUT FILE NAME
0018 ACCEPT 1001,NAM1
0019 NAM1(16)=0

```



```

FORTRAN IV-PLUS V02-51      16:14:00      15-APR-68      PAGE 3
GRESAMINF.FTN /14/TR:BLOCKS/WR

2006 ACCEPT 1003,ANS
2007 IF(ANS.NE.CHAR(3)) GO TO 2008 ICOMPLETE OUTPUT
2008 TYPE 1014 I DESIRED LENGTH OF FILE
2009 ACCEPT ' ',NLEN2
2010 TYPE ' ',NLEN2
2011 CONTINUE
2012 C -----
2013 OUTPUT FILE NAME
2014 TYPE 1019 IPROMPT FOR OUTPUT FILE NAME
2015 ACCEPT 1001,NAM2
2016 TYPE 1004,NAM2
2017 NAM2(16)=#
2018 C -----
2019 HEADER COMMENTS
2020 TYPE ' ',# ENTER HEADER COMMENTS, 40 CHARACTERS OR LESS'
2021 IF(IFL.EQ.1) GO TO 210
2022 TYPE 1015, HEAD1
2023 CONTINUE
2024 C -----
2025 IHEADER COMMENTS PROMPT
2026 TYPE 1016 IHEADER COMMENTS PROMPT
2027 ACCEPT 1001,HEAD2
2028 TYPE ' ',# THE HEADER CARD FOR THE OUTPUT FILE IS:'
2029 TYPE 1005,ISEN,IRATE2,NLEN2,IF1,IF2,ITRUN,HEAD2
2030 ONE OPPORTUNITY TO CHANGE ENTRIES
2031 C -----
2032 TYPE 1017 IVANNA CHANGE SOMETHING
2033 ACCEPT 1003,ANS
2034 IF(ANS.EQ.CHAR(3)) GO TO 1008 I DO WANT TO CHANGE
2035 OPEN(UNIT=2,NAME=NAM2,TYPE='NEW',CARRIAGECONTROL='LIST',ERR=220)
2036 WRITE(2,1000) ISEN,IRATE2,NLEN2,IF1,IF2,ITRUN,HEAD2
2037 TYPE ' ',# BEGINNING RESAMPLING. WILL INFORM YOU ' ,
2038 I'ON COMPLETION'
2039 CALL RESAMP(1,2)
2040 STOP
2041 220 CONTINUE
2042 TYPE ' ',# ERROR -- FAILED TO OPEN OUTPUT FILE'
2043 TYPE ' ', LOCATE PROBLEM AND TRY AGAIN'
2044 STOP
2045 1000 FORMAT(615,10X,20A2)
2046 1001 FORMAT(20A2)
2047 1002 FORMAT(615)
2048 1003 FORMAT(A1)
2049 1004 FORMAT(1X,20A2)
2050 1005 FORMAT(1X,615,10X,20A2)
2051 1006 FORMAT('S' DO YOU WISH TO SEE EXAMPLES OF RESPONSES? (Y,N):')
2052 1007 FORMAT('S' ENTER INPUT FILE NAME. NAME=')
2053 1008 FORMAT('S' ENTER RESAMPLING RATE. RATE=')
2054 1009 FORMAT('S' ENTER CORNER FREQ F1=')
2055 1010 FORMAT('S' WOULD YOU LIKE A PARTIAL OUTPUT? (Y,N):')
2056 1011 FORMAT('S' ENTER LENGTH DESIRED. LENGTH=')
2057 1012 FORMAT('S' EXAMPLE: ',20A2)
2058 1013 FORMAT('S' COMMENTS: ')
2059 1014 FORMAT('S' DO YOU WISH TO CHANGE ENTRIES? (Y,N):')
2060 1015 FORMAT('S' ENTER TRUNCATION NUMBER. ITRUN=')
2061 1016 FORMAT('S' ENTER OUTPUT FILE NAME. NAME=')
2062 1017
2063 1018
2064 1019
2065 1020
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2068 1023
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2144 1099
2145 1100
2146 1101
2147 1102
2148 1103
2149 1104
2150 1105
2151 1106
2152 1107
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2154 1109
2155 1110
2156 1111
2157 1112
2158 1113
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2168 1123
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*****
*
* SUBROUTINE RESAMP(NIN,NOUT)
*
*****

ARVIND S ARORA

PROGRAM DESCRIPTION:

THIS PROGRAM RESAMPLES A GIVEN FILE AT ONE SAMPLING
RATE TO THAT AT ANOTHER SAMPLING RATE. BECAUSE THE COEFFS
REQUIRED FOR THE FILTERING OPERATION DURING RESAMPLING ARE
COMPUTED ONLY ONCE AT 96000 SAMPLES/SEC, THE INPUT AND
OUTPUT FREQUENCIES ARE RESTRICTED TO INTEGER SUB-MULTIPLES
OF 96000, E.G. 16000, 12000, 9600, 6400. HOWEVER THIS MAKES
THIS PROGRAM OPERATE AN ORDER OF MAGNITUDE FASTER THAN THE
GENERAL VERSION OF RESAMP. ALL COMPUTATIONS IN THIS PROGRAM
ARE DONE IN THE PDP-11 CPU.

THE PROGRAM REQUIRES THE FOLLOWING INFORMATION BEFORE IT
CAN RESAMPLE A GIVEN FILE:

1) NIN LUN FOR INPUT FILE
2) NOUT LUN FOR OUTPUT FILE
3) NLEN1 LENGTH OF INPUT FILE
4) NLEN2 LENGTH OF OUTPUT FILE
5) IRATE1 SAMPLING RATE OF INPUT FILE
6) IRATE2 SAMPLING RATE OF OUTPUT FILE
7) IF1 CORNER FREQ OF FILTER
8) IF2 (IGNORED)
9) ITRUN (IGNORED)

IN ADDITION THE INPUT AND OUTPUT FILES MUST BE OPEN
FOR ACCESS.

DATA FORMATS:

BOTH THE INPUT & OUTPUT SAMPLES MUST HAVE VALUES V IN THE
RANGE -2048 TO 2047 (12 BIT RESOLUTION). THEY MUST BE STORED
USING A (1615) FORMAT.

SIGNIFICANT VARIABLES:

1) A1 INPUT FILE BUFFER (INTEGER*2)
2) A2 OUTPUT FILE BUFFER (INTEGER*2)
3) H FILTER COEFFS (REAL)
SYMMETRIC, CENTRE COEFF IN H(1),
COEFFS ONLY FOR +VE TIME

```

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 QRESAMP.FTN /I4/TR:BLOCKS/VR

C CALLS TO SUBROUTINES:

1)SUBROUTINE ERRSET(24,...,FALSE...)  
 2)FUNCTION-SUBROUTINE SECNDS(TIME)  
 3)SUBROUTINE COEFF(H??)

```

9991 SUBROUTINE RESAMP(NIN,NOUT)
9992   INTEGER*2 A1(32),A2(16)
9993   DIMENSION H(64)
9994   COMMON /RESAMP/NLEN1,NLEN2,IRATE2
9995   COMMON /COFF/IF1,IF2,ITRUN,IRATE1
9996   CONTINUE
9997   NLEN2=NLEN2-1
9998   IF(96888/IRATE1=IRATE1.NE.96888) GO TO 118
9999   IF(96888/IRATE2=IRATE2.NE.96888) GO TO 118
1000   GO TO 128
1001   C ----- INDICATE ILLEGAL FREQUENCIES AND STOP
1002   118 CONTINUE
1003   CLOSE(UNIT=NIN,DISPOSE='SAVE')
1004   CLOSE(UNIT=NOUT,DISPOSE='DELETE')
1005   TYPE '... ERROR QUICK RESAMPLE.'
1006   TYPE '...'
1007   TYPE '... THIS SUBROUTINE HANDLES ONLY A LIMITED SET OF FREQS.'
1008   TYPE '... INPUT AND OUTPUT FREQS MUST BE SUBMULTIPLES OF 96888'
1009   TYPE '... AND YOUR FREQS ARE, IN FREQ=,IRATE1, OUT FREQ=,IRATE2'
1010   STOP
1011   128 CONTINUE
1012   CALL ERRSET(24,...,FALSE...)
1013   C ----- INITIALIZE CLOCK TO COMPUTE TIME REQUIRED FOR RESAMPLING
1014   CLCK=SECNDS(8.8)
1015   288 CONTINUE
1016   C ----- INITIALIZE ALL VARIABLES AND THE INPUT BUFFER
1017   INTV1=96888/IRATE1
1018   INTV2=96888/IRATE2
1019   NBUF1=328
1020   NBUF2=168
1021   IHOLD=ITRUN
1022   ITRUN=688/INTV1
1023   NFLG1=ITRUN+1
1024   NFLG2=NBUF1-ITRUN
1025   IBUF1=NFLG1+MOD((NBUF1-NFLG1+1),16)
1026   DO 218 IAI=1,IBUF1-1
1027     A1(IAI)=8
1028   218 CONTINUE
1029   READ(NIN,1888)(A1(IAI),IAI=IBUF1,NBUF1)
1030   C ----- INITIALIZE INDICES
1031   IA1=8
1032   IA2=8
1033   IBUF2=1
1034   C ----- CAL SUBROUTINE TO COMPUTE COEFFICIENTS
1035   CALL COEFF(H)
1036   INTVN=INTV1+1

```



```

TRA--PL--B2-16--44--5-A--AGE
RESAMP.FIN /14/TR:BLOCKS/WR

C----- BEGIN CONVOLUTION LOOP FOR FILTERING
22# CONTINUE
C----- COMPUTE PHASE AND INITIALIZE INDICES FOR CONVOLUTION
IPHASE=IA2-INTV2-IA1*INTV1
IIN=IBUF1-1
IIP=IBUF1+1
IHN=INTVN+IPHASE
IHP=INTVN-IPHASE
C----- PERFORM CONVOLUTION
SUM=H(1+IPHASE)*A1(IBUF1)
DO 25# I1=IHN,601,INTV1
SUM=SUM+H(I1)*A1(IIN)+H(IHP)*A1(IIP)
IIN=IIN-1
IIP=IIP+1
IHP=IHP+INTV1
25# CONTINUE
ITEMP=SUM
IF(ITEMP.GE.2048) ITEM=2047
IF(ITEMP.LT.-2048) ITEM=-2048
A2(IBUF2)=ITEMP
C----- CONVOLUTION COMPLETED
C
C----- INCREMENT VARIOUS INDICES
IA2=IA2+1
IBUF2=IBUF2+1
C----- FIND CORRESPONDING INDICES IN THE INPUT FILE
INEXT=INTV2-IA2/INTV1
IBUF1=IBUF1+INEXT-IA1
IA1=INEXT
C----- CHECK IF OUTPUT FILE IS COMPLETE
IF(IA2.LE.NLEN2) GO TO 30# IIF NOT COMPLETE, PROCEED
IF FILE COMPLETE, WRITE OUTPUT BUFFER, CLOSE FILES & QUIT
WRITE(NOUT,1000) (A2(J),J=1,IBUF2-1)
NLEN2=NLEN2+1
ITRUN=I HOLD
C----- FIGURE OUT TIME TAKEN, SAY OPERATION COMPLETE & QUIT
CLK=SECONDS(CLK)
TYPE '...', TIME FOR RESAMPLING = '.CLK.' SECONDS'
TYPE '...',
TYPE '...',
TYPE '...', RESAMPLING OPERATION COMPLETE.'
RETURN
C----- CHECK IF OUTPUT BUFFER IS FULL
30# CONTINUE
IF(IBUF2.LE.NBUF2) GO TO 31# IIF NOT FULL, PROCEED
IF FULL, WRITE OUT OUTPUT BUFFER & INITIALIZE FLAG IBUF2
WRITE(NOUT,1000) A2
IBUF2=1
C----- CHECK IF RUN OUT OF INPUT BUFFER
31# CONTINUE
IF(IBUF1.LE.NFLG2) GO TO 35# IIF NOT RUN OUT, PROCEED
IF RUN OUT, REPLENISH BUFFER BY MOVING OLD DATA OVER
IFLNXT=NFLG1+MOD((IBUF1-NFLG1),16)
ISHFT=IBUF1-IFLNXT
IBUF1=IFLNXT
DO 32# J=ISHFT+1,NBUF1

```

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QRESAMP.FTN /14/TR:BLOCKS/VR

2004      A1(J-ISHFT)=A1(J)
2005      CONTINUE
2006      C -----
2007      FILL IN THE REST OF THE BUFFER WITH NEW DATA
2008      READ(NIN,1000,ERR=330) (A1(J),J=NBUFF1-ISHFT+1,NBUFF1)
2009      GO TO 350 IREAD IN BUFFER, SO PROCEED
2010      C -----
2011      RAN OUT OF INPUT SAMPLES SO FILL IN BUFFER WITH ZEROS
2012      CONTINUE
2013      DO 340 J1=J,NBUFF1
2014      A1(J1)=0
2015      CONTINUE
2016      C -----
2017      ALL SYSTEMS GO 1 BACK FOR NEXT SAMPLE
2018      GO TO 220
2019      C -----
2020      ALL THOSE LOUSY FORMAT STATEMENTS
2021      C
2022      1000 FORMAT(16I5)
2023      END
2024

```



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 MAPRESAM1.FTN /14/TR:BLOCKS/VR

```

C SIGNIFICANT VARIABLES:
C
C 1) A1 INPUT FILE BUFFER (INTEGER*2)
C 2) A2 OUTPUT FILE BUFFER (INTEGER*2)
C 3) N FILTER COEFFS (REAL)
C SYMMETRIC. CENTRE COEFF IN H(1),
C COEFFS ONLY FOR +VE TIME
C
C CALLS TO SUBROUTINES:
C
C 1) SUBROUTINE ERRSET(24,.....FALSE..)
C 2) FUNCTION-SUBROUTINE SECNDS(TIME)
C 3) SUBROUTINE COEFF(H?)
C 4) SUBROUTINES IN SNAP LIBRARY
C
C .....
C
C SUBROUTINE RESAMP(NIN,NOUT)
C INTEGER*2 A1(648),A2(648)
C INTEGER SP2847,SN2848,SFLAG
C DIMENSION H(681)
C COMMON /RESAMP/NLEN1,NLEN2,IRATE2
C COMMON /COFF/IF1,IF2,ITRUN,IRATE1
C CONTINUE
C
C ----- NAMES OF VARIOUS BUFFERS IN MAP AND HOST
C NMRI=1 1 INPUT BUFFER IN HOST: A1
C NMRI=2 1 OUTPUT BUFFER IN HOST: A2
C
C NMRI=28
C NMRI=21
C NMRI=22
C NMRI=23
C NMRI=24
C NMRI=25
C NMRI=26
C NMRI=27
C NMRI=28
C NMRI=11
C NMRI=12
C NMRI=13
C NMRI=14
C NMRI=38
C NMRI=31
C NMRI=32
C
C ----- NAMES OF VARIOUS SCALARS IN MAP
C SP2847=58
C SN2848=51
C SFLAG=52
C IF(96888/IRATE1*IRATE1.NE.96888) GO TO 118
C IF(96888/IRATE2*IRATE2.NE.96888) GO TO 118
C IF(1181*GT.32888.OR.IRATE1.LT.6488) GO TO 118
C IF(1182*GT.32888.OR.IRATE2.LT.6488) GO TO 118
C GO TO 128

```

```

C ----- INDICATE ILLEGAL FREQUENCIES AND STOP
110 CONTINUE
CLOSE(UNIT=NIN,DISPOSE='SAVE')
CLOSE(UNIT=NOUT,DISPOSE='DELETE')
TYPE '*** ERROR QUICK RESAMPLE.'
TYPE '...'
TYPE '...' THIS SUBROUTINE HANDLES ONLY A LIMITED SET OF FREQS.
TYPE '...' INPUT AND OUTPUT FREQS MUST BE SUBMULTIPLES OF 96000.
TYPE '...' AND MUST LIE BETWEEN 6400 AND 32000.
TYPE '...' AND YOUR FREQS ARE, IN FREQ=,IRATE1, OUT FREQ=,IRATE2
STOP
120 CONTINUE
CALL ERASET(24,.....FALSE,.)
INITIALIZE CLOCK TO COMPUTE TIME REQUIRED FOR RESAMPLING
CLK=SECONDS(0.0)
C ----- CALL SUBROUTINE TO COMPUTE COEFFICIENTS
C ----- CALL SUBROUTINE TO COMPUTE COEFFICIENTS
200 C ----- CCNVOOLUTION LOOP STARTING #200
CONTINUE
INTV1=96000/IRATE1
INTV2=96000/IRATE2
NPACK1=1920/INTV1
NPACK2=1920/INTV2
C ----- OPEN MAP
C ----- CALL REPORT(10,MPOPN(0))
C ----- CONFIGURE INPUT AND CCNVOOLUTION BUFFERS
CALL REPORT(20,MPCLB(MB1,0,3120,0,1,0))
CALL REPORT(30,MPCLB(MB2,5040,0,0,0,0,0,INTV1,0))
CALL REPORT(40,MPCLB(MB12,5040,0,0,0,0,0,INTV1,0))
CALL REPORT(50,MPCLB(MB13,1200,0,0,0,0,0,INTV1,0))
CALL REPORT(55,MPCLB(MB13,1200,0,0,0,0,0,INTV1,0))
SIZE=000/INTV1-1
CALL REPORT(60,MPCLB(MB4,1200,0,0,0,0,0,INTV1,0))
CALL REPORT(70,MPEOB(MB5,MBR2))
CALL REPORT(80,MPCLB(MB6,5040,0,0,0,0,0,INTV1,0))
C ----- CONFIGURE OUTPUT BUFFERS
CALL REPORT(90,MPCLB(29,9000,0,0,0,0,0,INTV1,0))
CALL REPORT(100,MPEOB(MB1,29))
CALL REPORT(110,MPCLB(29,11000,0,0,0,0,0,INTV1,0))
CALL REPORT(120,MPEOB(MB2,29))
CALL REPORT(130,MPCLB(29,9000,0,0,0,0,0,INTV1,0))
CALL REPORT(140,MPEOB(MB1,29))
CALL REPORT(150,MPCLB(29,11000,0,0,0,0,0,INTV1,0))
CALL REPORT(160,MPEOB(MB2,29))
C ----- CONFIGURE COEFF BUFFERS
CALL REPORT(170,MPCLB(MC0,0,1200,0,0,1,0))
CALL REPORT(180,MPCLB(MC1,1200,0,0,1,0))
CALL REPORT(190,MPCLB(MC2,1200,0,0,1,0))
C ----- CONFIGURE MOST RESIDENT BUFFERS
CALL REPORT(200,MPODN(MB1,1,1),A1(NPACK1))
CALL REPORT(202,MPODN(MB2,A2(1),A2(NPACK2))
INITIALIZE INPUT BUFFER AREA TO ZERO
CALL REPORT(205,MPCLB(29,0,4500,0,1,0))
CALL REPORT(206,MPCLB(MZERO,0,4500,0))
CALL REPORT(207,VSM1(28,0,MZERO,0))
C ----- WRITE IN THE SCALARS

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0070 CALL REPORT(211,MPVST(SP2B47,2B47,.1,1))
0080 CALL REPORT(212,MPVST(SN2B48,-2B48,.1,1))
0090 CALL REPORT(213,MPVST(SFLAG,1B,.1,1))
0100 C ----- COPY COEFFS INTO COEFF BUFFER
0110 CALL REPORT(220,MPVDB(MC1,H(1),4,1,H(51)))
0120 CALL REPORT(230,MPVDB(MC2,H(1),4,1,H(51)))

```

### C ---- MAP FUNCTION LISTS

```

C ----- FUNCTION LIST 1 (USES OUTPUT BUFFER 1)
0004 CALL REPORT(248,MPBFL(1))
0005 CALL REPORT(258,VFLT(MBR2,39,MB12,8))
0006 CALL REPORT(268,DCVH(MBR1,INTV2,MBR1,MCB))
0007 CALL REPORT(278,VSMAL(MBR4,1,MBR6,8))
0008 CALL REPORT(288,VSMAL(MBR3,1,MBR5,8))
0009 CALL REPORT(298,VCLIP(MOR1,SP247,MOR1,SN2548))
0010 CALL REPORT(308,VFIX(MO11,38,MOR1,11))
0011 CALL REPORT(318,MPBFO(MB12,NHR1,2,1))
0012 CALL REPORT(328,MPBFI(MO11,NHR2,2,1))
0013 CALL REPORT(338,MPEFL(1))

```

C ----- FUNCTION LIST 2 (USES OUTPUT BUFFER 2)

00094 CALL REPORT(345,MP8FL(2))  
00095 CALL REPORT(350,VFLT(MBR2,39,MB12,B))  
00096 CALL REPORT(355,DVCM(MOR2,INTV2,MBR1,MCS))  
00097 CALL REPORT(370,VSHA(MBR4,1,MBR6,B))  
00098 CALL REPORT(380,VSWA(MBR3,1,MBR5,B))  
00099 CALL REPORT(390,SP2B(MOR2,SP2B47,MOR2,SN2B48))  
0100 CALL REPORT(400,VFLX(MO12,30,MOR2,11))  
0101 CALL REPORT(410,MP8FO(MB12,NHR1,2,1))  
0102 CALL REPORT(420,MP8FI(MO12,NHR2,2,1))  
0103 CALL REPORT(430,MPEFL(2))

C ----- FUNCTION LIST 3 (MASTER FUNCTION LIST)

```

0104 CALL REPORT(44B,MPXFL(3))
0105 CALL REPORT(45B,MPXFL(1))
0106 CALL REPORT(46B,MPXFL(2))
0107 CALL REPORT(47B,MPEFL(3))
C ----- END OF FUNCTION LISTS IN MAP

```

C ----- PREPARING FOR LOOP IN HOST

```

C ----- INITIALIZE VARIOUS POSITION FLAGS. INITIALIZE INPUT BUFFER
C BUFFER IN MAP. TURN OVER OUTPUT BUFFER TO MAP
0100 READ(NIN,1555)IA(1:J),IA(1-NPACK1)
0110 CALL REPORT(555,MPVDB(MB13,A(1),2),A1(NPACK1))
0110 CALL REPORT(515,VFLT(MB13,39,MB13,B))

```

```

0111 READ(IN,1000)(A1(A1),IA1=1,NPACK1)
0112 CALL REPORT(525,MPVDB(MB12,A1(1),2,1,A1(NPACK1)))
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0122 RETURN(522,721(MBRS,33,MB13,B7))
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CALL REPORT(538,MPFBA(NHR2))

0114  
0115  
10UT-8  
CALL REPORT(548,MPWHL(SFLAG,2.3))

```

0110 C----- HOST LOOP
0110 400 CONTINUE
0110 C----- INPUT TO MAP

```

```

0117 C CALL REPORT(555,MPVBA(NHR1))
0118 READ(MIN,1000,ERR=455)(A1(A1),IA1=1,NPACK1)
0119 GO TO 555
C -----
0120 455 RUN OUT OF INPUT, FILL IN WITH ZEROS
CONTINUE
0121 DO 465 JAI=IA1,NPACK1
0122 A1(JAI)=0
0123 CONTINUE
C -----
0124 465 IF NOT RUN OUT, CARRY ON WITH SAMPLES READ IN
CONTINUE
0125 CALL REPORT(565,MPFBA(NHR1))
OUTPUT FROM MAP
C -----
0126 CALL REPORT(575,MPVBA(NHR2))
0127 IOUT=IOUT+NPACK2
0128 IF(IOUT.GE.NLEN2) GO TO 555
0129 WRITE(ROUT,1000)(A2(IA2),IA2=1,NPACK2)
0130 CALL REPORT(595,MPFBA(NHR2))
0131 GO TO 455
C ----- END OF HOST LOOP
C -----
C ----- IF YOU GOT ALL OUTPUT SAMPLES, STOP MAP LOOP AND RETURN
C -----
0132 555 CONTINUE
C -----
0133 ILST2=NPACK2+NLEN2-IOUT
0134 WRITE(ROUT,1000)(A2(IA2),IA2=1,ILST2)
C -----
0135 FIGURE OUT TIME TAKEN, SAY OPERATION COMPLETE & QUIT
CLCK=SECONDS(CLCK)
TYPE '...'
TYPE '...' TIME FOR RESAMPLING =',CLCK,' SECONDS'
TYPE '...'
TYPE '...' RESAMPLING OPERATION COMPLETE.'
C -----
0136 CLOSE MAP
CALL REPORT(615,MPCLS(B))
RETURN
C -----
C ----- AND THEN THERE'S THE FORMAT STATEMENTS
0142 1000 FORMAT(16I5)
0143 END

```

PORTMAN IV-PLUS V82-S1 16:17:53 15-APR-88  
MAPRESAM1.FTH /14/TR:BLOCKS/VR

PAGE 8

```
C ----- SUBROUTINE TO REPORT MAP ERRORS
C
0001 SUBROUTINE REPORT(I,J)
0002 INTEGER*2 I,J
0003 IF(J.EQ.0) RETURN
0004 TYPE *,** MAP ERROR',J,' AT',I
0005 STOP
0006 END
```





PAGE 2

15-APR-88

16:10:34

FORTRAN IV-PLUS V02-51  
GCOEFF.PTN /14/TR:BLOCKS/WR

0014 RETURN  
0015 END

[illegible]

## APPENDIX F CVSD ALGORITHM

In this appendix, the CVSD algorithm will be discussed. Before the design of this real-time CVSD system can be presented, it is essential to understand the structure of CVSD systems.

### F.1 The CVSD System

In this section, the structure of a CVSD system is presented. The system described here is identical to that of [1]. A schematic of an encoder and decoder pair for CVSD is shown in Figure F.1.

A CVSD encoder is simply a delta modulator with an adaptive stepsize. In order to minimize the difference between adjacent samples, the input signal  $s(k)$  is normally oversampled. Typically, the sampling rate is 16 k samples per second. Since one bit per sample is transmitted, the transmission rate is 16 K bits per second.

The encoder quantizes the difference  $e(k)$  between an input speech sample and its estimate which is predicted by a first order predictor.

$$e(k) = s(k) - \alpha * \hat{s}(k-1)$$

where  $\hat{s}(k-1)$  is the reconstructed speech of the input speech sample at time  $k-1$ . Then the encoder outputs a single bit,  $b(k)$ , for each corresponding input sample where

$$b(k) = \begin{cases} 1 & \text{if } e(k) \geq 0 \\ 0 & \text{if } e(k) < 0 \end{cases}$$

The adaptive stepsize logic derives its output  $\Delta(k)$  from the bit stream  $b(k)$  and an appropriate initial state,

$$\Delta(k) = \beta * \Delta(k-1) + g(k)$$

where

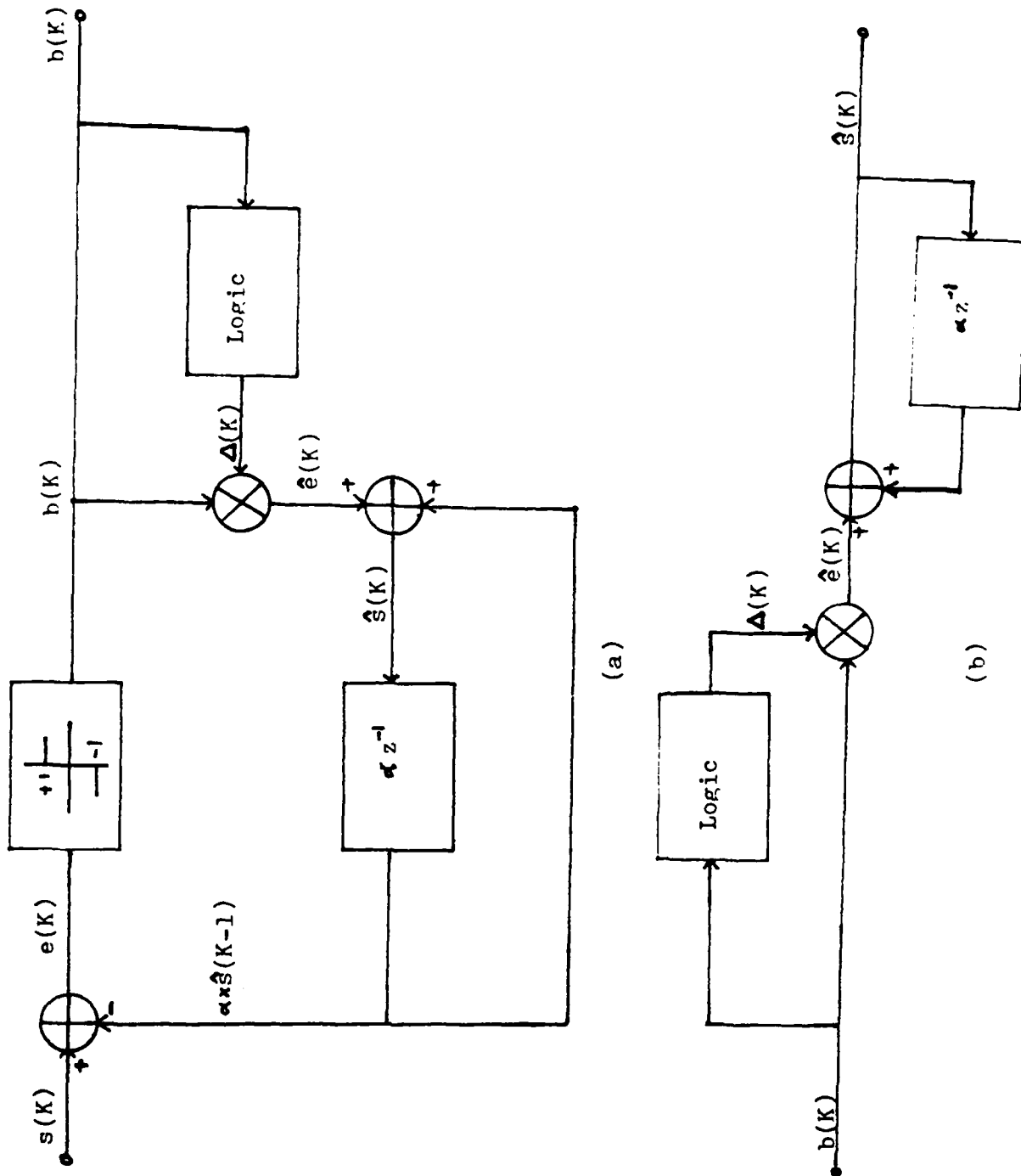


Fig. F.1 The CVSD System (a) Encoder (b) Decoder

$$g(k) = \begin{cases} \Delta_{\max} * (1 - \beta) & \text{If } b(k) = b(k-1) = b(k-2) \\ \Delta_{\min} * (1 - \beta) & \text{otherwise} \end{cases}$$

For a long run in which no three consecutive bits are identical, the stepsize approaches  $\Delta_{\min}$ . On the other hand, if the many consecutive bits are the same, the stepsize will approach  $\Delta_{\max}$ .

The estimate of the difference signal is given by

$$\hat{e}(k) = b(k) * \Delta(k)$$

Then the reconstructed speech is computed from

$$\hat{s}(k) = \alpha * \hat{s}(k-1) + \hat{e}(k)$$

Because the reconstructed speech in the transmitter is determined solely by the bit stream  $b(k)$  and an agreed initial state, the receiver can produce the same reconstructed speech samples if no channel error occur.

Normally, there is no best criteria to judge the performance of a speech algorithm. However, the basic signal to noise ratio criteria is used here.

$$SNR = 10 * \log_{10} \frac{\sum_{k=1}^M s(k)^2}{\sum_{k=1}^M (s(k) - \hat{s}(k))^2}$$

## F.2 The Real-Time CVSD System

In this section, the design of the real-time CVSD system is presented. The major design decisions and real-time algorithm are discussed. The program listings are followed.

### F.2.1 Design Overview

In order to design a real-time speech system, several points have to be considered. First, the flexibility of changing system parameters such as

speech algorithm parameters, buffer sizes and buffer starting locations must be provided. This allows system performance to be studied without any further modification of the real-time program. However, this approach will increase overhead time. Therefore, a "pre-bound" concept will be introduced. Second, the arithmetic execution time has to be minimized. This can be done by efficiently utilizing the arithmetic processors. Therefore, the "hiding" technique which hides additions inside the period of multiplication will be employed. Third, in order to decrease overhead time, all processors have to be utilized as asynchronously and as simultaneously as possible. However, the necessary synchronization between the processors has to be considered.

The real-time CVSD implementation employs five MAP processors to do speech processing asynchronously and simultaneously. The whole algorithm is divided into two steps: An initialization step and a processing step. Each processor has its own role in each step.

1. The Initialization Step

In this step, the host computer will initialize the MAP-300 system, set up the appropriate command sequence, and initiate the real-time CVSD algorithm. Each processor in the MAP-300 has to do the following functions:

- A. The CSPU acts as the resource controller. Responding to a host command, it loads a data acquisition program into the ADAM, loads digital-to analog conversion program into the AOM, configures the buffers, loads an arithmetic function into the AP which will reset the contents of the buffers, builds a recurrent sequence of commands called a function list and prebinds the APS module of the CVSD program.

- B. The AP executes the arithmetic function which is loaded by the CSPU. The purpose of this execution is to reset the buffers.

## 2. The Processing Step

After initialization, the MAP-300 can execute its functions without any further commands from host computer. The role of each processor are described as follows:

- A. The CSPU acts as the resource controller. Responding to each interrupt, it updates the contents of the corresponding processor control block. Responding to the function list, it checks the availability of the appropriate buffer and initiates AP operation by loading the CVSD program from MAP memory. The synchronization is also done by CSPU which is described in the next section.
- B. The APU executes the real-time CVSD algorithm.
- C. The APS produces data addresses and acts as the controller of the real-time CVSD system.
- D. The ADAM samples the input speech signal from telephone module and stores them into MAP memory.
- E. AOM converts input digital samples into an analog signal and output it to telephone module.

In the next two subsections, the detailed description of these two steps will be presented.

### F.2.2 The Initialization Step

The initialization step, which is controlled by host computer, includes reading system parameters, giving commands to the CSPU and building a function list. The algorithm is shown in Fig. F.2.



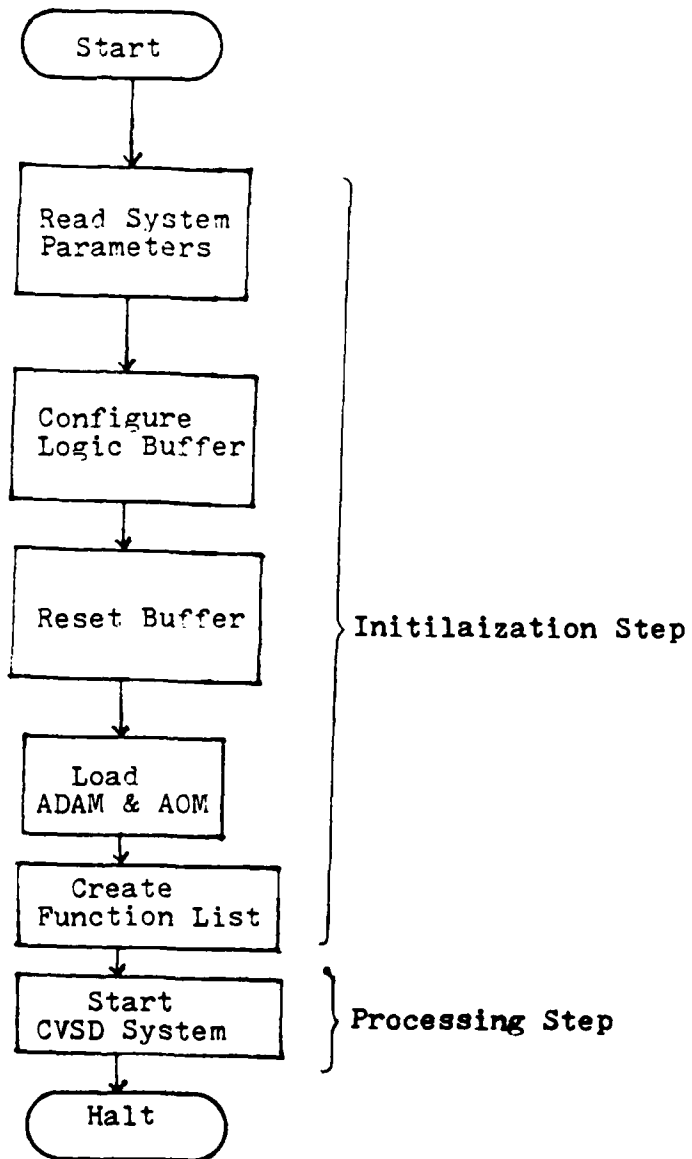


Fig. F.2 Algorithm for Initialization Step

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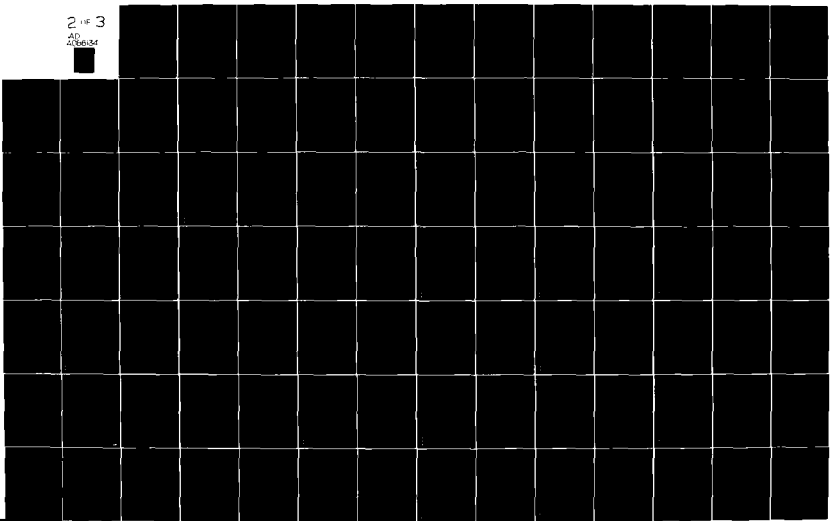
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There are two points worth to note as follows:

1. Because of parallel processing in the MAP-300, the synchronization between the AP and the AOM, and between the AP and the ADAM has to be considered. Memory is the common place which every processor has to access. Therefore, the synchronization is done by checking buffer availability as follows:
  - A. If the first ADAM buffer is busy, CSPU goes to wait. Otherwise, goes to Step B.
  - B. CSPU initiates AP. AP starts to read input samples from the first ADAM buffer, execute CVSD function and output results into the first AOM buffer.
  - C. If the second ADAM buffer is busy, CSPU goes to wait, otherwise, goes to Step D.
  - D. CSPU initiates AP. AP does the same function as Step B except it reads samples from the second ADAM buffer and outputs results to the second AOM buffer.
  - E. Go to Step A.This structure is included in a function list.
2. In order to increase the flexibility of changing system parameters, there are some substitutive attributes inside the APS module. In a normal operation, CSPU gets values for those attributes from a host command and then binds them with the APS module before loading it into the APS memory. In order to decrease this overhead time, a "pre-bound" has to be done prior to real-time execution. The prebinding process will create a new APS module from old APS module by permanently binding the attributes. At the execution time, all normal operations of binding and buffer protection will be bypassed. Thus, the overhead time is decreased.

### F.2.3 The Processing Step

In the processing step, each of three processors has a program. Among them, the data acquisition and data output programs, which are included in the Simple Notation for Array Processing library (SNAP library), are fairly simple. The actual CVSD algorithm is executed by the AP processor.

The real-time CVSD program can be divided into two parts as follows:

1. APU module of CVSD algorithm which is shown in Fig. F.3 will do the whole arithmetic operation described in the Section F.1. The input and output data are directed by APS module. The "hiding" technique is employed to reduced execution time.
2. The APS module of the CVSD algorithm which is shown in Fig. F.4 will produce address sequences of input and output data for APU module. Also, APS module acts as the controller of the real-time CVSD system. This AP control protocol is shown in Fig. F.5 and described as follows:
  - \* CPU starts APS-input by setting RI
  - \* APS sets the program counter for write routine and starts APS-output by setting RO.
  - \* APS starts APU by setting RA.
  - \* After producing addresses for input data, APS-input turns itself off by clearing RI.
  - \* When FI is cleared, APU leaves the loop.
  - \* After producing addresses for output data, APS-output turns itself off by clearing RO.
  - \* APU turns itself off by clearing RA.
  - \* CSPU is interrupted by both RAI (RA off) and DNI (AP done).

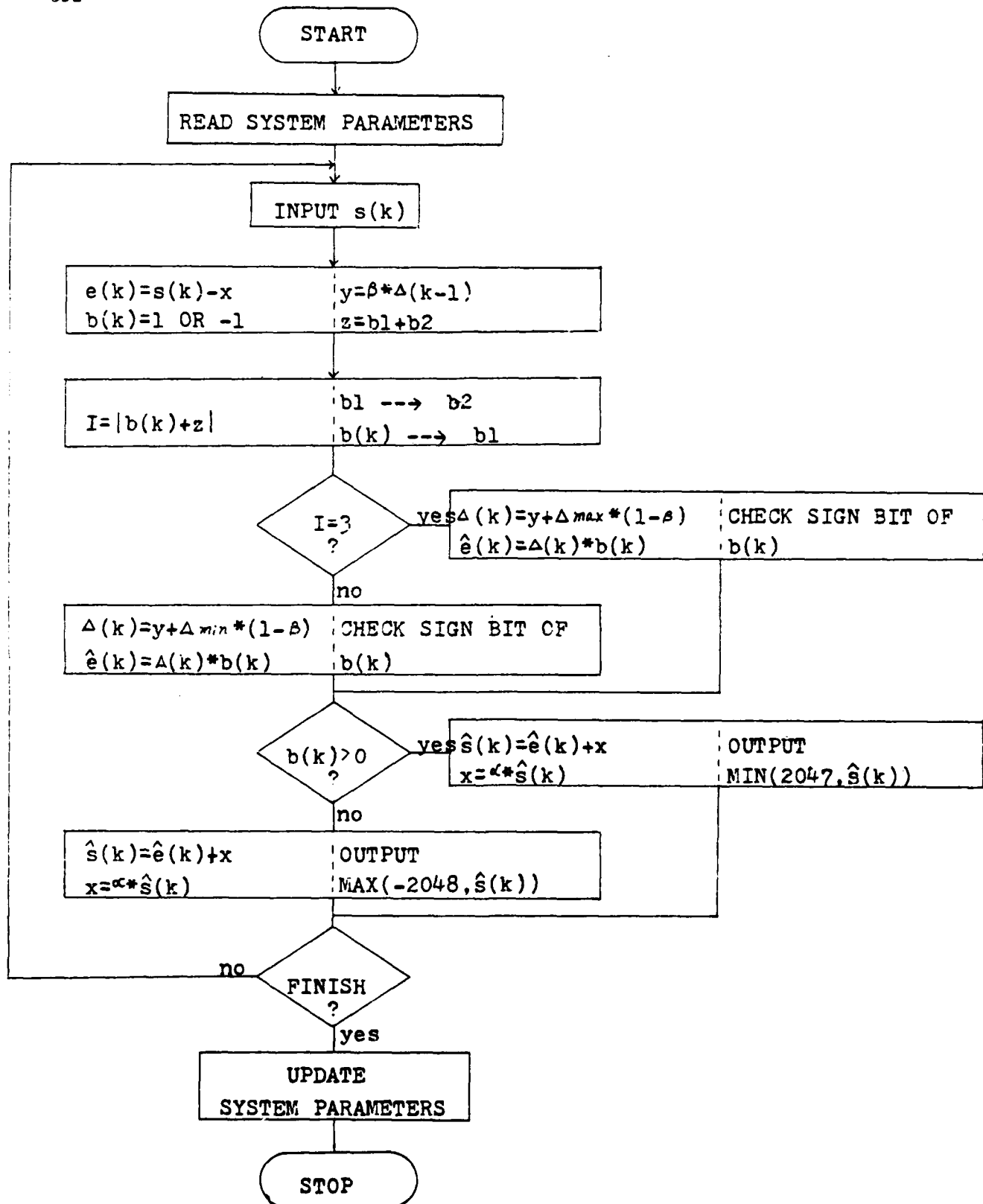
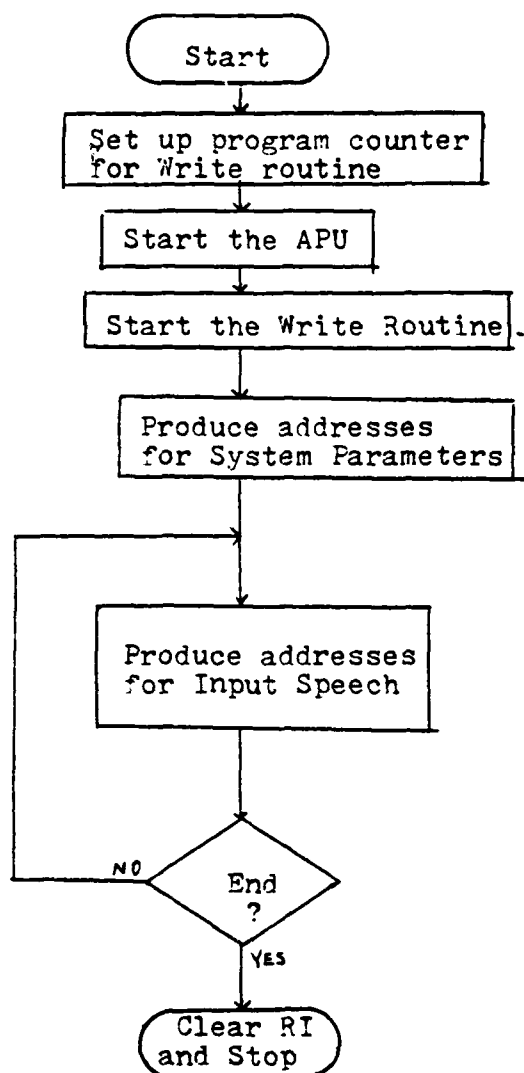
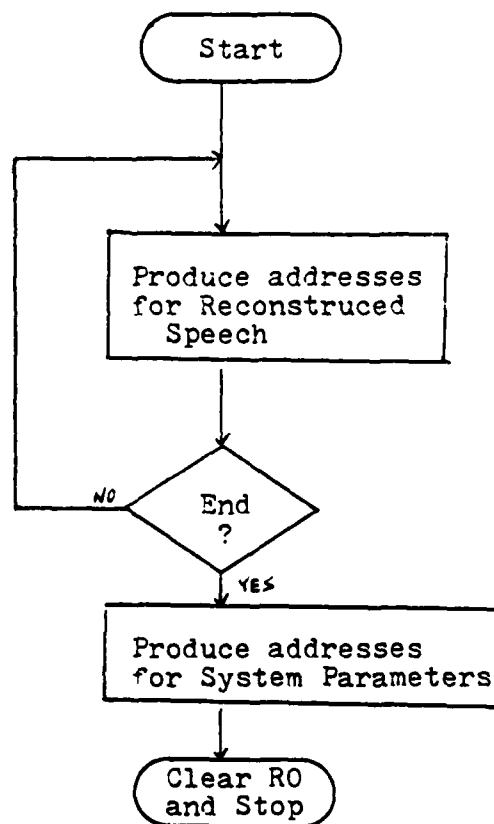


Fig. F.3 APU Flow Chart



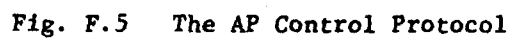
(a)



(b)

Fig. F.4 APS Flow Chart

- (a) APS-Input
- (b) APS-Output



**Fig. F.5 The AP Control Protocol**

### F.3 Conclusion

The execution time for the real-time CVSD algorithm is approximately 12 micro-seconds per sample. So, this implementation can be used with a sampling rate up to 83 KHz in the real-time mode. A set of parameters which gives a very good quality of speech is as follows:

$$\Delta_{\max} = 750$$

$$\Delta_{\min} = 25$$

$$\alpha = 0.94$$

$$\beta = 0.99$$

A two seconds sample speech is executed by this algorithm, and a 11.87 db signal-to-noise ratio performance is obtained.

### F.4 Reference

- [1] R. W. Schafer et. al., "Tandem Interconnection of LPC and CVSD Digital Speech Coders" Final Report to Defense Communications Agency, DCA Contract No. DCA 100-76-C-0073, November, 1977.



PAGE 1: MAP MODULE OF C V S D PROGRAM --- VERSION 1 --- FEB. 19, 1988

MAP MODULE OF C V S D PROGRAM --- VERSION 1 --- FEB. 19, 1988

\*\*\*\*\*

REAL-TIME CVSD TRANSMITTER

\*\*\*\*\*

DATA: 2/19/88

MAVLIN YEH

PROGRAM NAME : CVSD.ND1

PROGRAM DESCRIPTION:

THIS MAP-FUNCTION SIMULATES AN ADAPTIVE DELTA-MODULATOR WHICH USES A FIRST ORDER PREDICTOR WITH THE COEFFICIENT ALPHA AND A FIRST ORDER ADAPTOR WITH THE COEFFICIENT BETA. THE VALUES OF ALPHA AND BETA ARE TRANSFERRED FROM HOST PROGRAM TO MAP SCALAR TABLE.

PROCEDURE OF FUNCTIONS:

- 1.READ IN SPEECH --- S(K)
- 2.CALCULATE THE PREDICTING ERROR ---  $E(K)=S(K)-P(K)$
- 3.PASS  $E(K)$  THROUGH DELTA MODULATOR AND PRODUCE  $L(K)$
- 4.GET THE LOGIC OUTPUT  $G(K)$
- 5.CALCULATE ADAPTIVE STEP SIZE ---  $D(K)=BETA*D(K-1)+G(K)$
- 6.CALCULATE RECONSTRUCTED PREDICTING ERROR ---  $EHAT(K)=L(K)*D(K)$
- 7.CALCULATE RECONSTRUCTED SPEECH ---  $SHAT(K)=SHAT(K-1)+EHAT(K)$
- 8.UPDATE PREDICTOR'S PARAMETER =  $ALPHA=SHAT(K)$

THIS PROGRAM PROVIDES UPPER LIMIT AND LOWER LIMIT OF OUTPUT DATA. THESE TWO LIMITS ARE TRANSFERRED FROM HOST PROGRAM. THIS PROGRAM CONTAINS TWO SUB-PROGRAMS WHICH ARE CVSD FOR APU AND V2260D FOR APS. PASSING THROUGH MAP-SIMULATOR, CVSD TAKES 2.669 MICROSECONDS. (LOOP TIME)

CALL TO THIS PROGRAM:

CALL CVSD(Y,A,U)

OR

MAP=CVSD(Y,A,U)

WHERE V=OUTPUT BUFFER FROM MAP





```

19. 1000
MAP MODULE OF C.V.S. D PROGRAM
VERSION 1
A19 04834 4388268 (00133)
A1A 04836 0008000 (00134) *
A1B 04838 0420000 (00135)
A1C 0483A 0098000 (00136) LOOP2
A1D 0483C 0000000 (00137)
A1E 0483E 0001000 (00138)
A1F 04840 0005000 (00139)
A20 04842 41A5000 (00140)
A21 04844 0098000 (00141) *
A22 04846 000E000 (00142)
A23 04848 0000000 (00143)
A24 0484A 0000000 (00144)
A25 0484C 0001000 (00145)
A26 0484E 0000000 (00146)
A27 04850 0000000 (00147)
A28 04852 0005000 (00148)
A29 04854 41A5000 (00149)
A2A 04856 0098000 (00150)
A2B 04858 000E000 (00151)
A2C 0485A 0000000 (00152)
A2D 0485C 0000000 (00153)
A2E 0485E 0001000 (00154)
A2F 04860 0000000 (00155)
A30 04862 0005000 (00156)
A31 04864 0098000 (00157)
A32 04866 0000000 (00158)
A33 04868 0000000 (00159)
A34 0486A 0000000 (00160)
A35 0486C 0001000 (00161)
A36 0486E 0000000 (00162)
A37 04870 0000000 (00163)
A38 04872 4600000 (00164)
A39 04874 0000000 (00165)
A3A 04876 0000000 (00166)
A3B 04878 0000000 (00167)
A3C 0487A 0000000 (00168)
A3D 0487C 0000000 (00169)
A3E 0487E 0000000 (00170)
A3F 04880 0000000 (00171)
A40 04882 0000000 (00172)
A41 04884 0000000 (00173)
A42 04886 0000000 (00174)
A43 04888 0000000 (00175)
A44 0488A 0000000 (00176)
A45 0488C 0000000 (00177)
A46 0488E 0000000 (00178)
A47 04890 0000000 (00179)
A48 04892 0000000 (00180)
A49 04894 0000000 (00181)
A4A 04896 0000000 (00182)
A4B 04898 0000000 (00183)
A4C 0489A 0000000 (00184)
A4D 0489C 0000000 (00185)
A4E 0489E 0000000 (00186)
A4F 048A0 0000000 (00187)
A50 048A2 0000000 (00188)
A51 048A4 0000000 (00189)
A52 048A6 0000000 (00190)
A53 048A8 0000000 (00191)
A54 048AA 0000000 (00192)
A55 048AC 0000000 (00193)
A56 048AE 0000000 (00194)
A57 048B0 0000000 (00195)
A58 048B2 0000000 (00196)
A59 048B4 0000000 (00197)
A5A 048B6 0000000 (00198)
A5B 048B8 0000000 (00199)
A5C 048BA 0000000 (00200)
A5D 048BC 0000000 (00201)
A5E 048BE 0000000 (00202)
A5F 048C0 0000000 (00203)
A60 048C2 0000000 (00204)
A61 048C4 0000000 (00205)
A62 048C6 0000000 (00206)
A63 048C8 0000000 (00207)
A64 048CA 0000000 (00208)
A65 048CC 0000000 (00209)
A66 048CE 0000000 (00210)
A67 048D0 0000000 (00211)
A68 048D2 0000000 (00212)
A69 048D4 0000000 (00213)
A6A 048D6 0000000 (00214)
A6B 048D8 0000000 (00215)
A6C 048DA 0000000 (00216)
A6D 048DC 0000000 (00217)
A6E 048DE 0000000 (00218)
A6F 048E0 0000000 (00219)
A70 048E2 0000000 (00220)
A71 048E4 0000000 (00221)
A72 048E6 0000000 (00222)
A73 048E8 0000000 (00223)
A74 048EA 0000000 (00224)
A75 048EC 0000000 (00225)
A76 048EE 0000000 (00226)
A77 048F0 0000000 (00227)
A78 048F2 0000000 (00228)
A79 048F4 0000000 (00229)
A7A 048F6 0000000 (00230)
A7B 048F8 0000000 (00231)
A7C 048FA 0000000 (00232)
A7D 048FC 0000000 (00233)
A7E 048FE 0000000 (00234)
A7F 04900 0000000 (00235)
A80 04902 0000000 (00236)
A81 04904 0000000 (00237)
A82 04906 0000000 (00238)
A83 04908 0000000 (00239)
A84 0490A 0000000 (00240)
A85 0490C 0000000 (00241)
A86 0490E 0000000 (00242)
A87 04910 0000000 (00243)
A88 04912 0000000 (00244)
A89 04914 0000000 (00245)
A8A 04916 0000000 (00246)
A8B 04918 0000000 (00247)
A8C 0491A 0000000 (00248)
A8D 0491C 0000000 (00249)
A8E 0491E 0000000 (00250)
A8F 04920 0000000 (00251)
A90 04922 0000000 (00252)
A91 04924 0000000 (00253)
A92 04926 0000000 (00254)
A93 04928 0000000 (00255)
A94 0492A 0000000 (00256)
A95 0492C 0000000 (00257)
A96 0492E 0000000 (00258)
A97 04930 0000000 (00259)
A98 04932 0000000 (00260)
A99 04934 0000000 (00261)
A9A 04936 0000000 (00262)
A9B 04938 0000000 (00263)
A9C 0493A 0000000 (00264)
A9D 0493C 0000000 (00265)
A9E 0493E 0000000 (00266)
A9F 04940 0000000 (00267)
A00 04942 0000000 (00268)
A01 04944 0000000 (00269)
A02 04946 0000000 (00270)
A03 04948 0000000 (00271)
A04 0494A 0000000 (00272)
A05 0494C 0000000 (00273)
A06 0494E 0000000 (00274)
A07 04950 0000000 (00275)
A08 04952 0000000 (00276)
A09 04954 0000000 (00277)
A0A 04956 0000000 (00278)
A0B 04958 0000000 (00279)
A0C 0495A 0000000 (00280)
A0D 0495C 0000000 (00281)
A0E 0495E 0000000 (00282)
A0F 04960 0000000 (00283)
A10 04962 0000000 (00284)
A11 04964 0000000 (00285)
A12 04966 0000000 (00286)
A13 04968 0000000 (00287)
A14 0496A 0000000 (00288)
A15 0496C 0000000 (00289)
A16 0496E 0000000 (00290)
A17 04970 0000000 (00291)
A18 04972 0000000 (00292)
A19 04974 0000000 (00293)
A1A 04976 0000000 (00294)
A1B 04978 0000000 (00295)
A1C 0497A
```

PAGE 5: MAP MODULE OF C V S D PROGRAM --- VERSION 1 --- FEB. 19, 1988

84878 88888838 (88177)  
(88178)  
(88179)

CVSDSSZ=8A-CVSDSSA  
END  
EJECT

; COMPUTE THE SIZE OF THE MODULE

**AP53-V2260D**

**THIS IS APS PROGRAM FOR CVSD.**

IT EMPLOYES TWO INPUT-BUFFERS AND TWO OUTPUT-BUFFERS. ALSO ONE CAN REPEAT THIS PROGRAM WITHOUT LOADING IT AGAIN.

```

EVEN          ; START ON WORD BOUNDARY
ADDR          ; PTR TO CONSTR INSTR BLOCK
V226$D$I     ; STARTING ADDR. OF SCALAR
V226$D$S+2*V226$D$S
1            ; ONE SCALAR
DATA         ; SIZE
V226$D$Z     ; SIZE
V226$D$A     ; CHAIN ANCHOR
ADDR
EVEN

```

```

BEGIN      APS(V22680)
; BEGIN OF THIS MODULE

```

```

; SET APS-OUTPUT PC P2
; RUN APS-OUTPUT
JJSN(V2260D$5-1,P2)
SET(RO)

```

## SCALAR ADDRESSES

```
LOAD(BR0,MSS(1),L,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
UPPER LIMIT
LOWER LIMIT
LOWER LOGIC OUTPUT
HIGHER LOGIC OUTPUT
BETA
THRESHOLD
ALPHA
DELTA
L(K-1)
L(K-2)
ALPHA=SHAT(K-1)
```

[illegible]

PAGE 8: MAP MODULE OF C.V.S. D. PROGRAM VERSION 1.19.1989

```

AFDTS: 000E8 (00064) (00069)
BUSIS: 00091 (00061) (00259)
CSPUSMOS: 021FC (00063) (00073)
CVSDS: 04002 (00071) (00094)
CVSDSSA: 00000 (00091) (00102) (00177)
CVSDSSZ: 00030 (00092) (00177)
DMYS: 00794 (00060)
FCB: 000F5 (00060) (00069)
LOOP: 0000C (00117) (00150) (00162)
LOOP1: 00030 (00131) (00173)
LOOP2: 00010 (00136) (00175)
LOOP3: 00030 (00151) (00164)
LOOP4: 00020 (00139) (00155)
MSS: 00000 (00059) (00205) (00220) (00221) (00232) (00233)
TOESPRT: 00200 (00257) (00259)
V22600S: 04000 (00062) (00250)
V22600S1: 00000 (00072) (00190) (00197) (00253)
V22600S3: 00010 (00222) (00223)
V22600S5: 00016 (00200) (00231)
V22600S6: 00019 (00234) (00235)
V22600SA: 04002 (00193) (00244)
V22600S1: 040C2 (00189) (00251)
V22600S5: 00002 (00190) (00205)
V22600S2: 0004A (00192) (00253)

```

LINES WITH ERRORS: 0 (MAP VERSION 000101.10) E- 0



/TR:BLOCKS/VR

```

*****
*                                     *
*          CVSD HOST SUPPORT PROGRAM          *
*                                     *
*****

```

DATE: 11/14/79  
MAVLIN YEH

## CVSD HOST SUPPORT PROGRAM

CALL CVSD(Y,A,U)

**OR**

MAP=CVSD(Y,A,U)

**WHERE: Y=OUTPUT BUFFER**

### A-STARTING LOCATION OF SCALARS

## U-INPUT BUFFER

# INTEGER FUNCTION CVSD(Y,A,U)

**INTEGERS Y, A, U, FCBGN**

CVSD=FCBGN(245,Y,A,U,B,B,B,B,5)

## RETURN

**END**

**0001**

FORTRAN IV-PLUS V02-11  
CVSDHS TR-CKS/

PAGE 2

28:01:27 28-MAR-88

# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	25	RV,I,CON,LCL
2	SPDATA	6	RV,D,CON,LCL
3	SIDATA	12	RV,D,CON,LCL

## ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
------	------	---------	------	------	---------	------	------	---------

CVSD	I=2	1-888888						
------	-----	----------	--	--	--	--	--	--

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
A	I=2	F-888884	U	I=2	F-888886	Y	I=2	F-888882

## FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 888126 43

NO FPP INSTRUCTIONS GENERATED

CVSDHS,CVSDHS/-SP-CVSDHS

**F4P REALCVSD-REALCVSD**



```

FORTRAN IV-PLUS V02-B1          19:59:12    28-MAR-88          PAGE 3
CVSDBN.FTN    /TR:BLOCKS/VR

0031    SCAL(8)=SCAL(8)/16.**3
0032    TYPE = '...' TYPE IN SAMPLING FREQ.'
0033    READ(4,*)FREQ
0034    WRITE(6,*)' SAMPLING FREQUENCY =',FREQ
0035    CLOSE(UNIT=4)
C-----
0036    DEFINE BUS IDENTIFIERS
0037    IBUS1=64
0038    IBUS2=128
0039    IBUS3=192
C
C    MAP CONFIGURATION BEGINS HERE
C
0040    M=MPOPM(1)
0041    DO 100 I=1,2
0042        SSIZE=(I-1)*SIZE
0043        M=MPCLB(IBUS3+BSIN(I),B,B+SSIZE,SIZE,REAL,CONTIG,SHORT)
0044        M=MPCLB(IBUS2+BSHTR(I),B,B+SSIZE,SIZE,REAL,CONTIG,SHORT)
0045        INITIALIZE THESE BUFFERS
0046        M=VSHA1(BSIN(1),B,BSIN(1),B)
0047        M=VSHA1(BSHTR(1),B,BSHTR(1),B)
C
0048    CONTINUE
0049    M=MPCLB(IBUS1+IDAOM,38888,B,512,B,FIXED,CONTIG,LONG)
0050    M=MPCLB(IBUS1+IDADM,31888,B,512,B,FIXED,CONTIG,LONG)
0051    M=MPCLB(IBUS1+11,10246,100,2,1,B)
0052    CREATE PREBOUND FUNCTION
0053    M=MPCBF(11,25B)
0054    M=CVSD(BSHTR(1),5B,BSIN(1))
0055    M=CVSD(BSHTR(2),5B,BSIN(2))
0056    M=MPTEF(B)
C
C    LOAD THE ADAM AND AOM
0057    M=ADMD(IDAOM,FREQ,B,BSHTR(2),BSHTR(1),2)
0058    M=ADMD(IDADM,FREQ,1,B,B,CHAN1,BSIN(2),BSIN(1))
0059    M=PLDS(AOM,1052,IDAOM)
0060    M=PLDS(ADM,1052,IDADM)
0061    M=MPVST(5B,SCAL(1),15,1)
C
C-----
C
C    FUNCTION LIST
0062    M=MPBFL(FL1)
0063    M=MPVT(2,BSIN(1))
0064    M=MPXBF(25B)
0065    M=MPVT(2,BSIN(2))
0066    M=MPXBF(251)
0067    M=MPBFL(FL1)
0068    M=MPRAA(ADM,B,B,AOM,B,B)
0069    M=MPVHL(B,B,FL1)
C
C-----
C
C    GO INTO WAIT STATE
0070    TYPE = '...' REAL TIME CVSD IS RUNNING ...
0071    TYPE = '...' TYPE IN B-STOP OR 1-CHANGE PARAMETERS'
0072    READ(5,*)LDAT
0073    IF(LDAT.NE.B.AND.LDAT.NE.1)GO TO 500
0074    M=MPSAA(AOM)
0075    M=MPSAA(ADM)
0076    M=MPCLS(B)
0077    IF(LDAT.EQ.1)GO TO 999
0078    STOP
0079    END

```

# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	882522	681 RV,I,CON,LCL
2	SPDATA	888762	249 RV,D,CON,LCL
3	S1DATA	888328	184 RV,D,CON,LCL
4	SVARS	888248	88 RV,D,CON,LCL
5	STEPS	888882	1 RV,D,CON,LCL

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
ADM	I*2	4-888116	ALT	I*2	4-888174	ADM	I*2	4-888112
DELTH	R*4	4-888284	FIXED	I*2	4-888164	FL1	I*2	4-888184
IBUS1	I*2	4-888228	IBUS2	I*2	4-888228	IBUS3	I*2	4-888224
IOS2	I*2	4-888186	ISIZE	I*2	4-888282	LDAT	I*2	4-888236
REAL	I*2	4-888168	SHORT	I*2	4-888178	SIZE	R*4	4-888176
						CMPLX	I*2	4-888162
						FREQ	R*4	4-888214
						IDADM	I*2	4-888114
						LONG	I*2	4-888166
						SSIZE	R*4	4-888232
						THRE	R*4	4-888218
						CONTIG	I*2	4-888172
						I	I*2	4-888238
						IDAOM	I*2	4-888118
						M	I*2	4-888226

## ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
BSNTR	I*2	4-888188	888884	2 (2)
BSIN	I*2	4-888874	888884	2 (2)
CHAN1	I*2	4-888128	888848	16 (16)
SCAL	R*4	4-888888	888874	38 (15)

## LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
188	88	988	1-882348	999	1-888876

## FUNCTIONS AND SUBROUTINES REFERENCED

ADM8D	ADMID	CLOS	CVSD	MPBFL	MPCBF	MPCLB	MPCLS	MPEFL	MPLDS	MPOPN	MPRAA	MPSAA	MPTBF	MPVHL	MPVST
MPUT	MPXBF	VSNAL													

TOTAL SPACE ALLOCATED = 884266 1115

CVSDBN.CVSDBN/-SP-CVSDBN

## APPENDIX G

### PROGRAM LISTINGS FOR REAL TIME IMPLEMENTATION OF PARC ON MAP-300

This appendix contains the program listings of all the modules in the real time implementation of the PARC algorithm on the MAP-300 array processor. There are twenty modules in all, some in the PDP-11, and others in the various processors of the MAP 300. Ten modules execute in the MAP-300. Nine of these have host support programs in the PDP-11. And finally, there is the main program in the PDP-11 which sets up and initializes the real time PARC operation on the MAP-300.

The following is a list of these programs and the processors they execute on.

1.	PARC Mainline	PDP-11
2-10.	Host Support Subroutines	PDP-11
11.	Receiver Update Module	CSPU/MAP-300
12.	Transmitter Update Module	CSPU/MAP-300
13.	Initialization Module	CSPU/MAP-300
14.	Pitch Computation Module	AP/MAP-300
15.	PARC Transmitter Module	AP/MAP-300
16.	PARC Receiver Module	AP/MAP-300
17.	Encoder Module	CSPU/MAP-300
18.	IOS Simulator	CSPU/MAP-300
19.	Decoder Module	CSPU/MAP-300
20.	Digital I/O Module	IOS/MAP-300

### Operator Sequence to Run PARC at DCA

The two MAP's at DCA have different logical device names, MP and MA. There is a different task images corresponding to each MAP, called PARP.TSK and PARA.TSK. The task names for these programs are NDP and NDA.

To run the real time PARC algorithm, the following steps must be followed for each MAP. For the steps shown below, the devices are called MX. The underlined text is the computer response at the terminal. The rest of the text is the operator input.

```

> LOA MX:      (Load the map device)
> INS MXLD/TASK = ... XLO      (Install map loader program)
> XLO          (Load the map executive including PARC routines.
                The executive is called NDQL)
> INS PARX     (Install the initialization routines for PARC)
> NDX          (Run the initialization program)

```

MODE ?(1 - Internal Loopback, 2-Full Duplex)

```

2              (Mode Selection)

```

These steps for setting up and executing the PARC algorithm are combined into an indirect command file called PARC.CMD. If the indirect command file is used, the operator only needs to run the program (NDX) and select the mode.



PARC96.FTN

/TR:BLOCKS/VR

```

*****
"      PITCH EXTRACTION ADAPTIVE RESIDUAL CODER
"      P A R C
*****

```

MAR 25, 1985

```

REAL TIME IMPLEMENTATION INCLUDING ENCODER, DECODER,
IOS LOOP-BACK.

```

```

5551 REAL SCAL3(26), SCAL1(15), SCAL2(29), A1(85), A2(85)
5552 REAL OUTSCA(25), EXPN(25), T(25), B(25), HOBETA
5553 INTEGER ADM1, ADM2, SAMP, TXVHAT, T1SHAT, T2SHAT, TXPARA
5554 INTEGER INIS(14), KBLK, AOM1, AOM2, AOM3, AOM4
5555 INTEGER RCVHAT, R1SHAT, R2SHAT, RCPARA, BOUT1, BOUT2, TBLK, FBLK
5556 INTEGER RCVNT2
5557 INTEGER IOSPCH(255), SIZE
5558 INTEGER ENCT(35), ENCB(97), DECT(256), DECB(128)
5559 INTEGER PHSTA(8), DECTAB(2, 14), ISEL(3), OFFSET
5560 INTEGER ENTRB, ENTRT, DCRCCT, DCRCB
5561 INTEGER QTR1, QTR2, BTR1, BTR2, ORC1, ORC2, BRC
5562 INTEGER ITBTR1, ITBTR2, ITBRC1, ITBRC2
5563 INTEGER ADM, AOM, IOS, IOS2
5564 INTEGER IDADM, IDAOM, IDIOS
5565 INTEGER IFSEL, CHAN1(16)
5566 INTEGER REAL, CMPLX, FIXED, LONG, SHORT, CONTIG, ALT
5567 DATA IBUS1, IBUS2, IBUS3/64, 128, 192/
5568 DATA ADM1, ADM2, BOUT1, BOUT2/1, 2, 3, 4/
5569 DATA SAMP, TXVHAT, T1SHAT, T2SHAT, TXPARA/5, 6, 7, 8, 9/
5570 DATA RCVHAT, R1SHAT, RCVHAT2, RCPARA/15, 11, 12, 13/
5571 DATA ENTRB, ENTRT, DCRCCT, DCRCB/14, 15, 16, 17/
5572 DATA QTR1, QTR2, ORC1, ORC2, BTR1, BTR2, BRC/18, 19, 20, 21, 22, 23, 24/
5573 DATA IDADM, IDAOM, IDIOS/27, 28, 29/
5574 DATA CHAN1/1, -1, 14-B/
5575 DATA LONG, SHORT, REAL, CMPLX, FIXED, CONTIG, ALT/B, 1, 2, 1, 2, 1, 2/
5576 DATA AOM1, AOM2, AOM3, AOM4/31, 32, 33, 34/
5577 DATA ADM, AOM, IOS, IOS2/23, 22, 16, 2/
5578 DATA ITBTR1, ITBTR2, ITBRC1, ITBRC2, IFSEL/88, 91, 94, 96, 85/
5579 DATA IFPQL, IFPRC, IFPIOS, IFMODE, IFSYNC, IFRCVR/1, 2, 3, 4, 5, 6/
5580 DATA IFSYN1, IFSYN2, IFREC1, IFREC2/7, 8, 9, 15/

```

```

5581 DATA ENCT/3, 7, 5, 2, 5, 3, 11, 5, 47,
1 6, 95, 7, 191, 2, 1, 3, 3, 5, 15,
2 6, 31, 7, 63, 7, 127, 7, 255, 7, 255/
5582 DATA DECTAB/14, -25, 5, 1, 5, 2, 13, 3, 61, 4,
1 125, 5, 253, 6, 4, 7, 12, 8, 65, 9,
2 124, 15, 252, 11, 254, -12, 255, -12/
5583 DATA ENCB/7, 11, 13, 14, 15, 19, 21, 22, 23, 25, 26, 27, 28, 29, 35, 31,
1 35, 37, 38, 39, 41, 42, 43, 44, 45, 46, 47, 49, 55, 51, 52, 53,
2 54, 55, 56, 57, 58, 59, 65, 61, 62, 63, 67, 69, 75, 71, 73, 74,
3 75, 76, 77, 78, 79, 81, 82, 83, 84, 85, 86, 87, 88, 89, 95, 91,
4 92, 93, 94, 95, 97, 98, 99, 155, 151, 152, 153, 154, 155, 156,

```

```

FORTAN IV-PLUS V82-51      12:09:54      82-MAY-88      PAGE 2
PARC96.FTN

      C
8834      DATA PHBTA/B,1,2,4,8,16,32,64/

      C
8835      INFORMATION AND PARAMETERS

      C
8836      OPEN(UNIT=4,NAME='PARA.DAT',SHARED,TYPE='OLD',READONLY)
      TYPE *, TYPE IN FILTER PARAMETERS : A, B?
8837      READ(4,*)SCAL1(2),SCAL1(3)
      TYPE *, TRANSFER BLOCK SIZE (MULTIPLES OF 2) ?
8838      READ(4,*)TBLK
      TYPE *, FILTERING BLOCK SIZE?
8839      READ(4,*)FBLK
      TYPE *, CORRELATION BLOCK SIZE (MULTIPLES OF 4) ?
8840      READ(4,*)KBLK
      INIS(3)=FBLK-1
8841      INIS(5)=KBLK-1
8842      INIS(7)=TBLK
8843      INIS(14)=TBLK
8844      FFBLK=FBLK
8845      KBLK=KBLK
8846      TBULK=TBULK
8847      SCAL1(1)=TBULK/2.-B.5
8848      SCAL1(4)=FFBLK-B.5
8849      SCAL1(5)=KBLK/4.-B.5
8850      SCAL3(5)=TBULK-B.5
      C
8851      TYPE *, RUN LENGTH, BIT # FOR LEVEL 1 AND BIT # FOR RUN LENGTH CODE ?
8852      READ(4,*)SCAL2(5),BIT1,BITLNT
8853      NRUNE=SCAL2(5)-1
8854      SCAL2(15)=SCAL2(5)
      C
8855      TYPE *, PITCH PERIOD SEARCH RANGE: FROM ? TO ?
8856      READ(4,*)ITSTRT,ITEND
8857      TSTRT=ITSTRT
8858      TEND=ITEND
8859      INIS(4)=ITSTRT-1
8860      INIS(10)=ITSTRT
8861      SCAL1(6)=TEND-TSTRT+B.5
8862      SCAL1(8)=TEND-B.5
8863      SCAL1(10)=TSTRT
      C
8864      TYPE *, BIT BLOCK SIZE, # BITS NULL CODE, GAP SIZE, # BITS PHONEY BETA ?
8865      READ(4,*)SCAL2(2),SCAL2(21),IGAP,SCAL2(6)
8866      INIS(6)=IGAP
8867      INIS(9)=IGAP
8868      INIS(13)=IGAP
8869      GAP=IGAP
8870      SCAL2(7)=GAP-B.5
8871      SCAL3(19)=SCAL2(7)
      C
8872      TYPE *, GAP THRESHOLD & FILTER THRESHOLD ?
      READ(4,*)INIS(1),INIS(2)

```

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```

C
D
TYPE ' ' VALUES FOR RMSHIN,ALAD,ALP,SMIN,G,AINV,INIT STATE?
READ(4,*)RMSHIN,ALAD,ALP,SMIN,G,AINV,STATE
N=4
SCAL2(18)=AINV*(1/ALAD-1)
SCAL2(19)=ALAD
SCAL2(20)=N-2.5
SCAL2(3)=RMSHIN/16.**3
SCAL2(4)=STATE
SCAL2(8)=RMSHIN/16.**3
SCAL2(9)=N-2.5
SCAL2(10)=1-ALP
SCAL2(11)=ALP
SCAL2(12)=SMIN
SCAL2(13)=G
SCAL3(6)=RMSHIN/16.**3
SCAL3(7)=STATE
SCAL3(9)=RMSHIN/16.**3
SCAL3(11)=ALAD
SCAL3(18)=N-2.5
SCAL3(15)=1-ALP
SCAL3(16)=ALP
SCAL3(12)=SMIN
SCAL3(14)=G
SCAL3(17)=AINV*(1/ALAD-1)

C
D
TYPE ' ' OF QUANTIZER LEVELS?
READ(4,*)IK
IL=IK/2
SCAL2(14)=IL
ILL=IL+1
TYPE ' ' OUTPUT SCALING FACTORS FROM 1 TO',ILL
TYPE ' ' EXPANSION/CONTRACTION FACTORS FROM 1 TO',ILL
READ(4,*)(EXPN(J),J=1,ILL)
TYPE ' ' # BITS CORRESPONDING TO EACH LEVEL FROM 1 TO',IK
READ(4,*)(B(I),I=1,IK)
K1=9
K11=9
A1(K1)=(OUTSCA(1)+OUTSCA(2))/2
T(1)=A1(K1)
A1(K1+1)=OUTSCA(1)
A1(K1+2)=EXPN(1)
A1(K1+3)=B(1)
A1(K1+4)=B(1)
A2(K11)=EXPN(1)
A2(K11+1)=OUTSCA(1)
DO 48 I=2,ILL
T(I)=(OUTSCA(1)+OUTSCA(I+1))/2
K11=K11+2
A2(K11)=EXPN(I)
A2(K11+1)=OUTSCA(I)
K1=K1+5
A1(K1)=T(I)
A1(K1+1)=OUTSCA(I)
A1( 2)=( 1)

```

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```

0120      A1(K1+3)=B(1)
0121      A1(K1+4)=B(1+IL)
0122      K1=K1+5
0123      A1(K1)=OUTSCA(ILL)
0124      A1(K1+1)=EXPN(ILL)
0125      A1(K1+2)=B(ILL)
0126      A1(K1+3)=B(ILL+IL)
0127      K1=K1+2
0128      A2(K1)=EXPN(ILL)
0129      A2(K1+1)=OUTSCA(ILL)
0130      DO 44 I=1,IL
0131      K1=K1+2
0132      A2(K1)=A2(9+2*I)
0133      A2(K1+1)=-A2(9+2*I+1)
0134      CONTINUE
44
C
C      TYPE ' ' UPPER LIMIT OF BETA?
C      READ(4,'')UBETA
C      SCAL1(11)=-UBETA
C      SCAL1(12)=-UBETA
C      SCAL3(13)=SCAL1(12)
C
C      TYPE ' ' OF QUANTIZATION LEVELS FOR BETA?
C      READ(4,'')QBETA
C      IQBETA=QBETA
C      HQBETA=IQBETA/2
C      SCAL1(13)=HQBETA/(UBETA*(2.**15))
C      SCAL1(14)=HQBETA/(UBETA*(2.**24))
C      SCAL1(15)=1./SCAL1(14)
C      SCAL3(8)=1./SCAL1(13)
C
C      TYPE ' ' SAMPLING FREQUENCY FOR ADAM ?
C      READ(4,'')FREADM
C
C      TYPE ' ' INVERSE GAIN FACTOR FOR MASKING LSBS ?
C      READ(4,'') SCAL3(24)
C      SCAL3(24)=1./SCAL3(24)**13)
C      TYPE ' ' MAX. Q-BUFFER LENGTH ( < 500 ) ?
C      READ(4,'') SCAL3(25)
C      TYPE ' ' GAIN FACTOR AT ADAM INPUT ?
C      READ(4,'') SCAL3(26)
C      SCAL3(26)=SCAL3(26)/SCAL3(24)
C
C      SCAL1(7)=1./12.**15)
C      SCAL1(9)=B.BB1
C      SCAL2(1)=B
C      SCAL2(17)=1./12.**14)
C      SCAL2(22)=SCAL1(7)
C      SCAL2(23)=B
C      SCAL2(26)=B
C      SCAL2(29)=B
C      SCAL3(18)=2.**14
C      SCAL3(20)=SCAL1(7)
C      SCAL3(21)=B
C      SCAL3(22)=2047./16.**3)
C      SCAL3(23)=-2048./16.**3)
C
C      18BIT COUNTER
C      11/2**14
C
C      10N FOR TRANSMITTER
C      18BITA
C      18BITB
C      11/2**14
C      11/2**15
C      10N FOR RECEIVER

```

```

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      INIS(8)=1823
      INIS(11)=INIS(8)
      INIS(12)=2848
      A1(1)=AINV
      A2(1)=AINV
      CLOSE(UNIT=4)

      CREATE INFORMATION FILE

      WRITE(6,*) '***** REAL-TIME PARC ALGORITHM *****'
      WRITE(6,*) 'PARAMETERS FOR THE ADAPTIVE FILTER:'
      WRITE(6,*) 'A=' SCAL1(2), 'B=' SCAL1(3)
      WRITE(6,*) 'TRANSFER BLOCK SIZE =' TBLK
      WRITE(6,*) 'FILTERING BLOCK SIZE =' FBLK
      WRITE(6,*) 'CORRELATION BLOCK SIZE =' KBLK
      WRITE(6,*) 'RUN LENGTH =' SCAL2(5), 'BIT # FOR ITS CODE =' BITLMT
      WRITE(6,*) 'BIT # FOR LEVEL 1 =' BIT1
      WRITE(6,*) 'PITCH PERIOD SEARCHING RANGE =' ITSTRT, 'TO', ITEND
      WRITE(6,*) 'BIT BLOCK SIZE =' SCAL2(2), 'NULL BIT # =' SCAL2(21)
      WRITE(6,*) 'GAP SIZE =' IGAP, 'PHONY BETA BITS =' SCAL2(6)
      WRITE(6,*) 'RMSMIN =' RMSMIN, 'ALAD =' ALAD, 'ALP =' ALP
      WRITE(6,*) 'SMIN =' SMIN, 'G =' G, 'AINV =' AINV, 'STATE =' STATE
      WRITE(6,*) 'NUMBER OF QUANTIZER LEVELS =' IK
      WRITE(6,*) 'OUTPUT SCALING FACTOR:'
      WRITE(6,*) 'OUTSCA(1), I=1, ILL)
      WRITE(6,*) 'EXPANSION/CONTRACTION FACTORS:'
      WRITE(6,*) 'EXPN(1), I=1, ILL)
      WRITE(6,*) 'QUANTIZER THRESHOLDS:'
      WRITE(6,*) 'T(1), I=1, ILL)
      WRITE(6,*) 'OF BITS CORRESPONDING TO EACH LEVEL:'
      WRITE(6,*) 'UB(1), I=1, IK)
      WRITE(6,*) 'UPPER BETA LIMIT =' UBETA, 'LOWER BETA LIMIT =' SCAL1(11)
      WRITE(6,*) 'OF QUANTIZING LEVELS FOR BETA =' IOBETA
      WRITE(6,*) 'GAP THRESHOLD =' INIS(1), 'FILTER THRESHOLD =' INIS(2)
      WRITE(6,*) 'ADAM SAMPLING FREQ =' FREADM, 'AOM SAMPLING FREQ =' FREADM
      WRITE(6,*) 'INV. GAIN FACTOR FOR MASKING LBS =' SCAL3(24)*2.**13)
      WRITE(6,*) 'MAX. O-BUFFER LENGTH =' SCAL3(25)
      WRITE(6,*) 'GAIN FACTOR AT ADAM INPUT =' SCAL3(24)*SCAL3(26)

      C----- SET UP ROUTINE FOR IOS TRANSFER
      C
      CALL ASSIGN(3, 'SY:IOSDC.CSP')
      CALL FPMID(IOSPGM, SIZE, MSGERR)
      IF (MSGERR.EQ.0) GO TO 88
      TYPE *, '*** ERROR', MSGERR, ' IN IOS PROGRAM'
      STOP
      CONTINUE

      88
      C----- SET IOS DATA RATE
      C
      CNTS=256.-(1.536E6/(4.*2.*FREADM))
      CNTD=256.-(1.536E6/(8.*1.5.*FREADM))
      CNTIOS=256.-CNTD+CNTS
      IF (CNTIOS.GT.32767.) CNTIOS=CNTIOS-65536.
      IOSPGM(2)=CNTIOS

```



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```

C
C
C      INITIALIZE THESE BUFFERS
M=VSMAL(ADM1,B,ADM1,B)
M=VSMAL(ADM2,B,ADM2,B)
M=VSMAL(AOM1,B,AOM1,B)
M=VSMAL(AOM2,B,AOM2,B)
M=VSMAL(AOM3,B,AOM3,B)
M=VSMAL(AOM4,B,AOM4,B)
M=VSMAL(SAMP,B,SAMP,B)
M=VSMAL(TXVHAT,B,TXVHAT,B)
M=VSMAL(TISHAT,B,TISHAT,B)
M=VSMAL(RCVHAT,B,RCVHAT,B)
M=VSMAL(RISHAT,B,RISHAT,B)

C
C
C      INITIALIZE Q-BUFFERS FOR ENCODER
DO 98 I=1,138
  DECT(I)=2
  DECT(I)=1
  DECT(128)=-12
  DECT(129)=-12
  DECT(138)=-12
M=MPVDB(OTR1,DECT(1),2,B,DECT(138))
M=MPVDB(OTR2,DECT(1),2,B,DECT(138))

C
C
C      CONSTRUCT DECODE TABLES
1.DECT - SIZE:256
DO 188 I=1,256
  DECT(I)=B
  CONTINUE
188 C

DO 182 I=1,14
  II=DECTAB(1,I)+1
  DECT(II)=DECTAB(2,I)+2
  CONTINUE
182 C

2.DECB - SIZE:128
DO 185 I=1,128
  DECB(I)=48
  CONTINUE
185 C

DO 186 I=1,97
  II=ENCB(1)+1
  DECB(II)=I-1
  CONTINUE
186 C

DO 187 I=1,8
  II=PHBTA(1)+1
  DECB(II)=-1
  CONTINUE
187 C

C
C
C      INITIALIZE FUNCTION LIST SELECTOR

```

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```

C
#265      ISEL(1)=B
#266      ISEL(2)=-1
#267      ISEL(3)=56

C      C----- OFFSET
C      C----- OFFSET=2

#268      C-----

C      C----- INITIALIZE ENCODE-DECODE TABLES
C      C-----
#269      M=MPVDB(ENTRT,ENCT(1),2,B,ENCT(3B))
#270      M=MPVDB(ENTRB,ENCB(1),2,B,ENCB(97))
#271      M=MPVDB(DCRCT,DECT(1),2,B,DECT(256))
#272      M=MPVDB(DCRB,DECB(1),2,B,DECB(128))
C      C----- INITIALIZE PARAMETERS, SCALARS FOR PARC
C      C-----
#273      M=MPVST(5B,SCAL1(1),15,1)
#274      M=MPVST(6B,SCAL2(1),29,1)
#275      M=MPVST(9A,SCAL3(1),26,1)
#276      M=MPVST(5B,INIS(1),14,1)
#277      M=MPVDB(TXPARA,A1(1),4,1,A1(8B))
#278      M=MPVST(IFSEL,ISEL(1),3,B)
#279      M=MPVDB(RCPARA,A2(1),4,1,A2(8B))

C      C----- SET UP IOS TRANSFER ROUTINE AND LOAD IOS
C      C-----
#280      M=MPVDB(IDIOS,IOSPGM(1),2,B,IOSPGM(2B))
#281      M=MPLDS(IOS,IOS2,IDIOS)

C      C----- LOAD ADAM, AOM FUNCTIONS
C      C-----
#282      M=ADMSD(IDADM,2,B,1,B,2,CHAN1,ADM2,ADM1)
#283      M=AOMID(IDAOM,1,B,2,AOM2,AOM1,OFFSET)
#284      M=MPLDS(ADM,IOS2,IDAOM)
#285      M=MPLDS(AOM,IOS2,IDAOM)

C      C----- FUNCTION LISTS
C      C-----
C      C----- FUNCTION LIST FOR Q-LEVEL LOOP-BACK OPERATION
C      C-----
#286      M=MPBFL(IFPRC)
#287      M=MPVT(2,ADM1)
#288      M=PICH3(ITBTR1,ADM1)
#289      M=PCTX(ITBTR1+2,QTR1)
#290      M=MPVT(1,1)
#291      M=RC(ITBTR1,59)
#292      M=TX(56)
#293      M=PCRC(ITBTR1+1,QTR1,AOM3)
#294      M=MPVT(2,ADM2)
#295      M=PICH3(ITBTR2,ADM2)
#296      M=PCTX(ITBTR2+2,QTR2)
#297      M=MPVT(1,1)
#298      M=RC(ITBTR2,59)

```

188 ---> 94  
1 SAME AS ISEL(3)  
189 ---> 95

191 ---> 96





```

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#337 M=PICH3(ITBTR2,ADM2)
#338 M=PCIX(ITBTR2+2,QTR2)
#339 M=DECD(BRC,IFSEL,ORC1,ITBRC1,ORC2,ITBRC2,DCRCT,DCRCB,IGAP)
#340 M=MPVT(1,1)
#341 M=TX(56)
#342 M=MPEFL(B)

C ----- PARC FULL OP FUNC LIST - 1
C
#343 M=MPBFL(IFREC1)
#344 M=MPVT(2,ADM1)
#345 M=RC(ITBRC1,59)
#346 M=PICH3(ITBTR1,ADM1)
#347 M=ENCD(QTR2,BTR2,ENTR8,ENTRT,ITBTR2,ITBRC1,59)
#348 M=PCIX(ITBTR1+2,QTR1)
#349 M=PCRC(ITBRC1+1,ORC1,ADM3)
#350 M=DECD(BRC,IFSEL,ORC1,ITBRC1,ORC2,ITBRC2,DCRCT,DCRCB,IGAP)
#351 M=MPVT(1,1)
#352 M=TX(56)
#353 M=MPEFL(B)

C ----- PARC FULL OP FUNC LIST - 2
C
#354 M=MPBFL(IFREC2)
#355 M=MPVT(2,ADM2)
#356 M=RC(ITBRC2,59)
#357 M=PICH3(ITBTR2,ADM2)
#358 M=ENCD(QTR1,BTR1,ENTR8,ENTRT,ITBTR1,ITBRC2,59)
#359 M=PCIX(ITBTR2+2,QTR2)
#360 M=PCRC(ITBRC2+1,ORC2,ADM4)
#361 M=DECD(BRC,IFSEL,ORC1,ITBRC1,ORC2,ITBRC2,DCRCT,DCRCB,IGAP)
#362 M=MPVT(1,1)
#363 M=TX(56)
#364 M=MPEFL(B)

C ----- FUNCTION LIST TO RUN PARC WITH Q-LEVEL LOOP-BACK
C
#365 M=MPBFL(IFPOL)
#366 M=INI(58,NRUNL)
#367 M=MPRNS(105,IOS2,B)
#368 M=MPRAA(ADM,B,ADM,B)
#369 M=MPVT(2,ADM2)
#370 M=RCINI(61)
#371 M=MPVHL(B,B,IFPRC)
#372 M=MPEFL(B)

C ----- READY TO RUN. SELECT MODE AND GO
C
#373 CONTINUE
#374 TYPE '...' SELECT OPERATION MODE:'
#375 TYPE '...' - STOP PROGRAM.
#376 TYPE '...' 1 - Q-LEVEL LOOP-BACK IN MEMORY. (NO IOS)'
#377 TYPE '...' 2 - BIT STREAM LOOP-BACK THRU IOS. (FULL DUP OP.)'
#378 ACCEPT '...' LMODE
#379 GO TO(75B,58B,68B) LMODE+1

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PARC96.FTH /TR:BLOCKS/VR

```

C ----- OPERATION MODE 1
C
8388 M-MPXFL(IFPOL)
8389 TYPE '...' PARC IN Q-LEVEL LOOP-BACK MODE (NO IOS)'
8390 TYPE '...'
8391 GO TO 788
C ----- OPERATION MODE 2
C
8394 M-MPXFL(IFPIOS)
8395 TYPE '...' PARC IN FULL DUPLEX MODE (THRU IOS)'
8396 TYPE '...'
C ----- STOP ADM,ADM,IOS, CLOSE MAP, AND STOP.
C
788 CONTINUE
      PAUSE ' TYPE RES... TO CONTINUE'
      M-MPSAA(ADM)
      M-MPSAA(ADM)
      M-MPCLS(B)
      GO TO 85
8397 CONTINUE
8398 M-MPCLS(B)
8399 STOP
8400 END

```

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 PARC96.FTN /TR:BLOCKS/VR  
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## PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	012752 2885	RV,I.CON,LCL
2	SFOATA	001030 268	RV,D.CON,LCL
3	SIDATA	002024 522	RV,D.CON,LCL
4	SVARS	005756 1527	RV,D.CON,LCL
5	STEMPS	000004 2	RV,D.CON,LCL

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
ADM	I*2	4-005440	ADM1	I*2	4-002334	ADM2	I*2	4-002336	AINV	R*4	4-005664
ALP	R*4	4-005650	ALT	I*2	4-005534	AOM	I*2	4-005442	AOM1	I*2	4-002410
AOM3	I*2	4-002414	AOM4	I*2	4-002416	BITLMT	R*4	4-005610	BITI	R*4	4-005604
BOUT2	I*2	4-002432	BRC	I*2	4-005426	BTRI	I*2	4-005416	BTR2	I*2	4-005420
CNTD	R*4	4-005740	CNTIOS	R*4	4-005744	CNTS	R*4	4-005734	CONTIG	I*2	4-005532
DCRCT	I*2	4-005406	ENTRB	I*2	4-005402	ENTRT	I*2	4-005404	FBLK	I*2	4-002436
FIXED	I*2	4-005524	PREADM	R*4	4-005726	G	R*4	4-005660	GAP	R*4	4-005634
I	I*2	4-005706	IBUS1	I*2	4-005536	IBUS2	I*2	4-005540	IBUS3	I*2	4-005542
IDAOM	I*2	4-005452	IDIOS	I*2	4-005454	IFMODE	I*2	4-005552	IFPIOS	I*2	4-005550
IFPRC	I*2	4-005546	IFRCVR	I*2	4-005556	IFREC1	I*2	4-005564	IFPQL	I*2	4-005544
IFSYN1	I*2	4-005554	IFSYN1	I*2	4-005560	IFSYN2	I*2	4-005562	IFSEL	I*2	4-005456
IK	I*2	4-005676	IL	I*2	4-005700	ILL	I*2	4-005702	IOS	I*2	4-005632
IOBETA	I*2	4-005724	ITBRC1	I*2	4-005434	ITBRC2	I*2	4-005436	IOS2	I*2	4-005444
ITEND	I*2	4-005620	ITSTRT	I*2	4-005616	J	I*2	4-005704	ITBTR2	I*2	4-005432
K11	I*2	4-005712	LMODE	I*2	4-005754	LONG	I*2	4-005526	K1	I*2	4-005710
N	I*2	4-005674	NRUNL	I*2	4-005514	OFFSET	I*2	4-005400	MSGERR	I*2	4-005732
ORC2	I*2	4-005424	QTR1	I*2	4-005412	QTR2	I*2	4-005414	QRC1	I*2	4-005422
RCVHT2	I*2	4-002440	REAL	I*2	4-005520	RKBLK	R*4	4-005574	RCVHAT	I*2	4-002420
R2SHAT	I*2	4-002424	SAMP	I*2	4-002340	SHORT	I*2	4-005530	RISHAT	I*2	4-002422
STATE	R*4	4-005670	TBLK	I*2	4-002434	TEND	R*4	4-005626	SMIN	R*4	4-005654
TXPARA	I*2	4-002350	TXVHAT	I*2	4-002342	TISHAT	I*2	4-002344	TBLK	R*4	4-005600
									T2SHAT	I*2	4-002346
									UBETA	R*4	4-005714

## ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
A1	R*4	4-000430	000500	160 (80)
A2	R*4	4-001130	000500	160 (80)
B	R*4	4-002210	000120	40 (20)
CHAN1	I*2	4-005460	000040	16 (16)
DECB	I*2	4-004662	000400	128 (128)
DECT	I*2	4-003662	001000	256 (256)
DECTAB	I*2	4-005302	000070	28 (2,14)
ENCB	I*2	4-003360	000302	97 (97)
ENCT	I*2	4-003264	000074	30 (30)
EXPN	R*4	4-001750	000120	40 (20)
INIS	I*2	4-002352	000034	14 (14)
IOSPGM	I*2	4-002442	000620	200 (200)
ISEL	I*2	4-005372	000006	3 (3)
OUTSCA	R*4	4-001630	000120	40 (20)

```

TRC.FTN      /TR:BLOCKS/VR
C
C *** HOST SUPPORT MODULES FOR PARC ***
C
C THERE ARE SIX HOST SUPPORT MODULES FOR PARC AS FOLLOWS:
C
C INI(ISA,LRUN) --- INITIALIZATION PROGRAM FOR ALL APS MODULES.
C TX(ISA) --- UPDATE PROGRAM FOR THE APS MODULES OF PARC-TRANSMITTER
C RC(ISA,ISA) --- UPDATE PROGRAM FOR THE APS MODULES OF PARC-RECEIVER
C PIC3(SA,U) --- FOR BETA, T CALCULATION AND FILTER, GAPPING OPERATIONS.
C PCTX(SA,U) --- PARC-TRANSMITTER
C PCRC(SA,U,V) --- PARC-RECEIVER
C RCINI(ISA) --- INITIALIZATION PROGRAM FOR PARC-RECEIVER
C
C
C INTEGER FUNCTION INI(ISA,LRUN)
C
C INI(ISA,LRUN) --- INITIALIZATION PROGRAM FOR ALL APS MODULES.
C
C FCB = 115
C
C CALL FORMAT:
C
C MAP=INI(ISA,LRUN)
C WHERE ISA --- THE STARTING INTEGER SCALAR LOCATION
C LRUN --- RUN LENGTH FOR ENCODER
C
C INTEGER FCBRG,FCBSZ,HVS,FCB,MPDCB,HRD,LEVEL
C INTEGER ISA,LRUN
C COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
C
C INI=0
C DO 100 I=1,11
C   FCBRG(I)=0
C   FCBRG(2)=115
C   CHECK ARGUMENT
C   IF(ISA .LT. 0 .OR. ISA .GT. 127)INI=-1
C
C   IF(INI .EQ. 0)GO TO 200
C   CALL MPERR(INI)
C   RETURN
C
C   FCBRG(3)=ISA
C   FCBRG(5)=LRUN
C
C   INI=RUNMP(FCBRG(1),FCBSZ(1,4))
C
C   RETURN
C   END

```

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TRRC.FTN /TR:BLOCKS/VR

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# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	000222	73
3	SIDATA	000014	6
4	SVARS	000006	3
6	MPZZZ	000312	101

# ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
INI	I*2	1-000000						

# VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	I*2	4-000002	HR1	R*4	6-000304	HVS	I*2	4-000000
LEVEL	I*2	6-000310	LRUN	I*2	F-000004*	ISA	I*2	F-000002*

# ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	I*2	6-000260	000014	6
FCBRG	I*2	6-000000	000026	11
FCBSZ	I*2	6-000026	000232	77
MPDCB	I*2	6-000274	000010	4

# LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000144		

# FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 000556 183

```

FORTRAN IV-PLUS V02-51      12:47:28      15-APR-88      PAGE 3
TRNC.FTN /TR:BLOCKS/WR

      C
      C      INTEGER FUNCTION TX(ISA)
      C 11. TX(ISA) --- UPDATE PROGRAM FOR APS MODULES FOR PARC-TRANSMITTER
      C
      C      FCB = 114
      C
      C      CALL FORMAT:
      C
      C      MAP=TX(ISA)
      C      WHERE ISA --- THE STARTING INTEGER SCALAR LOCATION
      C
      C      INTEGER FCBRG,FCBSZ,HWS,FCB,MPDCB,HRD,LEVEL
      C      INTEGER ISA
      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
      C
      C      TX=B
      C      DO 100 I=1,11
      C      FCBRG(I)=B
      C      FCBRG(2)=114
      C      CHECK ARGUMENT
      C      IF(ISA.LT. B .OR. ISA.GT. 127)TX=-1
      C
      C      IF(TX.EQ. B)GO TO 200
      C      CALL MPERR(TX)
      C      RETURN
      C
      C      FCBRG(3)=ISA
      C      TX=RUNMP(FCBRG(1),FCBSZ(1,3))
      C
      C      RETURN
      C      END

```

FORTRAN IV-PLUS V02-51  
TRAC.FTM /TR:BLOCKS/VR

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# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	000214 78	RV,I,CON,LCL
3	SIDATA	000014 6	RV,D,CON,LCL
4	SVARS	000006 3	RV,D,CON,LCL
6	MPZZZ	000312 101	RV,D,OVR,GBL

## ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
TX	1*2	1-000000						

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	1*2	4-000002	HRI	R*4	6-000304	HVS	1*2	4-000000
LEVEL	1*2	6-000310				I	1*2	4-000004
						ISA	1*2	F-000002*

## ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	1*2	6-000260	000014	6 (6)
FCBRG	1*2	6-000000	000026	11 (11)
FCBSZ	1*2	6-000026	000232	77 (11,7)
MPDCB	1*2	6-000274	000010	4 (4)

## LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000144		

## FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 000550 100



```

FORTRAN IV-PLUS V02-51      12:47:34      15-APR-80      PAGE 5
TRRC.FTN

      C
      C      INTEGER FUNCTION RC(SA,ISA)
      C III.  RC(SA,ISA) --- UPDATE PROGRAM FOR APS MODULES OF PARC-RECEIVER
      C      FCB = 113
      C      CALL FORMAT:
      C      MAP=RC(SA,ISA)
      C      WHERE SA --- SCALAR LOCATION FOR T
      C      ISA --- THE STARTING INTEGER SCALAR LOCATION
      C
      C      INTEGER FCBRG,FCBSZ,HWS,FCB,MPDCB,HRD,LEVEL
      C      INTEGER SA,ISA
      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),MRI,LEVEL
      C
      C      RC=0
      C      DO 100 I=1,11
      C      FCBRG(I)=0
      C      FCBRG(2)=113
      C      CHECK ARGUMENTS
      C      IF(SA.LT.0.OR.SA.GT.127)RC=-1
      C      IF(ISA.LT.0.OR.ISA.GT.127)RC=-2
      C
      C      IF(RC.EQ.0)GO TO 200
      C      CALL MPERR(RC)
      C      RETURN
      C
      C      FCBRG(9)=SA
      C      FCBRG(11)=ISA
      C      RC=RUNMP(FCBRG(1),FCBSZ(1,5))
      C
      C      RETURN
      C      END

```

FORTRAN IV-PLUS V02-51  
TRNC.FTN /TR:BLOCKS/VR

12:47:34 15-APR-80

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# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	83	RV,I.COM,LCL
3	SIDATA	6	RV,D.COM,LCL
4	SVARS	3	RV,D.COM,LCL
6	MPZZZ	101	RV,D.OVR,GBL

## ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
RC	1*2	1-000000						

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	1*2	4-000002	HR1	R*4	6-000304	HVS	1*2	4-000000
LEVEL	1*2	6-000310	SA	1*2	F-000002*	ISA	1*2	4-000004
								F-000004*

## ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	1*2	6-000260	000014	6 (6)
FCBGC	1*2	6-000000	000026	11 (11)
FCBSZ	1*2	6-000026	000232	77 (11,7)
MPDCB	1*2	6-000274	000010	4 (4)

## LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000170		

## FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED - 000602 193

```

FORTRAN IV-PLUS V02-51      12:47:41    15-APR-88      PAGE 7
TRAC.FTN                    /TR:BLOCKS/VR

      C
      C
0001      C      INTEGER FUNCTION PICH3(SA,U)
      C IV.    PICH3 -- FOR BETA, T COMPUTATION AND FILTER, GAPPING OPERATIONS
      C
      C      FCB = 248
      C
      C      CALL FORMAT:
      C      MAP=PICH3(SA,U)
      C
      C      WHERE SA --- SCALAR LOCATION FOR ENCD. BETA, BETA AND T
      C      U --- INPUT ADAM BUFFER
      C
      C      INTEGER SA,U
      C      IDUMY=8
      C      PICH3=FCBGN(248,B.SA,U,IDUMY,B,B,B,6)
      C      RETURN
      C      END
0002
0003
0004
0005
0006

```

FORTRAM IV-PLUS V02-51  
TRRC.FTN /TR:BLOCKS/VR

12:47:41 15-APR-88

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# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	000102	RV,I,CON,LCL
2	SPDATA	000014	RV,D,CON,LCL
3	SIDATA	000038	RV,D,CON,LCL
4	SVARS	000002	RV,D,CON,LCL

# ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
PICH3	I*2	1-000000						

# VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
IDUHV	I*2	4-000000	SA	I*2	F-000002*	U	I*2	F-000004*

# FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 000158 52

FORTRAN IV-PLUS V02-51 12:47:45 15-APR-68 PAGE 9  
TRRC.FTN /TR:BLOCKS/VR

```

0001      C      INTEGER FUNCTION PCTX(SA,U)
          C V.    PCTX -- PARC-TRANSMITTER
          C      FCB = 242
          C      CALL FORMAT:
          C      MAP=PCTX(SA,U)
          C      WHERE SA --- THE SCALAR LOCATION FOR BETA
          C      U --- OUTPUT QUANTIZING BUFFER
          C
          C      INTEGER SA,U
          C      IDUMY=0
          C      PCTX=FCBGN(242,B,SA,U,IDUMY,B,B,B,6)
          C      RETURN
          C      END
0002
0003
0004
0005
0006

```

FORTMAN IV-PLUS V02-S1  
TRRC.FTN /TR:BLOCKS/WR

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# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	000102	33
2	SPDATA	000014	6
3	SIDATA	000038	12
4	SVARS	000002	1

## ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
PCTX	I*2	1-000000									

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
IDUHY	I*2	4-000000	SA	I*2	F-000002	U	I*2	F-000004			

## FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 000158 52

```

FORTRAN IV-PLUS V02-S1      12:47:48   15-APR-88      PAGE 11
TRRC.FTN /TR:BLOCKS/VR

      C
0001      INTEGER FUNCTION PCRC(SA,U,V)
      C
      C VI.      PCRC --- PARC-RECEIVER
      C
      CCB      FCB = 243
      C
      CCB      CALL FORMAT:
      CCB      MAP-PCRC(SA,U,V)
      C
      CCB      WHERE SA --- SCALAR NUMBER FOR INPUT ENCD. BETA AND T
      CCB      V --- AQH BUFFER
      CCB      U --- INPUT QUANTIZING BUFFER
      C
      CCB      INTEGER SA,U,V
      CCB      PCRC=FCBGN(243,B,SA,U,B,V,B,B,7)
      CCB      RETURN
      CCB      END

0002
0003
0004
0005

```

FORTAN IV-PLUS V82-S1  
TRAC.FTH

12:47:48

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/TR:BLOCKS/VR

# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	34	RV,I,CON,LCL
2	SPDATA	6	RV,D,CON,LCL
3	SIDATA	12	RV,D,CON,LCL

## ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
PCRC	I*2	1-888888						

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
SA	I*2	F-888882*	U	I*2	F-888884*	V	I*2	F-888886*

## FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 888158 52



```

FORTRAN IV-PLUS V02-51      12:47:52      15-APR-88      PAGE 13
TRAC.FTN      /TR:BLOCKS/VR

      C      INTEGER FUNCTION RCINI(ISA)
      C VII.  RCINI(ISA) --- INITIALIZATION PROGRAM FOR APS MODULES OF RECEIVER.
      C
      C      FCB = 116
      C
      C      CALL FORMAT:
      C
      C      MAP-RCINI(ISA)
      C      WHERE ISA --- THE STARTING INTEGER SCALAR LOCATION
      C
      C      INTEGER FCBRG,FCBSZ,HVS,FCB,MPDCB,HRD,LEVEL
      C      INTEGER ISA
      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
      C
      C      RCINI=0
      C      DO 100 J=1,11
      C      FCBRG(1)=0
      C      FCBRG(2)=116
      C      CHECK ARGUMENT
      C      IF(ISA .LT. 0 .OR. ISA .GT. 127)RCINI=-1
      C
      C      IF(RCINI .EQ. 0)GO TO 200
      C      CALL MPERR(RCINI)
      C      RETURN
      C
      C      FCBRG(3)=ISA
      C      RCINI=RUNMP(FCBRG(1),FCBSZ(1,3))
      C
      C      RETURN
      C      END

```

FORTRAN IV-PLUS V02-51  
TRRC.FTN /TR:BLOCKS/VR

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# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	71	RV,I,CON,LCL
3	STDATA	6	RV,D,CON,LCL
4	SVARS	3	RV,D,CON,LCL
6	MPZZZ	101	RV,D,OVR,GBL

## ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
RCINI	I*2	1-000000									

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	I*2	4-000002	HR1	R*4	6-000304	HVS	I*2	4-000000	I	I*2	4-000004
LEVEL	I*2	6-000310							ISA	I*2	F-000002*

## ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	I*2	5-000260	000014	6 (6)
FCBRG	I*2	6-000000	000026	11 (11)
FCBSZ	I*2	6-000026	000232	77 (11,7)
MPDCB	I*2	6-000274	000010	4 (4)

## LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000106				

## FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 000552 101

FORTRAN IV-PLUS V#2-B1  
TRAC.FTN /TR:BLOCKS/VR PAGE 15

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C  
C

.TRAC/NOSP=TRRC

```

FORTRAN IV-PLUS V02-S1      12:48:04    15-APR-80      PAGE 1
ENCD.FTN /TR:BLOCKS/VR

      C
0001  C      INTEGER FUNCTION ENCD(QHAT,OUTB,BETA,ENCT,ISTB,SID,ISID)
      C ----- HOST SUPPORT MODULE FOR SOURCE CODING THE Q-OUTPUT OF
      C           THE PARC ALGORITHM.
      C
      C      FCB=110
      C
      C      CALLING SEQUENCE:
      C      M=ENCD(QHAT,OUTB,BETA,ENCT,ISTB,SID,ISID)
      C
      C      WHERE:
      C      QHAT = Q-OUTPUT BUFFER, LENGTH=400
      C      OUTB = OUTPUT BIT BUFFER, LENGTH=200
      C      BETA = CODING TABLE FOR 99 BETA VALUES, LENGTH=100
      C      ENCT = SOURCE CODE BUFFER, LENGTH=30
      C      CONTAINS FOR EACH LEVEL:
      C          1ST WORD: CODE LENGTH-1
      C          2ND WORD: CODE
      C
      C      ISTB = SID IN INTEGER TABLE WHERE T,BETA ARE LOCATED
      C      SID = SCALAR ID FOR RCVR UPDATE
      C      ISID = INT. SCALAR ID FOR RCVR UPDATE
      C
      C      INTEGER FCBRG,FCBSZ,HVS,FCB,MPDCB,HRD,LEVEL
      C      INTEGER QHAT,OUTB,BETA,ENCT,ISTB,SID,ISID
      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
      C
      C      ENCD=0
      C      DO 100 I=1,11
      C      FCBRG(I)=0
      C      CONTINUE
      C      FCBRG(2)=110
      C
      C ----- CHECK BID VALUES
      C
      C      IF(QHAT.LT.1.OR.QHAT.GT.63) ENCD=-1
      C      IF(OUTB.LT.1.OR.OUTB.GT.63) ENCD=-2
      C      IF(BETA.LT.1.OR.BETA.GT.63) ENCD=-3
      C      IF(ENCT.LT.1.OR.ENCT.GT.63) ENCD=-4
      C
      C ----- CHECK SCALAR VALUES
      C
      C      IF(ISTB.LT.1.OR.ISTB.GT.127) ENCD=-5
      C      IF(SID.LT.1.OR.SID.GT.127) ENCD=-6
      C      IF(ISID.LT.1.OR.ISID.GT.127) ENCD=-7
      C
      C      IF(ENCD.EQ.0) GO TO 150
      C      CALL MPERR(ENCD)
      C      RETURN
      C
      C      CONTINUE
      C      FCBRG(3)=ISTB
      C      FCBRG(4)=OUTB
      C      FCBRG(5)=QHAT
      C      FCBRG(6)=BETA
      C      FCBRG(7)=ENCT

```

FORTAN IV-PLUS V02-51  
ENCD.FTN

/TR:BLOCKS/VR

12:48:04

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0026  
0027  
0028  
0029  
0030

FCBRC(9)=SID  
FCBRC(11)=ISID

C

ENCD=RUNMP(FCBRC(1),FCBSZ(1,5))

C

RETURN  
END

FORTRAM IV-PLUS V02-51  
 ENCD.FTN /TR:BLOCKS/VR

12:48:04 15-APR-88

PAGE 3

# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1 988478	156	RV,I.COM,LCL
3	SIDATA 888814	6	RV,D.COM,LCL
4	SVARS 888886	3	RV,D.COM,LCL
6	MP22Z 888312	181	RV,D.OVR,GBL

# ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
ENCD	I*2	1-888888									

# VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
BETA	I*2	F-888886*	ENCT	I*2	F-888818*	HRD					
I	I*2	4-888884	ISID	I*2	F-888816*	ISTB					
QHAT	I*2	F-888882*	SID	I*2	F-888814*						
						HR1	R*4	6-8888384	HWS	I*2	4-888888
						LEVEL	I*2	6-8888318	OUTB	I*2	F-888884*

# ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	I*2	6-8888268	888814	6 (6)
FCBGR	I*2	6-8888888	888826	11 (11)
FCBSZ	I*2	6-8888826	888232	77 (11.7)
MPDCB	I*2	6-8888274	888818	4 (4)

# LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
188	**	158	1-8888354				

# FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 881824 266

FORTAN IV-PLUS V82-51  
ENCD.FTN /TR:BLOCKS/VR

C

.ENCD/NOSP=ENCD

12:48:15

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```

FORTRAN IV-PLUS V2-51      12:48:21    15-APR-88      PAGE 1
TRBUF.FTN      /TR:BLOCKS/MP

C
0001      INTEGER FUNCTION TRBUF(DBUF1,DBUF2,INIT,CBUF)
C
C----- HOST SUPPORT MODULE FOR DOUBLE BUFFER TO CIRC BUFF TRANSFER
C----- PROGRAM.
C----- IOS SIMULATOR IN CSPU. (ON/OFF HOOK SIMULATION)
C
C      FCB=112
C
C      ARGUMENTS:
C      DBUF1 = BID OF DOUBLE BUFFER 1
C      DBUF2 = BID OF DOUBLE BUFFER 2
C      INIT = INT. SCALAR ID FOR INIT. SELECT SWITCH
C      INIT+1 = INT. SCALAR ID FOR IOS MODE
C      # - OFF HOOK
C      1 - ON HOOK
C      CBUF = BID FOR CIRCULAR BUFFER
C
C      INTEGER FCBRG,FCBSZ,HWS,FCB,MPDCB,HRI,LEVEL,RUNMP
C      INTEGER DBUF1,DBUF2,INIT,CBUF
C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
C
C      TRBUF=#
C      DO 100 I=1,11
C      FCBRG(I)=#
C      CONTINUE
C      FCBRG(2)=112
C
C----- CHECK ARGUMENTS
C
C      IF(DBUF1.LT.1.OR.DBUF1.GT.63) TRBUF=-1
C      IF(DBUF2.LT.1.OR.DBUF2.GT.63) TRBUF=-2
C      IF(INIT.LT.1.OR.INIT.GT.127) TRBUF=-3
C      IF(CBUF.LT.1.OR.CBUF.GT.63) TRBUF=-4
C
C      IF(TRBUF.EQ.#) GO TO 150
C      CALL MPERR(TRBUF)
C      RETURN
C
C      CONTINUE
C      FCBRG(3)=INIT
C      FCBRG(4)=DBUF1
C      FCBRG(5)=DBUF2
C      FCBRG(7)=CBUF
C
C      TRBUF=RUNMP(FCBRG(1),FCBSZ(1,4))
C
C      RETURN
C      END

```



FORTAN IV-PLUS V02-51  
TRBUF.FTN /TR:8BLOCKS/VR

12:48:21 15-APR-88

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# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	88326	187
3	SIDATA	88814	6
4	SVARS	88884	2
6	MPZZZ	88318	188

## ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
TRBUF	1*2	1-888888						

## VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
CBUF	1*2	F-888818*	DBUF1	1*2	F-888882*	DBUF2	1*2	F-888884*
1	1*2	4-888882	INIT	1*2	F-888886*	LEVEL	1*2	6-888886
						HR1	1*2	6-888884
						HVS	1*2	4-888888

## ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	1*2	6-888268	88814	6 (6)
FCRG	1*2	6-888888	88826	11 (11)
FCBSZ	1*2	6-888826	88832	77 (11,7)
MPDCB	1*2	6-888274	88818	4 (4)

## LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
188	**	158	1-888252		

## FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 888656 215

NO FPP INSTRUCTIONS GENERATED

FORTAN IV-PLUS V#2-51  
TRBUF.FTN /TR:BLOCKS/VR

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C

.TRBUF/NOSP=TRBUF

```

FORTAN IV-PLUS V02-S1          12:48:36    15-APR-88          PAGE 1
DECD.FTN      /TR:BLOCKS/VR

0001      INTEGER FUNCTION DECD(ICB,ISL,OOB1,ITB1,OOB2,ITB2,DECT,DECB,IG)
C----- MOST SUPPORT MODULE FOR DECODING BIT STREAM INPUT FOR THE
C      PARC RECEIVER.
C
C      FCB=111
C
C      CALLING SEQUENCE:
C      M=DECD(ICB,ISL,OOB1,ITB1,OOB2,ITB2,DECT,DECB,IG)
C
C      WHERE:
C      ICB = INPUT BIT BUFFER, CIRCULAR, LENGTH=1024
C      ISL = FUNCTION LIST SELECTOR
C      ISL1 = 0 - INITIALIZE, SYNCHRONIZE
C      -1 - SYNCHRONIZE
C      +1 - DECODE
C      ISL2 = -1 - FUNC. LIST 1
C      +1 - FUNC. LIST 2
C      ISL3 = INT. SCAL ID FOR XMTR UPDATE
C      OOB1 = OUTPUT QHAT BUFFER 1, LENGTH=400
C      ITB1 = INT. SC. TABLE LOC. FOR T.BETA 1, LENGTH=2
C      OOB2 = OUTPUT QHAT BUFFER 2, LENGTH=400
C      ITB2 = INT. SC. TABLE LOC. FOR T.BETA 2, LENGTH=2
C      DECT = Q-LEVEL DECODE TABLE, LENGTH=256
C      DECB = BETA DECODE TABLE, LENGTH=128
C      IG = GAP SIZE IN INTEGER FORMAT
C
0002      INTEGER FCBRG,FCBSZ,HVS,FCB,MPDCB,HRI,LEVEL,RUNMP
0003      INTEGER ICB,ISL,OOB1,ITB1,OOB2,ITB2,DECT,DECB
0004      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
C
C      DECD=0
C      DO 100 I=1,11
0005      FCBRG(I)=0
0006      CONTINUE
0007      FCBRG(2)=111
C
C----- CHECK BID VALUES
C
0008      IF(ICB.LT.1.OR.ICB.GT.63) DECD=-1
0009      IF(OOB1.LT.1.OR.OOB1.GT.63) DECD=-3
0010      IF(OOB2.LT.1.OR.OOB2.GT.63) DECD=-5
0011      IF(DECT.LT.1.OR.DECT.GT.63) DECD=-7
0012      IF(DECB.LT.1.OR.DECB.GT.63) DECD=-8
C
C----- CHECK SID VALUES
C
0013      IF(ISL.LT.1.OR.ISL.GT.127) DECD=-2
0014      IF(ITB1.LT.1.OR.ITB1.GT.127) DECD=-4
0015      IF(ITB2.LT.1.OR.ITB2.GT.127) DECD=-6
C
C----- CHECK GAP SIZE
C
0016      IF((IC.LT.1) OR (IG.GT.125)) DECD=-9
0017
0018

```

FORTAN IV-PLUS V02-51  
 DECD.FTN /TR:BLOCKS/VR PAGE 2

12:48:36 15-APR-80

```

C
0019 IF(DECD.EQ.0) GO TO 150
0020 CALL MPERR(DECD)
0021 RETURN
C
0022 CONTINUE
0023 FCBRG(3)=ISL
0024 FCBRG(4)=OQB2
0025 FCBRG(5)=OQB1
0026 FCBRG(6)=ITB2
0027 FCBRG(7)=ITB1
0028 FCBRG(8)=DECT
0029 FCBRG(9)=DECB
0030 FCBRG(10)=IG
0031 FCBRG(11)=ICB
C
0032 DECD=RUNMP(FCBRG(1),FCBSZ(1,5))
C
0033 RETURN
0034 END

```

FORTRAN IV-PLUS V02-S1  
DECD.FTN /TR:BLOCKS/WR PAGE 3

12:48:36 15-APR-88

# PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	177	RV,I,CON,LCL
3	SIDATA	6	RV,D,CON,LCL
4	SVARS	2	RV,D,CON,LCL
6	MPZZZ	188	RV,D,OVR,GBL

# ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
DECD	I*2	1-000000						

# VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
DECB	I*2	F-000028*	DECT	I*2	F-000016*	HRI	I*2	6-000304
ICB	I*2	F-000002*	IG	I*2	F-000022*	ISL	I*2	F-000004*
LEVEL	I*2	6-000306	OQB1	I*2	F-000006*	OQB2	I*2	F-000012*

# ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	I*2	6-000268	000014	6
FCBRG	I*2	6-000000	000026	11
FCBSZ	I*2	6-000026	000232	77
MPDCB	I*2	6-000274	000010	4

# LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	150	1-0000430		

# FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 001072 205

NO FPP INSTRUCTIONS GENERATED

FORTAN IV-PLUS VB2-51  
DECD.FTN /TR:BLOCKS/VR  
PAGE 4

12:48:47 15-APR-88

C

.DECD/NOSP-DECD

```

(00001) *
(00002) *
(00003) *
(00004) *
(00005) *
(00006) *
(00007) *
(00008) *
(00009) *
(00010) *
(00011) *
(00012) *
(00013) *
(00014) *
(00015) *
(00016) *
(00017) *
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(00019) *
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(00034) *
(00035) *
(00036) *
(00037) *
(00038) *
(00039) *
(00040) *
(00041) *

```

```

MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980
*****
* REAL TIME IMPLEMENTATION OF THE P A R C ALGORITHM *
* *****

```

```

PROGRAM: PARC.MAP
JAN. 30, 1980

```

```

MAVLIN YEH
ARVIND S ARORA

```

P A R C (PITCH EXTRACTED, ADAPTIVE, PREDICTIVE RESIDUAL ENCODER) IS A SPEECH COMPRESSION ALGORITHM DEVELOPED AT THE DEPARTMENT OF ELECTRICAL ENGINEERING, UNIVERSITY OF NOTRE DAME UNDER CONTRACT FROM THE DEFENCE COMMUNICATION AGENCY. THE ALGORITHM HAS BEEN CURRENTLY DEVELOPED AND OPTIMIZED FOR DIGITAL TRANSMISSION OF SPEECH AT 9600 BAUD.

THE REAL TIME IMPLEMENTATION OF P A R C HAS BEEN DONE ON THE MAP-300 ARRAY PROCESSOR. SEVEN OF THE EIGHT PROGRAM MODULES USED IN THE IMPLEMENTATION ARE CONTAINED IN THIS FILE:

1. INITIALIZATION AND UPDATING.
2. ESTIMATION OF THE PITCH PERIOD AND THE CORRELATION COEFFICIENT REQUIRED FOR PITCH REDUNDANCY REMOVAL (PRR).
3. PARC-TRANSMITTER.
4. PARC-RECEIVER.
5. DOUBLE-BUFFER (189\*2) TO CIRCULAR-BUFFER (1024) TRANSFER PROGRAM. THIS IS USED TO SIMULATE THE FUNCTION OF THE IOS2.
6. THE SOURCE ENCODER PREPARES THE DIGITAL BIT STREAM BY ENCODING THE QUANTIZER LEVELS AND THE PRR SIDE INFORMATION PUT OUT BY THE PARC TRANSMITTER. IT USES A VARIABLE-LENGTH TO VARIABLE-LENGTH ENCODING SCHEME.
7. THE DECODER PERFORMS TWO FUNCTIONS. IT FIRST ACQUIRES FRAME SYNCHRONIZATION ON THE INCOMING BIT STREAM. IT THEN DECODES THE BIT STREAM TO THE QUANTIZER LEVELS AND THE PRR INFORMATION FOR USE BY THE PARC RECEIVER.

EJECT





PAGE 3: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

(000000) EJECT







PAGE 7: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

B483F F05405B3 (00206)      MOVHR      R5,ISVT1S(R2)
B4841 4A4A (00207)          ANDRR      R4,R5
B4842 E040A21 (00208)      MOVHR      R4,DASTX
B4844 F040A25 (00209)      MOVHR      R4,VHSTX
B4846 4C46 (00210)          ADDR      R4,R3
B4847 4A4A (00211)          ANDRR      R4,R5
B4848 E040A25 (00212)      MOVHR      R4,VHSTX
B484A F040A1D (00213)      MOVHR      R4,SSTX
B484C 4C46 (00214)          ADDR      R4,R3
B484D F061FFCE (00215)      MOVHR      R6,SYSSFLGS
B484F 5A6C0004 (00216)      ANDKR      R6,R6,S4
B4851 0010A958 (00217)      JMP          CONT2S,EQ
B4853 F00DFCE (00218)      MOVLM      S6,SYSSFLGS
B4855 F0640504 (00219)      MOVHR      R6,ISVT2S(R2)
B4857 4C4C (00220)          ADDR      R4,R6
B4858 4A4A (00221)          ANDRR      R4,R5
B4859 E040A1D (00222)      MOVHR      R4,SSTX
B485B 0E70 (00223)          RETURN
                                EVEN
                                EJECT
                                (00224)
                                (00225)
                                (00226)

```

;MASK FOR SAMPLE BUFFER  
 ;  
 ;OUTPUT TRANSFERING POINTER  
 ;  
 ;ADD N OF TX  
 ;MASKING  
 ;OUTPUT WHAT POINTER  
 ;  
 ;ADD N OF TX  
 ;GET SYSTEM FLAG  
 ;CHECK G2  
 ;JUMP IF G2=0  
 ;RESET G2  
 ;GET PITCH REPETITION SIZE  
 ;ADD PITCH REPETITION SIZE  
 ;MASKING  
 ;OUTPUT S POINTER

# MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

PAGE

INIS MODULE TO INITIALIZE APS PARAMETERS.  
 IT INITIALIZES THE FOLLOWING PARAMETERS:  
 PITCH REPETITION THRESHOLD, FILTER THRESHOLD, FILTERING SIZE, ISTART,  
 CORRELATION SIZE, PITCH REPETITION SIZE, NSTX, SSTX, DASTX, VHSTX  
 INTEGER SCALAR SEQUENCE: PITCH REPETITION THRESHOLD, FILTER THRESHOLD,  
 FILTER SIZE - 1, ISTART - 1, KBLK - 1, PITCH REPETITION SIZE  
 FCB FORMAT ( 16 BIT WORD FORMAT SHOWN )

WORD	LEFT BYTE	RIGHT BYTE
1	115	INTEGER SCALAR
2	B	B
3	B	B
4	B	B
5	B	B

MOVJK R2,R1,MSKSRBYT  
 MOVHR R3,ISVTS(R2)  
 ;GET INTEGER SCALAR  
 ;PITCH REPETITION THRESHOLD

00227) \*  
 00228) \*  
 00229) \*  
 00230) \*  
 00231) \*  
 00232) \*  
 00233) \*  
 00234) \*  
 00235) \*  
 00236) \*  
 00237) \*  
 00238) \*  
 00239) \*  
 00240) \*  
 00241) \*  
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 00251) \*  
 00252) \*  
 00253) \*  
 00254) \*  
 00255) \*  
 00256) \*  
 00257) \*  
 00258) \*  
 00259) \*  
 00260) \*  
 00261) \*  
 00262) \*  
 00263) \*  
 00264) \*  
 00265) \*  
 00266) \*  
 00267) \*  
 00268) \*  
 00269) \*  
 00270) \*  
 00271) \*  
 00272) \*

00273) \*  
 00274) \*  
 00275) \*  
 00276) \*  
 00277) \*

```

PAGE      9:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 38, 1988

#4868 E0304A4F (#0271)      MOVHM      R3,INSGTH      ;WRITE PITCH REPETITION THRESHOLD
#4862 F0340503 (#0272)      MOVHM      R3,ISVT1S(R2)      ;FILTER THRESHOLD
#4864 E0304A57 (#0273)      MOVHM      R3,INSFTH      ;WRITE FILTER THRESHOLD
#4866 F0340504 (#0274)      MOVHM      R3,ISVT2S(R2)      ;FILTER SIZE - 1
#4868 E0304A68 (#0275)      MOVHM      R3,INSFBS      ;WRITE FILTER SIZE - 1
#486A F0340505 (#0276)      MOVHM      R3,ISVT3S(R2)      ;STARTING CORRELATION 0 - 1
#486C E0304A8F (#0277)      MOVHM      R3,INSCST      ;WRITE STARTING CORRELATION 0
#4870 E0304A9F (#0278)      MOVHM      R3,ISVT4S(R2)      ;CORRELATION BLOCK SIZE - 1
#4872 F0340507 (#0279)      MOVHM      R3,INSCSZ      ;WRITE CORRELATION BLOCK SIZE - 1
#4874 E0304AF1 (#0280)      MOVHM      R3,ISVT5S(R2)      ;PITCH REPETITION SIZE
#4876 E0304C81 (#0281)      MOVHM      R3,INSGSZ      ;WRITE PITCH REPETITION SIZE
#4878 2731 (#0282)      MOVHM      R3,INSTX      ;
#4879 E0304F18 (#0283)      DECR      R3,1      ;PITCH REPETITION SIZE - 1
#487B 4E36 (#0284)      MOVHM      R3,INSCR      ;
#487C E0300430 (#0285)      SUBRM      R3,R3      ;RESET R3
#487E E0304A21 (#0286)      MOVHM      R3,INSTX      ;
#487F E0304A25 (#0287)      MOVHM      R3,VHSTX      ;
#4880 E0304A1D (#0288)      MOVHM      R3,SSSTX      ;
#4882 E0304A1D (#0289)      MOVHM      R3,SSSTX      ;
#4884 2611 (#0290)      INCR      R1,1      ;POINT TO RUN LENGTH
#4885 702200FF (#0291)      MOVVM      R2,R1,SFF      ;VALUE OF RUN LENGTH
#4887 E0205115 (#0292)      MOVVM      R2,LSRUN      ;INIT VAL FOR ENCD, DECD
#4889 0C20 (#0293)      CCR      R2      ;R2=1
#488A E020E114 (#0294)      MOVVM      R2,VSDCL      ;BIT CNT.=1, FOR ENCD
#488C 0D20 (#0295)      CLR      R2      ;R2=0
#488D E0205480 (#0296)      MOVVM      R2,PSBASE      ;BASE OF FRAME POINTER,DEC
#488F 0E70 (#0297)      RETURN      ;
#4890 0000 (#0298)      EVEN      ;
#4891 0000 (#0299)      EJECT      ;

```

# --- INITIALIZATION FOR THE ENCODER AND DECODER

PAGE 18: MAP MODULES FOR THE P A R C ALGORITHM ---- JAN. 38, 1988

RCINIS MODULE TO INITIALIZE APS PARAMETERS OF RECEIVER.  
 IT INITIALIZES THE FOLLOWING PARAMETERS:  
 NSRC, VHSRC, SHSRC, DASRC AND G3  
 INTEGER SCALAR SEQUENCE: STARTING LOCATION OF RECEIVER BUFFER  
 TRANSFER BLOCK SIZE  
 FCB FORMAT ( 16 BIT WORD FORMAT SHOWN )

WORD	LEFT BYTE	RIGHT BYTE
1	116	INTEGER SCALAR #
2	#	#
3	#	#
4	#	#
5	#	#

RCINIS  
 MOVW R2,R1,MSKSRBYT  
 MOVW R3,ISVTS(R2)  
 MOVW R3,VHSRC

RCINIS  
 MOVW R2,R1,MSKSRBYT  
 MOVW R3,ISVTS(R2)  
 MOVW R3,VHSRC

RCINIS  
 MOVW R2,R1,MSKSRBYT  
 MOVW R3,ISVTS(R2)  
 MOVW R3,VHSRC

RCINIS  
 MOVW R2,R1,MSKSRBYT  
 MOVW R3,ISVTS(R2)  
 MOVW R3,VHSRC



PAGE 11: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

04896 E0304FF (00349)	MOVW	R3, SHSRC	
04898 F0440504 (00350)	MOVW	R4, ISVT2S(R2)	
0489A 4E38 (00351)	SUBRR	R3, R4	
0489B E0304ED3 (00352)	MOVW	R3, DASRC	
0489D F00FFCE (00353)	MOVL	R7, SYSSFLGS	
0489F 4E36 (00354)	SUBRR	R3, R3	
048A1 E030466 (00355)	MOVW	R3, NSRC	
048A2 0E70 (00356)	RETURN		
048A3 0000 (00357)	EVEN		
000048A4 (00358)			
000048A4 (00359)	CONIS = 0L		
000048A4 (00360)			
000048A4 (00361)	EJECT		

TRANSFER SIZE  
RESET G3

PAGE 12:

MAP MODULES FOR THE P A R C ALGORITHM

--- JAN. 30, 1980

```

(00362) *
(00363) *
(00364) *
(00365) *
(00366) *
(00367) *
(00368) *
(00369) *
(00370) *
(00371) *
(00372) *
(00373) *
(00374) *
(00375) *
(00376) *
(00377) *
(00378) *
(00379) *
(00380) *
(00381) *
(00382) *
(00383) *
(00384) *
(00385) *
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(00387) *
(00388) *
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(00394) *
(00395) *
(00396) *
(00397) *
(00398) *
(00399) *
(00400) *
(00401) *
(00402) *
(00403) *
(00404) *
(00405) *
*****
*
*      ADAPTIVE FILTERS AND
*      PITCH PERIOD AND CORRELATION CALCULATION
*
*****
IT USES V3.5 MAP-EXECUTIVE

* DESCRIPTION:
THIS PROGRAM CALCULATES THE PITCH PERIOD AND CORRELATION COEFFICIENT
OF A BLOCK SAMPLES. ALSO, DEPENDING ON THE CONDITION OF THE SAMPLE
BUFFER IN TRANSMITTER, IT WILL EMPLOY ADAPTIVE FILTER AND/OR PITCH
REpetition.

* THIS PROGRAM EMPLOYS THE FOLLOWING BUFFERS:

1. ADAM BUFFER: ADAM SAMPLES INPUT ANALOG SIGNALS AND PUTS THE
CORRESPONDING QUANTIZED DIGITAL SIGNALS INTO THIS BUFFER.
--- DOUBLE BUFFERING --- SHORT FLOATING FORMAT ---
2. SAMPLE BUFFER: THE INPUT DATA COME FROM ADAM BUFFER. THE PURPOSE
OF THIS BUFFER IS TO PROVIDE BUFFER CONTROL TECHNIQUE.
--- CIRCULAR BUFFER --- SHORT FLOATING FORMAT ---
3. WHAT BUFFER: THIS BUFFER CONTAINS RECONSTRUCTED REDUCED SPEECH
SAMPLES FROM RARC-TRANSMITTER. ( THIS PROGRAM ONLY DEFINES THE
STARTING LOCATION OF WHAT POINTER.)

* SYMBOLIC DEFINITIONS:

TBLK: TRANSFERING BLOCK SIZE FROM ADAM BUFFER TO SAMPLE BUFFER
FBLK: FILTERING BLOCK SIZE
KBLK: CORRELATION BLOCK SIZE
IEND: UPPER LIMIT OF PITCH PERIOD
SSTX: DATA POINTER IN SAMPLE BUFFER FOR USING IN PARC-TRANSMITTER
DASTX: DATA POINTER IN SAMPLE BUFFER FOR THE TRANSFER FROM ADAM
      BUFFER
VHSTX: WHAT POINTER IN WHAT BUFFER
INSGTH: LOCATION OF PITCH REPETITION THRESHOLD
INSFTH: LOCATION OF FILTER THRESHOLD
INSFBS: LOCATION OF FBLK-1
INCSST: LOCATION OF LOWER LIMIT OF PITCH PERIOD
INCSZ: LOCATION OF CORRELATION BLOCK SIZE -1
INSGSZ: LOCATION OF PITCH REPETITION SIZE

```

PAGE 13: MAP MODULE FOR THE P A R C ALGORITHM --- JAN. 38, 1988

\* RESTRICTIONS:

1. TBLK SHOULD BE MULTIPLE OF 2. THIS RESTRICTION CAN BE REMOVED IF THOSE STATEMENTS MARKED \*\*A\*\* ARE SLIGHTLY MODIFIED. THE PURPOSE OF THIS RESTRICTION IS TO REDUCE THE DATA TRANSFERING TIME.
2. IT IS ASSUMED THAT DASTX NEVER OVERRIDES SSTX. THAT IS CONTROLLED BY 3. BY PITCH REPETITION THRESHOLD AND SIZE.
3. KBLK SHOULD BE MULTIPLE OF 4.
4. THE ABSOLUTE VALUES OF UPPER LIMIT AND LOWER LIMIT OF CORRELATION COEFFICIENT SHOULD BE THE SAME.
5. THE SEQUENCE OF INPUT SCALARS ARE AS FOLLOWS:  
TBLK/2-A.B.FBLF-B.5.KBLK-B.5.SEARCHING SIZE-B.5.2\*-15,  
IEND-B.5.B.8881,1START,LB,UB,HL/(UB\*2\*\*15),HL/(UB\*2\*\*24),  
2\*\*24\*UB/HL
6. THE LOCATIONS OF ARRAYS ARE AS FOLLOWS:

SAMPLE BUFFER: B(3) ... 1823(3)  
WHAT BUFFER: B(2) ... 1823(2) --- THE SIZE AND STARTING LOCATION  
OF THIS BUFFER CAN BE CHANGED BY SLIGHTLY MODIFICATIONS  
IN TRANSMITTER PROGRAMS.

\* CALL THIS FUNCTION:

MAP = PICH3(SA,U)  
WHERE SA --- SCALAR \* FOR PITCH PERIOD  
U --- BUFFER \* FOR ADAM BUFFER

CONTAINS FOR ASSEMBLY

```

00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
00000079 00000079 00000079 00000079 00000079 00000079 00000079 00000079
00000001 00000001 00000001 00000001 00000001 00000001 00000001 00000001
000021FC 000021FC 000021FC 000021FC 000021FC 000021FC 000021FC 000021FC
000008E8 000008E8 000008E8 000008E8 000008E8 000008E8 000008E8 000008E8
000003E6 000003E6 000003E6 000003E6 000003E6 000003E6 000003E6 000003E6
000003E8 000003E8 000003E8 000003E8 000003E8 000003E8 000003E8 000003E8
000003EE 000003EE 000003EE 000003EE 000003EE 000003EE 000003EE 000003EE
000003F2 000003F2 000003F2 000003F2 000003F2 000003F2 000003F2 000003F2
00000404 00000404 00000404 00000404 00000404 00000404 00000404 00000404
0000040E 0000040E 0000040E 0000040E 0000040E 0000040E 0000040E 0000040E
00000412 00000412 00000412 00000412 00000412 00000412 00000412 00000412
0000041A 0000041A 0000041A 0000041A 0000041A 0000041A 0000041A 0000041A

MSS=B
DMS=$794
BUSIS=$8881
TOESPRT=$288
CSPUSNOS=$21FC
AFDTS=$8E8

SVT588=SVTS+188
SVT518=SVT588+2
SVT548=SVT518+6
SVT568=SVT548+4
SVT638=SVT568+18
SVT688=SVT638+18
SVT708=SVT688+4
SVT748=SVT708+8

DUMMY OUTPUT SPACE
:BUS 1
:TOP OF EXEC.
:LOCATION OF NO-CSPU SUPPORT
:STARTING ADDRESS OF AFD
:SCALAR TABLE 58

:ADD TWO SCALAR

```

PAGE 14: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

00000426 (00450) SVT79S=SVT74S+12 ;ADD ONE SCALAR
0000042E (00451) SVT83S=SVT79S+8
00000430 (00452) SVT98S=SVT83S+24
00000432 (00453) SVT99S=SVT98S+4 ;ADD UPSAMPLING
00000434 (00454) SVT111S=SVT99S+26 ;ADD ONE SCALAR
00000436 (00455) NSTX=SVT83S+2
00000438 (00456) NSRC=SVT111S+2
0000043A (00457) SVT115S=NSRC+2
0000043C (00458) SVT117S=SVT115S+4
0000043E (00459) SVT118S=SVT117S+2
00000440 (00460) DISPATCH TABLE ENTRY
00000442 (00461) *
00000444 (00462) *
00000446 (00463) *
00000448 (00464) *
0000044A (00465) ADDR PICH3S(R7,1) ;APU=PICH3
0000044C (00466) ADDR VPICH3S(R7,1) ;APS=VPICH3
0000044E (00467) ADDR CSPUSNOS(1,0) ;NO CSPU
00000450 (00468) *
00000452 (00469) *
00000454 (00470) *
00000456 (00471) *
00000458 (00472) *
0000045A (00473) *
0000045C (00474) *
0000045E (00475) *
00000460 (00476) *
00000462 (00477) *
00000464 (00478) *
00000466 (00479) PICH3S BEGIN APU(PICH3)
00000468 (00480) * #M=3 ;STARTING ADDRESS
0000046A (00481) * #A=B ;MODULE SIZE
0000046C (00482) * DATA TRANSFER FROM ADAM BUFFER TO SAMPLE BUFFER
0000046E (00483) *
00000470 (00484) *
00000472 (00485) *
00000474 (00486) *
00000476 (00487) *
00000478 (00488) *
0000047A (00489) *
0000047C (00490) *
0000047E (00491) *
00000480 (00492) *
00000482 (00493) PICH3SSA K(1)
00000484 (00494) *
00000486 (00495) *
00000488 (00496) *
0000048A (00497) *
0000048C (00498) *
0000048E (00499) *
00000490 (00500) *
00000492 (00501) *
00000494 (00502) *
00000496 (00503) *
00000498 (00504) *
0000049A (00505) *
0000049C (00506) *
0000049E (00507) *
00000500 (00508) *
00000502 (00509) *
00000504 (00510) *
00000506 (00511) *
00000508 (00512) *
0000050A (00513) *
0000050C (00514) *
0000050E (00515) *
00000510 (00516) *
00000512 (00517) *
00000514 (00518) *
00000516 (00519) *
00000518 (00520) *
0000051A (00521) *
0000051C (00522) *
0000051E (00523) *
00000520 (00524) *
00000522 (00525) *
00000524 (00526) *
00000526 (00527) *
00000528 (00528) *
0000052A (00529) *
0000052C (00530) *
0000052E (00531) *
00000530 (00532) *
00000532 (00533) *
00000534 (00534) *
00000536 (00535) *
00000538 (00536) *
0000053A (00537) *
0000053C (00538) *
0000053E (00539) *
00000540 (00540) *
00000542 (00541) *
00000544 (00542) *
00000546 (00543) *
00000548 (00544) *
0000054A (00545) *
0000054C (00546) *
0000054E (00547) *
00000550 (00548) *
00000552 (00549) *
00000554 (00550) *
00000556 (00551) *
00000558 (00552) *
0000055A (00553) *
0000055C (00554) *
0000055E (00555) *
00000560 (00556) *
00000562 (00557) *
00000564 (00558) *
00000566 (00559) *
00000568 (00560) *
0000056A (00561) *
0000056C (00562) *
0000056E (00563) *
00000570 (00564) *
00000572 (00565) *
00000574 (00566) *
00000576 (00567) *
00000578 (00568) *
0000057A (00569) *
0000057C (00570) *
0000057E (00571) *
00000580 (00572) *
00000582 (00573) *
00000584 (00574) *
00000586 (00575) *
00000588 (00576) *
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PAGE 16:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 38, 1988

A1C 848DE 888888EE (88538)
A1D 848EB 84588448 (88539)
A1E 848E2 88288888 (88540)
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A1F 848E4 88818881 (88541)
A20 848E6 88EE8888 (88542)
A21 848E8 88588888 (88543)
A22 848EA 84588448 (88544)
A23 848EC 41888888 (88545)
A24 848EE 88888888 (88546)
A25 848F0 4F888888 (88547)
A26 848F2 88888888 (88548)
A27 848F4 8892889C (88549)
A28 848F6 881E881F (88550)
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A29 848F8 88038888 (88551)
A2A 848FA 88F88888 (88552)
A2B 848FC 28242824 (88553)
A2C 848FE 8888888F (88554)
A2D 848FF 88168816 (88555)
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      M6=SF(K-1)
      M6=SF(K-1)

      MOV(P,A1)
      MOV(IA,M6) \ NOP
      MOV(EX1,AB) \ MOV(IA,M6)
      MOV(EXO),MUL(M6,M6) \ MUL(M6,M6)
      ADD(AB,A1) \ MOV(EX1,EXO)
      MOV(R,EXO) \ NOP
      SUB(A2,A7) \ MOV(EX1,AB)
      NOP \ SUB(AB,A1)
      MOV(R,A2) \ MOV(R,00)
      JUMPC(LOOP1,T1)

      INITIALIZATION FOR SEARCHING PITCH PERIOD

      REGISTERS TO BE USED LATER:

      ADM1: A3,A6,EXO
      ADM2: A4,A6

      INPUT SEQUENCE: KBLK/4,SEARCHING SIZE - 8.5

      FLAGS AFFECTED: GB

      MOV(IQ,A3) \ NOP
      MOV(IA,EXO) \ NOP
      CLEAR(GB)
      NOP \ MOV(IA,A4)
      MOV(ZERO,A6)

      FIND T

      REGISTERS AFFECTED:

      ADM1: AB,A1,A2,A3,A5,A6
      ADM2: AB,A1,A2,A4,A5,A6

      INPUT SEQUENCE: S(J-T),S(J),S(J),S(J-T),S(J-T),S(J),S(J)

      FLAGS AFFECTED: AF8,AF1,AF3

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(00582) *
(00583) *
A2E 04902 20492049 (00584)
A2F 04904 20482048 (00585)
A30 04906 00F10000 (00586) LOOP6
A31 04908 000000F1 (00587)
A32 0490A 00F00000 (00588)
A33 0490C 000000F0 (00589)
(00590) *
A34 0490E 49004900 (00591) LOOP6
A35 04910 12851285 (00592)
A36 04912 00F10000 (00593)
A37 04914 000000F1 (00594)
A38 04916 46854685 (00595)
A39 04918 00F00000 (00596)
A3A 0491A 000000F0 (00597)
(00598) *
A3B 0491C 49164916 (00599)
A3C 0491E 12851285 (00600)
A3D 04920 00F10000 (00601)
A3E 04922 000000F1 (00602)
A3F 04924 46854685 (00603)
A40 04926 00F00000 (00604)
A41 04928 000000F0 (00605)
A42 0492A 4F760896 (00606)
A43 0492C 00930898 (00607)
A44 0492E 901E0034 (00608)
(00609) *
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A46 04932 46A00858 (00611)
A47 04934 9009004E (00612)
(00613) *
A48 04936 20292029 (00614)
A49 04938 00530894 (00615)
A4A 0493A 00920892 (00616)
A4B 0493C 00150815 (00617)
A4C 0493E 00160816 (00618)
A4D 04940 1000002F (00619)
(00620) *
A4E 04942 4E560000 (00621) LOOP7
A4F 04944 00530000 (00622)
A50 04946 00160815 (00623)
A51 04948 00000894 (00624)
A52 0494A 911E0058 (00625)

; FIRST SEARCHING
; SIGNAL APS TO PRODUCE DATA
; A1=S(J-T)
; AB=S(J)
;
; R=S(J)-S(J-T)
; R=ABS(S(J)-S(J-T))
;
; A6=SUM3
;
; R=S(J)-S(J-T)
;
; R=SUM3
; R=KBLK/4 - 1
;
; R=SEARCHING SIZE-1
; EXO=KBLK/4
;
; A2=IEND-B.5-T
;
; R=SMALL-SUM3
; A3=KBLK/4
;
; A4=SEARCHING SIZE-1

```

PAGE 18: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

A53 8494C 28482848 (88626) *
A54 8494E 82C88892 (88627)
A55 8495B 88928888 (88628)
A56 84952 88888888 (88629)
A57 84954 91888856 (88630)
A58 84956 88168816 (88631)
A59 84958 981F882F (88632)
A60 84960 88888888 (88633)
A61 84962 88888888 (88634)
A62 84964 88888888 (88635)
A63 84966 88888888 (88636)
A64 84968 88888888 (88637)
A65 84970 88888888 (88638)
A66 84972 88888888 (88639)
A67 84974 88888888 (88640)
A68 84976 88888888 (88641)
A69 84978 88888888 (88642)
A70 84980 88888888 (88643)
A71 84982 88888888 (88644)
A72 84984 88888888 (88645)
A73 84986 88888888 (88646)
A74 84988 88888888 (88647)
A75 84990 88888888 (88648)
A76 84992 88888888 (88649)
A77 84994 88888888 (88650)
A78 84996 88888888 (88651)
A79 84998 88888888 (88652)
A80 85000 88888888 (88653)
A81 85002 88888888 (88654)
A82 85004 88888888 (88655)
A83 85006 88888888 (88656)
A84 85008 88888888 (88657)
A85 85010 88888888 (88658)
A86 85012 88888888 (88659)
A87 85014 88888888 (88660)
A88 85016 88888888 (88661)
A89 85018 88888888 (88662)
A90 85020 88888888 (88663)
A91 85022 88888888 (88664)
A92 85024 88888888 (88665)
A93 85026 88888888 (88666)
A94 85028 88888888 (88667)
A95 85030 88888888 (88668)
A96 85032 88888888 (88669)

; SIGNAL APS TO RENEW T
;
; A2=SMALL
;
; JUMPS(WAIT,AF3)
;
; MOV(ZERO,A6)
; JUMPC(LOOP8-1,T2)
;
; CALCULATE CORRELATION COEFFICIENT
;
; REGISTERS AFFECTED:
;
; ADM1: A8,A3,A4,A5,A6,M8,M1,M2,M6,M7
; ADM2: A8,A4,A5,A6,M8,M1,M2,M6,M7
;
; INPUT SEQUENCE: S(J-T),S(J-T),S(J-T),S(J-T),S(J-T),S(J),S(J),S(J),
;                  S(J-T),S(J-T)
;
; FLAGS AFFECTED: AF2
;
; SET(AF2)
; MOV(ZERO,A4)
; MOV(IQ,M7) \ NOP
; MOV(IQA,M1) \ NOP
; NOP \ MOV(IQ,M7)
; NOP \ MOV(IQA,M1)
;
; MUL(M1,M7)
; ADD(A5,A6)
; MOV(IQA,M8) \ NOP
; NOP \ MOV(IQA,M8)
; MOV(A8),MUL(M8,M7)
; MOV(A6),ADD(A4,A8)
; MOV(IQ,M6) \ NOP
; MOV(IQA,M2) \ NOP
; NOP \ MOV(IQ,M6)
; NOP \ MOV(IQA,M2)
; MOV(A5),MUL(M2,M6)
; MOV(A4),ADD(A5,A6)
; MOV(IQA,M8) \ NOP
; MOV(A8),MUL(M8,M6)
;
; SET(AF3)
; R(A6) \ MOV(R,A2)
; MOV(R,A2) \ NOP
; NOP
; JUMPS(WAIT,AF3)
;
; MOV(ZERO,A6)
; JUMPC(LOOP8-1,T2)
;
; CALCULATE CORRELATION COEFFICIENT
;
; REGISTERS AFFECTED:
;
; ADM1: A8,A3,A4,A5,A6,M8,M1,M2,M6,M7
; ADM2: A8,A4,A5,A6,M8,M1,M2,M6,M7
;
; INPUT SEQUENCE: S(J-T),S(J-T),S(J),S(J),S(J-T),S(J-T),S(J),S(J),
;                  S(J-T),S(J-T)
;
; SIGNAL APS TO STOP SEARCHING
; A4=SUM OF S(J-T)**2
; M7=S(J-T)
; M1=S(J-T)
;
; P=S(J-T)**2
; R=SUM1
; MB=S(J)
;
; P=S(J)*S(J-T)
; R=SUM2

```



PAGE 19: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

A6F B4984 B8964596 (B8678)
A7B B4986 B8CFB88B (B8671)
A71 B4988 B8E9B88B (B8672)
A72 B498A 4F74B894 (B8673)
A73 B498C B8B8B8CF (B8674)
A74 B498E B8B8B8E9 (B8675)
A75 B499B B8B5B885 (B8676)
A76 B4992 B893B898 (B8677)
A77 B4994 9B1EB88B (B8678)
      (B8679) *
      (B8680) *
      (B8681) *
      (B8682) *
      (B8683) *
      (B8684) *
      (B8685) *
      (B8686) *
      (B8687) *
      (B8688) *
      (B8689) *
      (B8690) *
      (B8691) *
A78 B4996 B85B88EA (B8692)
A79 B4998 4AB8B8F4 (B8693)
A7A B499A B8F14A8B (B8694)
A7B B499C B8B8B8E7 (B8695)
A7C B499E B8B84F94 (B8696)
A7D B49AB B8B8B88E (B8697)
A7E B49A2 B8B8B854B (B8698)
A7F B49A4 B88FB8F7 (B8699)
A8B B49A6 4C34B884 (B8700)
A81 B49AB B8F73A8B (B8701)
A82 B49AA B88B889C (B8702)
A83 B49AC 9B1EB88B (B8703)
      (B8704) *
A94 B49AE 2E8B888B (B8705)
A85 B498B 46A846AB (B8706)
A86 B4982 846B888B (B8707)
A87 B4984 168B888B (B8708)
A88 B4986 B8B8B885B (B8709)
A89 B4988 48314616 (B8710)
A8A B498A B88EB88A (B8711)
A8B B498C 844B8898 (B8712)
A8C B498E B84AB88B (B8713)
A8D B49C8 B88B888B (B8714)

MOV(A6),ADD(A4,A6)
MOV(IQ,M7) \ NOP
MOV(IQ,M1) \ NOP
MOV(A4),SUB(A3,A7) \ MOV(R,A4)
NOP \ MOV(IQ,M7)
NOP \ MOV(IQ,M1)
MOV(P,A5)
MOV(R,A3) \ MOV(R,EXO)
JUMPC(LOOP9,T1)

OUTPUT BETA AND T

REGISTERS TO BE USED:

ADM1: A6,A1,A4,A7,M6,M2,M5,M7,EXO
ADM2: A6,A2,A4,A6,A7,M2,M6,EXO

INPUT SEQUENCE: 1/2**15,IEND-B.5,B.88B1,1START,LOWER BETA LIMIT,
UPPER BETA LIMIT
OUTPUT SEQUENCE: T(IN INTEGER)

MOV(EXT,A6) \ MOV(IQ,M2)
ADD(A6,A4) \ MOV(IQ,A4)
MOV(IQ,A1) \ SUB(A4,A2)
NOP \ MOV(IQ,A7)
NOP \ MOV(A4),SUB(A4,A7)
NOP \ MOV(R,M6)
NOP \ MUL(M2,M6)
MOV(R,M7) \ MOV(IQ,A7)
MOV(A4),SUB(A1,A4) \ MOV(P,A4)
MOV(IQ,A7) \ ALIGN(A4)
MOV(R,NULL) \ MOV(R,OO)
JUMPC(RESET,T1)

RCP(A4) \ NOP
MOV(MB),ADD(A5,A6) \ ADD(A5,A6) \ MB=FB
MUL(MB,M7) \ NOP
MOV(EXO),K(2) \ NOP
MOV(P,A6) \ MOV(EXT,A6)
MOV(A1),SUB(A1,A6) \ MOV(A6),ADD(A6,A6) \ R=2-A6
MOV(R,M6) \ MOV(R,M2)
MUL(MB,M6) \ MOV(R,EXO)
MOV(EXT,M2) \ NOP
MOV(P,EXO) \ NOP

M2=1./(2.**15)
A4=IEND-B.5
A7=1START
ENCODE T
M6=T
A7=LOWER BETA

R=SUM1
A6=SUM1
R=SUM1
M2=SUM1
EXO=SUM1

```



PAGE 21:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

00000000 (00750) PICH3SSZ-0A-PICH3SSA      ! COMPUTE THE SIZE OF THE MODULE  
 04A06      (00759)      END  
          (00760)      \*  
          (00761)      EJECT



```

PAGE 23:          AP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

A15 04A30 2A210039 (00006)
A16 04A3A 2CA10001 (00007)
A17 04A3C 2E0A0001 (00008)
A18 04A3E 30210039 (00009)
A19 04A40 32A10001 (00010)
A1A 04A42 34200004 (00011)
A1B 04A44 362020F8 (00012)
A1C 04A46 380A0001 (00013)
A1D 04A48 3A210039 (00014)
A1E 04A4A 3CA10001 (00015)
A1F 04A4C 3E201C01 (00016)
      (00017) *
      (00018) *
      (00019) *
      (00020) *
      (00021) *
      (00022) *
      (00023) *
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      (00048) *
      (00049) *

      VLOOP3
      VLOOP4

      ADDL(BV2,1)
      AND8(BV2,BV2,TF)
      ADD(BR3,1,TF)
      ADDL(BV2,1)
      AND8(BV2,BV2,TF)
      SUBL(BR2,4),JUMPP(VLOOP2)
      ADDL(BR2,3),JUMPN(CKP)
      ADD(BR3,1,TF)
      ADDL(BV2,1)
      AND8(BV2,BV2,TF)
      SUBL(BR2,1),JUMPP(VLOOP4)

      CHECK ADAPTIVITY (INCLUDING FILTERING AND PITCH REPETITION)

      REGISTERS PERMANENTLY USED BY THIS PROGRAM:

      BV2=THE POINTER FOR ADAM OUTPUT ADDRESS
      BV1=THE POINTER FOR PARC INPUT ADDRESS

      REGISTERS AFFECTED: BR0,BR2,BR3
      FLAGS AFFECTED: G2,AF1

      INSGTH=0L+1
      LOAD(BR3,650)
      MOV8(BR2,BV2)
      SUB8(BR2,BV1),JUMPP(CONT1)
      ADD(BR2,1024)
      INSGTH=0L+1
      LOAD(BR0,500)
      SUB8(BR2,BR3),JUMPN(NEXT1)
      SET(G2)
      ADD8(BR2,BR3)
      SUB8(BR2,BR0),JUMPN(NOTR)
      SET(AF1)

      INITIALIZE PITCH REPETITION THRESHOLD
      PITCH REPETITION THRESHOLD

      **
      INITIALIZE FILTER THRESHOLD
      NO FILTER THRESHOLD
      IF < 0 -> PITCH REPETITION
      -> PITCH REPETITION
      IF > 0 -> NO FILTER IS EMPLOYED
      SIGNAL APU --- FILTERING

      FILTER

      REGISTERS AFFECTED: BR0,BR2,BR3,BV0

      LOAD(BR0,SVT510),L,TF)
      MOV8(BR2,BV1,TF)
      ADD(BR0,2,TF)

      A20 04A62 54C203E0 (00047)
      A21 04A64 56A90012 (00048)
      A22 04A66 580A0002 (00049)

```









PAGE 27: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(00974) *
(00975) *
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(01017) *

```

PITCH EXTRACTION ADAPTIVE RESIDUAL CODER  
P A R C

IT USES V3.5 MAP-EXECUTIVE

\* DESCRIPTION:

THIS IS A SPEECH CODING PROGRAM IN MAP-300 ARITHMETIC PROCESSOR FOR DIGITAL TRANSMISSION OF SPEECH AT A RATE OF 9600 BITS PER SECOND. THE ALGORITHM COMBINES PITCH EXTRACTION LOOP, PITCH COMPENSATING ADAPTIVE QUANTIZER, SEQUENTIALLY ADAPTIVE PREDICTOR.

1. THE REDUNDANCY OF SPEECH IS REMOVED IN THE PITCH EXTRACTION LOOP BLOCK BY BLOCK.
2. THE SEQUENTIALLY ADAPTIVE PREDICTOR USING BACKWARD ADAPTION IS USED TO FORM AN ESTIMATE OF PITCH REDUCED SIGNAL.
3. THE ERROR IN THIS ESTIMATE IS NORMALIZED AND QUANTIZED BY THE PITCH COMPENSATING ADAPTIVE QUANTIZER.
4. IF PITCH REPETITION MODE HAPPENS, A BLOCK OF SHAT IS DUPLICATED.

\* SYMBOLIC ABBREVIATIONS:

INSTX LOCATION OF PITCH REPETITION SIZE IN APS MODULE

\* BUFFERS:

1. SAMPLE BUFFER: IT CONTAINS INPUT SPEECH SAMPLES AND FILTERED INPUT SPEECH SAMPLES.  
--- CIRCULAR BUFFER --- SHORT REAL FORMAT ---
2. WHAT BUFFER: IT CONTAINS RECONSTRUCTED REDUCED SPEECH SAMPLES.  
--- CIRCULAR BUFFER --- SHORT REAL FORMAT ---
3. SHAT BUFFER: IT CONTAINS RECONSTRUCTED SPEECH SAMPLES.  
--- CIRCULAR BUFFER --- SHORT REAL FORMAT ---
4. Q BUFFER: IT CONTAINS OUTPUT QUANTIZING LEVELS.  
--- DOUBLE BUFFERS --- INTEGER \* 2 FORMAT ---
5. PARAMETER BUFFER: IT CONTAINS PARAMETERS FOR QUANTIZER INCLUDING A(8),(T(J),OUT(J),EXP(N(J),B(J)) ( IN SEQUENCE )

\* RESTRICTION:

```

PAGE      28:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

```

(B1018) *	1. THE ORDER OF THE PREDICTOR IS 4.
(B1019) *	2. THE LOCATIONS OF SOME ARRAYS ARE AS FOLLOWS:
(B1020) *	SAMPLE BUFFER: B(3) ... 1023(3)
(B1021) *	WHAT BUFFER: W(2) ... 1023(2)
(B1022) *	SHAT BUFFER: S(24)(3) ... 2047(3)
(B1023) *	PARAMETER BUFFER: P(72)(2) ...
(B1024) *	3. THE SEQUENCE OF INPUT SCALARS ARE AS FOLLOWS:
(B1025) *	BITCOUNT,BIT BUFFER SIZE,RMS,STATE VARIABLE,RUN LENGTH,
(B1026) *	PHONY BETA BITS,GAP SIZE,RMSMIN,N-2.5,I-ALP,ALP,SMIN,
(B1027) *	G,NQ,RUN LENGTH,COMPENSATOR,2**14,AINV*(I/ALAD-1),
(B1028) *	ALAD,N-2.5,NULL BITS,I/2**15,NSTX,ENCD,T,ENCD.BETA,
(B1029) *	BETA,ENCD,T,ENCD.BETA,BETA
(B1030) *	* TO CALL THIS FUNCTION:
(B1031) *	MAP = PCTX(SA,U)
(B1032) *	WHERE SA --- THE SCALAR LOCATION FOR BETA
(B1033) *	U --- THE BUFFER # FOR OUTPUT QUANTIZING LEVELS
(B1034) *	
(B1035) *	
(B1036) *	
(B1037) *	
(B1038) *	
(B1039) *	
*****F2 (B1040) *	DISPATCH TABLE ENTRY
*****B94 (B1041) *	FCB242=242
(B1042) *	#L=AFTD\$+3=2*(FCB242-128)
*****4FA (B1043) *	ADDR PCTXS(R7,1)
*****E4C84 (B1044) *	ADDR VPCTXS(R7,1)
*****B21FC (B1045) *	ADDR CSPUSNOS(1,B)
(B1046) *	
(B1047) *	APU & APS MODULE
(B1048) *	
*****4FA8 (B1049) *	#L=CONZ\$
(B1050) *	APU MODULE
(B1051) *	
(B1052) *	EVEN PCTXSSA
(B1053) *	DATA PCTXSZ
(B1054) *	DATA
(B1055) *	
(B1056) *	PCTXS BEGIN APU(PCTX)
(B1057) *	#M=3
(B1058) *	#A=#
*****B3 (B1059) *	INITIALIZATION
*****BC1 (B1060) *	
(B1061) *	

: START ON WORD BOUNDARY  
: STARTING ADDRESS  
: SIZE  
  
: START OF APU MODULE

```

PAGE 29: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1988

(01062) *
(01063) *
(01064) *
(01065) *
(01066) *
(01067) *
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(01071) *
(01072) *
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(01074) *
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(01081) *
(01082) *
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(01091) *
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(01095) *
(01096) *
(01097) *
(01098) *
(01099) *
(01100) *
(01101) *
(01102) *
(01103) *
(01104) *
(01105) *

A00 04AFA 08F21688 PCTXSSA MOV(1QA,A2) \ K(1)
A01 04AFC 08F30814 MOV(1QA,A3) \ MOV(ZERO,A4)
A02 04AFE 434008F2 ADD(A2,A3) \ MOV(1QA,A2)
A03 04B00 080008F5 NOP \ MOV(1QA,A5)
A04 04B02 080008F8 NOP \ MOV(1QA,A8)
A05 04B04 08F70897 MOV(1QA,A7) \ MOV(R,A7)
A06 04B06 08920898 MOV(R,A2) \ MOV(R,EXO)

CHECK PITCH REPETITION MODE

REGISTERS USED:
ADM1: A2
ADM2: A7

REGISTERS AFFECTED:
ADM1: A1,A2
ADM2: A6

FLAGS SENSED: G2

INPUT SEQUENCE: PHONY BETA BIT,PITCH REPETITION SIZE,INPUT PITCH REPETIT
OUTPUT SEQUENCE: PHONY BETA CODE,OUTPUT PITCH REPETITION DATA

FUNCTIONS: BITCOUNT = BITCOUNT - PHONY BETA BITS
PITCH REPETITION

JUMPC(PRE3-1,G2) ;JUMP IF NO PITCH REPETITION

REGISTERS WHICH ARE PERMANENTLY USED IN THIS PROGRAM

ADM1: A2,A7
ADM2: A0,A2,A4,A5,A7

REGISTER AFFECTED:
ADM1: A2,A3
ADM2: A0,A2,A4,A5,A7,EXO

INPUT SEQUENCE: BITCOUNT,BIT BUFFER SIZE,RMS,STATE VARIABLE,RUN LENGTH

FUNCTIONS: NEW BITCOUNT = OLD BITCOUNT + BIT BUFFER SIZE

ADM1 *****
ADM2 *****

A2=BITCOUNT
A3=BIT BUFFER SIZE
A4=SAMPLE COUNT
A5=STATE VARIABLE
A6=RUN LENGTH
A7=1
EXO=NO PHONY BETA

```

PAGE 30: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A00 0400A 00F10A0B (011106)
A01 0400A 00F10A0B (011107)
A02 0400C 49400000 (011107)
A03 0400E 000000F6 (011108)
A04 04010 0092009C (011109)
A05 04012 00FC4FC0 (011110)
A06 04014 00000096 (011111)
A07 04016 001F000C (011112)
A08 04018 10000011 (011113)
A09 04020 00EA0000 (011114)
A10 04022 00000000 (011115)
A11 04024 00000000 (011116)
A12 04026 00000000 (011117)
A13 04028 00000000 (011118)
A14 04030 00000000 (011119)
A15 04032 00000000 (011120)
A16 04034 00000000 (011121)
A17 04036 00000000 (011122)
A18 04038 00000000 (011123)
A19 04040 00000000 (011124)
A20 04042 00000000 (011125)
A21 04044 00000000 (011126)
A22 04046 00000000 (011127)
A23 04048 00000000 (011128)
A24 04050 00000000 (011129)
A25 04052 00000000 (011130)
A26 04054 00000000 (011131)
A27 04056 00000000 (011132)
A28 04058 00000000 (011133)
A29 04060 00000000 (011134)
A30 04062 00000000 (011135)
A31 04064 00000000 (011136)
A32 04066 00000000 (011137)
A33 04068 00000000 (011138)
A34 04070 00000000 (011139)
A35 04072 00000000 (011140)
A36 04074 00000000 (011141)
A37 04076 00000000 (011142)
A38 04078 00000000 (011143)
A39 04080 00000000 (011144)
A40 04082 00000000 (011145)
A41 04084 00000000 (011146)
A42 04086 00000000 (011147)
A43 04088 00000000 (011148)
A44 04090 00000000 (011149)
A45 04092 00000000 (011150)
A46 04094 00000000 (011151)
A47 04096 00000000 (011152)
A48 04098 00000000 (011153)
A49 04100 00000000 (011154)
A50 04102 00000000 (011155)
A51 04104 00000000 (011156)
A52 04106 00000000 (011157)
A53 04108 00000000 (011158)
A54 04110 00000000 (011159)
A55 04112 00000000 (011160)
A56 04114 00000000 (011161)
A57 04116 00000000 (011162)
A58 04118 00000000 (011163)
A59 04120 00000000 (011164)
A60 04122 00000000 (011165)
A61 04124 00000000 (011166)
A62 04126 00000000 (011167)
A63 04128 00000000 (011168)
A64 04130 00000000 (011169)
A65 04132 00000000 (011170)
A66 04134 00000000 (011171)
A67 04136 00000000 (011172)
A68 04138 00000000 (011173)
A69 04140 00000000 (011174)
A70 04142 00000000 (011175)
A71 04144 00000000 (011176)
A72 04146 00000000 (011177)
A73 04148 00000000 (011178)
A74 04150 00000000 (011179)
A75 04152 00000000 (011180)
A76 04154 00000000 (011181)
A77 04156 00000000 (011182)
A78 04158 00000000 (011183)
A79 04160 00000000 (011184)
A80 04162 00000000 (011185)
A81 04164 00000000 (011186)
A82 04166 00000000 (011187)
A83 04168 00000000 (011188)
A84 04170 00000000 (011189)
A85 04172 00000000 (011190)
A86 04174 00000000 (011191)
A87 04176 00000000 (011192)
A88 04178 00000000 (011193)
A89 04180 00000000 (011194)
A90 04182 00000000 (011195)
A91 04184 00000000 (011196)
A92 04186 00000000 (011197)
A93 04188 00000000 (011198)
A94 04190 00000000 (011199)
A95 04192 00000000 (011200)
A96 04194 00000000 (011201)
A97 04196 00000000 (011202)
A98 04198 00000000 (011203)
A99 04200 00000000 (011204)
A00 04202 00000000 (011205)
A01 04204 00000000 (011206)
A02 04206 00000000 (011207)
A03 04208 00000000 (011208)
A04 04210 00000000 (011209)
A05 04212 00000000 (011210)
A06 04214 00000000 (011211)
A07 04216 00000000 (011212)
A08 04218 00000000 (011213)
A09 04220 00000000 (011214)
A10 04222 00000000 (011215)
A11 04224 00000000 (011216)
A12 04226 00000000 (011217)
A13 04228 00000000 (011218)
A14 04230 00000000 (011219)
A15 04232 00000000 (011220)
A16 04234 00000000 (011221)
A17 04236 00000000 (011222)
A18 04238 00000000 (011223)
A19 04240 00000000 (011224)
A20 04242 00000000 (011225)
A21 04244 00000000 (011226)
A22 04246 00000000 (011227)
A23 04248 00000000 (011228)
A24 04250 00000000 (011229)
A25 04252 00000000 (011230)
A26 04254 00000000 (011231)
A27 04256 00000000 (011232)
A28 04258 00000000 (011233)
A29 04260 00000000 (011234)
A30 04262 00000000 (011235)
A31 04264 00000000 (011236)
A32 04266 00000000 (011237)
A33 04268 00000000 (011238)
A34 04270 00000000 (011239)
A35 04272 00000000 (011240)
A36 04274 00000000 (011241)
A37 04276 00000000 (011242)
A38 04278 00000000 (011243)
A39 04280 00000000 (011244)
A40 04282 00000000 (011245)
A41 04284 00000000 (011246)
A42 04286 00000000 (011247)
A43 04288 00000000 (011248)
A44 04290 00000000 (011249)
A45 04292 00000000 (011250)
A46 04294 00000000 (011251)
A47 04296 00000000 (011252)
A48 04298 00000000 (011253)
A49 04300 00000000 (011254)
A50 04302 00000000 (011255)
A51 04304 00000000 (
```

```

A1E B4B36 B8B1046B (B115B) *
A1F B4B38 41A94E4B (B1151) *
A2B B4B3A B8EA8B8B (B1152) *
A21 B4B3C B8EF8B8B (B1153) *
A22 B4B3E B56B8B8B (B1154) *
A23 B4B4B B89B84D1 (B1155) *
A24 B4B4E B8B8462B (B1156) *
A25 B4B4A B8B1B88B (B1157) *
A26 B4B4E 41A94231 (B1158) *
A27 B4B4B B89B888F (B1159) *
A28 B4B4A B8B8B88B (B1160) *
A29 B4B4C B8B8B892 (B1161) *
      (B1162) *
      (B1163) *
      (B1164) *
A2A B4B4E B8EA84EB (B1165) PREZ
A2B B4B5B B8EF82AB (B1166) *
A2C B4B52 B56B8B8B (B1167) *
A2D B4B54 B8B1B88B (B1168) *
A2E B4B5E 41A94F78 (B1169) *
A2F B4B5B B89B8893 (B1170) *
A3J B4B5A 9B1FB82A (B1171) *
      (B1172) *
      (B1173) *
      (B1174) *
      (B1175) *
      (B1176) *
      (B1177) *
      (B1178) *
      (B1179) *
      (B1180) *
      (B1181) *
      (B1182) *
      (B1183) *
      (B1184) *
      (B1185) *
      (B1186) *
A31 B4B5C B8B1B8AF (B1187) *
A32 B4B5E 2E2B2E2B (B1188) *
A33 B4B6B B84FB88B (B1189) *
A34 B4B62 B8BA8B8B (B1190) *
A35 B4B64 B56B84EB (B1191) *
A36 B4B6E 16A816AB (B1192) *
A37 B4B6B B8B8B883 (B1193) *

MOV(P,A1) \ MUL(MB,M7)
ADD(A5,A1) \ SUB(A2,A6)
MOV(IQA,M7) \ NOP
MOV(IQA,M2) \ NOP
MUL(M2,M7) \ MOV(R,M1)
MOV(R,A5) \ MOV(A1),MUL(M1,M6)
NOP \ ADD(A1,A6)
MOV(P,A1) \ MOV(P,A2)
ADD(A5,A1) \ MOV(A1),ADD(A1,A2)
MOV(R,A5) \ MOV(R,M7)
NOP \ MOV(R,M1)
NOP \ MOV(R,A2)

PREDICTOR LOOP

MOV(IQA,M2) \ MUL(M1,M7)
MOV(IQA,M7) \ R(A5)
MUL(M2,M7) \ NOP
MOV(P,A1) \ MOV(P,A1)
ADD(A5,A1) \ MOV(EXO),SUB(A3,A7)
MOV(R,A5) \ MOV(R,A3)
JUMPC(PRE2,T2)

RECIPROCAL PART

REGISTERS USED:
ADM1:
ADM2: A1,EXO

REGISTERS AFFECTED:

ADM1: A1,A3,M2,M6,M7
ADM2: A1,A3,M1,M6,M7

FUNCTIONS: 1/SIZE
          1/(RMS**2)

MOV(EXI,A1) \ MOV(P,M7)
RCPI(A1) \ RCPI(A1)
MOV(EXI,M7) \ NOP
MOV(R,M2) \ MOV(R,M1)
MUL(M2,M7) \ MUL(M1,M7)
K(2) \ K(2)
MOV(P,A3) \ MOV(P,A3)

P2=(1-ALP)*MT
R2=RMS-RMSMIN
-----
M1=R2
P4=R2=ALP
R3=P2+RMSMIN
A2=P4
A1=R3
M7=NEW RMS
M1=NEW RMS
A2=NEW RMS

P=RMS**2
R=SIZE
-----
A1=RMS**2
EXO=SIZE
A3=COUNTER-1

M7=RMS**2
R=/RMS**2+DEL
M1=F#
P2=F#*RMS**2
A3=P2

A1=SIZE
R=1/SIZE+DEL
M7=SIZE
M2=F#
P1=F#*SIZE
A3=P1
```

PAGE 32: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A30 0486A 08314831 (01194)
A39 0486C 080E080E (01195)
A3A 0486E 054084C0 (01196)
A3B 04870 300000AF (01197)
A3C 04872 300000AF (01198)
      (01199) *
      (01200) *
      (01201) *
      (01202) *
      (01203) *
      (01204) *
      (01205) *
      (01206) *
      (01207) *
      (01208) *
      (01209) *
      (01210) *
      (01211) *
      (01212) *
      (01213) *
      (01214) *
      (01215) *
      (01216)
A3D 04874 080E0800 (01217)
A3E 04876 080E0800 (01218)
A3F 04878 04EE4780 (01219)
A40 0487A 16000800 (01220)
A41 0487C 08000800 (01221)
A42 0487E 08F408F1 (01222)
A43 04880 08000800 (01223)
A44 04882 08F408F1 (01224)
A45 04884 08F10800 (01225)
A46 04886 08060800 (01226)
A47 04888 4E290894 (01227)
A48 0488A 080E0800 (01228)
      (01229) *
      (01230) *
      (01231) *
      (01232) *
      (01233) *
      (01234) *
      (01235) *
      (01236) *
      (01237) *

MOV(A1),SUB(A1,A3) \ MOV(A1),SUB(A1,A3) \ R=2-P1
MOV(R,M6) \ MOV(R,M6) \ M6=2-P1
MUL(M2,M6) \ MUL(M1,M6) \ P=FB*(2-P1)
CALL(RCP1) \ CALL SUBROUTINE RCP1
CALL(RCP1)

CALCULATE REDUCED SPEECH

REGISTERS USED:
ADM1:
ADM2: A4,A7

REGISTERS AFFECTED:
ADM1: A0,A1,A4,A6,M1,M5,M6,M7
ADM2: A1,A4,A6,M0,M4,M7

INPUT SEQUENCE: SHAT(K-T),BETA,SMIN,G,NQ,RUNCOUNT,COMPANSATION,S(K),1/2

FUNCTIONS: V(K) = S(K) - BETA * SHAT(K-T)
SAMPLE COUNT = SAMPLE COUNT + 1

MOV(IGA,M7) \ NOP \ M7=SHAT(K-T)
MOV(IGA,M1) \ NOP \ M1=BETA
MOV(M6),MUL(M1,M7) \ ADD(A4,A7) \ M6=1/2*SIZE
K(1) \ MOV(IGA,M0) \
NOP \ MOV(IGA,M7) \
MOV(IGA,A4) \ MOV(IGA,A1) \
NOP \ MOV(IGA,A6) \
MOV(IGA,A0) \ NOP \ A0=COMPANSATION
MOV(P,A6) \ MOV(R,M4) \ A1=S(K)
MOV(M1),SUB(A1,A6) \ MOV(R,A4) \ A6=BETA*SHAT(K-T)
MOV(IGA,M5) \ NOP \ M5=1/2*14

M0=SMIN
M7=G
A1=NQ
A6=RUNLENGTH

QUANTIZER

REGISTERS USED:
ADM1: A0,A2,A4,A5,M1,M5,M6
ADM2: A1,A2,A5,A6,A7,M0,M7

REGISTERS AFFECTED:
ADM1: A1,A2,A3,A4,M1,M2,M7,EX0

```



```

A5C 04002 00004F20 (01282)
A5D 04004 00000200 (01293)
A5E 04006 00510000 (01284)
A5F 04008 00000000 (01285)
A60 0400A 91040007 (01286)
      (01287) *
      (01288) *
      (01289) *
A61 0400C 004A00E9 (01290)
A62 0400E 00EF008E (01291)
A63 0400F 056004CF (01292)
A64 04010 00000300 (01293)
A65 04012 00530051 (01294)
A66 04014 00400000 (01295)
A67 04016 45600320 (01296)
A68 04018 00500000 (01297)
A69 0401A 00930049 (01298)
      (01299) *
A6A 0401C 009C0000 (01300)
A6B 0401E 00000075 (01301)
A6C 04020 490002C0 (01302)
A6D 04022 20202020 (01303)
A6E 04024 00A00000 (01304)
A6F 04026 00090000 (01305)
A70 04028 04A00000 (01306)
A71 0402A 00840000 (01307)
A72 0402C 3A000000 (01308)
A73 0402E 009C0000 (01309)
A74 04030 10000070 (01310)
A75 04032 00840000 (01311)
A76 04034 3A000000 (01312)
A77 04036 009C0000 (01313)
A78 04038 001F0070 (01314)
A79 0403A 420002C0 (01315)
A7A 0403C 00920000 (01316)
A7B 0403E 00F10000 (01317)
A7C 04040 49A00000 (01318)
A7D 04042 00920000 (01319)
A7E 04044 001E0000 (01320)
A7F 04046 20002040 (01321)
      (01322) *
      (01323) *
      (01324) *
      (01325) *

      NOP \ SUB(A1,A7)
      MOV \ MOV(EXO),R(A5)
      MOV(EXT,A1) \ NOP
      NOP \ MOV(R,EXO)
      JUMPS(NEGA,GB)
      ERROR >= B
      MOV(EXT,M2) \ MOV(IGA,M1)
      MOV(IGA,M7) \ MOV(R,M6)
      MUL(M2,M7) \ MOV(M7),MUL(M1,M6)
      MOV(P,EXO) \ MOV(P,EXO)
      MOV(EXT,A3) \ MOV(EXT,A1)
      MUL(M1,M5) \ NOP
      ADD(A3,A5) \ MAX(A1,A3)
      MOV(EXT,EXO) \ MOV(R,A5)
      MOV(R,A3) \ MOV(EXT,M1)
      MOV(R,OQ) \ NOP
      JUMPC(QUAN4,AF3)
      SUB(A4,A1) \ R(A6)
      CLEAR(AF3)
      MOV(P,NULL) \ NOP
      MOV(R,M1) \ NOP
      MUL(M1,M5) \ NOP
      MOV(P,A4) \ NOP
      ALIGN(A4) \ NOP
      MOV(R,OQ) \ MOV(R,A0)
      JUMP(QUAN5)
      MOV(P,A4) \ SUB(A0,A7)
      ALIGN(A4) \ NOP
      MOV(R,OQ) \ MOV(R,A0)
      JUMPC(QUAN5,T2)
      ADD(A0,A2) \ R(A6)
      MOV(R,A2) \ MOV(R,A0)
      MOV(IGA,A1) \ NOP
      SUB(A2,A1) \ NOP
      MOV(R,A2) \ NOP
      JUMPC(ADAP1,T1)
      SET(AF3)
      ADAPTATION
      REGISTERS USED:

      M1=OUT(J)
      M6=STATE VARIABLE(SI)
      M7=P1 P=OUT(J)=SIZE
      EXO=OUT(J)=SIZE
      A1=SIZE=EXP(J)
      P=1/2**14
      OUT(J)=SIZE+PRE
      EXO=+-OUT(J)=SIZE
      A3=VHAT(K)
      OUTPUT VHAT(K)
      JUMP IF Q(L)=1
      CALCULATE L
      CLEAR AF3
      M1=L
      READY TO ALIGN
      OUTPUT L
      A0=RUNCOUNT
      OUTPUT L=1
      DECREMENT A0
      A6=RUNLENGTH
      A0=RUNCOUNT
      JUMP IF NO ENOUGH FOR RUN LENGTH
      COMPASATING
      A1=B(K)
      UPDATE BITCOUNT
      JUMP IF BITCOUNT > B
      SIGNAL END OF PARC

```



```

(01326) *
(01327) *
(01328) *
(01329) *
(01330) *
(01331) *
(01332) *
(01333) *
(01334) *
(01335) *
(01336) *
(01337) *
(01338) *
(01339) *
(01340) *
(01341) *
(01342) *
(01343) *
(01344) *
(01345) *
(01346) *
(01347) ADAP1
(01348)
(01349)
(01350)
(01351) *
(01352)
(01353)
(01354)
(01355)
(01356)
(01357)
(01358)
(01359)
(01360)
(01361)
(01362)
(01363)
(01364)
(01365)
(01366)
(01367) ADAP2
(01368)
(01369)

ADM1: A3,A6
ADM2: A7,M1,M7

REGISTERS AFFECTED:

ADM1: A0,A1,A4,A5,A6,M1,M2,M6
ADM2: A3,M1,M6,M7,EXO

INPUT SEQUENCE: AINV*(1/ALAD-1),ALAD,N-2.5,NULL BITS.
OUTPUT SEQUENCE: SHAT(K-1),A(1),VHAT(K-1)

FLAGS AFFECTED: GB

FUNCTIONS: ERR = G * EHAT(K) / (RMS ** 2)
          A(1) = (A(1) + AINV*(1/ALAD-1)) * ALAD + VHAT(K-1)*ERR
          SHAT(K) = VHAT(K) + BETA*SHAT(K-T)
          OUTPUT SHAT(K) AND A(1)
          A(1) = A(1)*ALAD + VHAT(K-1)*ERR
          OUTPUT A(1)

MOV(IGA,A4) \ NOP
MOV(IGA,M6) \ NOP
NOP \ MOV(IGA,A3)
MOV(IGA,A0) \ NOP

MOV(IGA,A5) \ MUL(M1,M7)
ADD(A5,A4) \ NOP
MOV(M2),ADD(A3,A6) \ MOV(P,M1)
MUL(M2,M6) \ MOV(IGA,M7)
MOV(IGA,M1) \ MUL(M1,M7)
MOV(R,00) \ NOP
MOV(A1),MUL(M1,M6) \ MOV(P,EXO)
MOV(EXT,A6) \ MOV(IGA,M6)
ADD(A6,A1) \ MUL(M1,M6)
CLEAR(G0)
MOV(R,00) \ NOP
MOV(P,A1) \ MOV(P,EXO)
MOV(EXT,A6) \ NOP
ADD(A6,A1) \ NOP
MOV(R,00) \ NOP
MOV(IGA,M1) \ NOP
MUL(M1,M6) \ MOV(IGA,M7)
NOP \ MUL(M1,M7)

;A4=AINV*(1/ALAD-1)
;M6=ALAD
A3=N-2.5
;A0=NULL BIT
;A5=A(1)
;A(1)+A4
;M2=R1
;P2=ALAD*A1
;M1=A(2)
;OUTPUT SHAT(K)
;A1=P2
;A6=VHAT(K-1)*ERR
;R=NEW A(1)
;OUTPUT A(1)
;A1=ALAD*A(2)
;A6=VHAT(K-2)*ERR
;R=NEW A(2)
;OUTPUT A(2)
;M1=A(1)
;P=A(1)*ALAD
M7=VHAT(K-1)
P=VHAT(K-1)*ERR

P1=G*EQ/RMS**2
M1=P1
M7=VHAT(K-1)
P3=VHAT(K-1)*P1
EXO=P3
M6=VHAT(K-2)
P=VHAT(K-2)*ERR
EXO=VHAT(K-2)*ERR
M7=VHAT(K-1)
P=VHAT(K-1)*ERR

```

```

A96 0AC26 00010000 (01370)
A97 0AC28 0056AF60 (01371)
A98 0AC2A 41C00000 (01372)
A99 0AC2C 009C0000 (01373)
A9A 0AC2E 901F0000 (01374)
A9B 0AC30 00000000 (01375)
A9C 0AC32 910000A2 (01376)
A9D 0AC34 90050011 (01377)
A9E 0AC36 40400000 (01378)
A9F 0AC38 00920000 (01379)
AA0 0AC3A 911E00A2 (01380)
AA1 0AC3C 00120000 (01381)
AA2 0AC3E 00000000 (01382)
AA3 0AC40 00000000 (01383)
AA4 0AC42 024000A0 (01384)
AA5 0AC44 0000025C (01385)
AA6 0AC46 009C0000 (01386)
AA7 0AC48 00020000 (01387)
AA8 0AC4A 00000000 (01388)
AA9 0AC4C 00000000 (01389)
AA0 0AC4E 00000000 (01390)
AA1 0AC50 00000000 (01391)
AA2 0AC52 00000000 (01392)
AA3 0AC54 00000000 (01393)
AA4 0AC56 00000000 (01394)
AA5 0AC58 00000000 (01395)
AA6 0AC5A 00000000 (01396)
AA7 0AC5C 00000000 (01397)
AA8 0AC5E 00000000 (01398)
AA9 0AC60 00000000 (01399)
AAA 0AC62 00000000 (01400)
AAB 0AC64 00000000 (01401)
AAC 0AC66 00000000 (01402)
AAD 0AC68 00000000 (01403)
AAE 0AC6A 00000000 (01404)
AAF 0AC6C 00000000 (01405)
AAG 0AC6E 00000000 (01406)
AAH 0AC68 00000000 (01407)
AAI 0AC6A 00000000 (01408)
AAJ 0AC6C 00000000 (01409)
AAK 0AC6E 00000000 (01410)
AAL 0AC68 00000000 (01411)
AAM 0AC6A 00000000 (01412)
AAN 0AC6C 00000000 (01413)

```

MOV(P,A1) \ MOV(P,EXO)  
MOV(EXT,A6) \ SUB(A3,A7)  
ADD(A6,A1) \ NOP  
MOV(R,00) \ MOV(R,A3)  
JUMPC(ADAP2,T2)  
NOP  
END OF PROCESSING ?  
FLAGS SENSED: G1,AF3  
JUMPS(FEND,AF3)  
JUMPC(PRE3,G1)  
NULL MODE  
REGISTERS USED:  
ADM1: A0,A2  
ADM2: A2,A5,A7,M4  
REGISTERS AFFECTED:  
ADM1: A2  
ADM2: M3,EXO  
FLAGS AFFECTED: G1,AF3,RA  
INPUT SEQUENCE: 1/2\*\*15  
OUTPUT SEQUENCE: END CODE,BIT COUNT,RMS,STATE VARIABLE, OF SAMPLES  
FUNCTIONS: IF MORE THAN TWO NULL CODES, SET BIT COUNT = 0  
OTHERWISE UPDATE BITCOUNT  
OUTPUT END CODE, BITCOUNT, RMS, SIZE AND SAMPLE COUNTER  
SUB(A2,A0) \ NOP  
MOV(R,A2) \ NOP  
JUMPS(FEND,T1)  
MOV(ZERO,A2) \ NOP  
NOP \ MOV(IQA,M3)  
NOP \ MUL(M3,M4)  
R(A2) \ NEG(A7)  
NOP \ MOV(OQ),R(A2)  
MOV(R,00) \ MOV(P,EXO)  
MOV(EXT,A2) \ MOV(OQ),R(A5)  
; UPDATE BITCOUNT  
; JUMP IF BITCOUNT < 0  
; RESET BITCOUNT TO SYNC. TRANSMISSIONS  
; M3=1/(2.\*\*15)  
; OUTPUT END CODE  
; OUTPUT BITCOUNT  
; OUTPUT RMS

NOTRE DAME UNIV IN DEPT OF ELECTRICAL ENGINEERING  
DESIGN AND IMPLEMENTATION OF A SPEECH CODING ALGORI  
APR 80 J L MELSA, D L COHN, A ARORA OCA

THM AT 9600 --ETC(U)

APR 80 J L MELSA, D L COHN, A ARORA

DCA100-79-C-0005

ML

3 of 3

AD  
609534

END  
DATE  
FILMED  
8-80  
DTIC



```

(01448) *
(01449) *
(01450) *
(01451)
(01452)
(01453)
(01454)
(01455)
(01456)
(01457)
(01458) *
(01459) *
(01460) *
(01461) *
(01462) *
(01463) *
(01464) *
(01465) *
(01466) *
(01467) *
(01468) *
(01469) *
(01470) *
(01471) *
(01472) *
(01473) *
(01474) *
(01475) *
(01476) *
(01477) *
(01478) *
(01479) *
(01480)
(01481)
(01482)
(01483)
(01484)
(01485)
(01486)
(01487)
(01488)
(01489) *
(01490) *
(01491) *

B4C7C 00004082
B4C7E 0000ACF4
B4C80 0001
B4C81 0100
B4C82 0000AC92

APS MODULE OF PCTX PROGRAM

EVEN
ADDR VPCTXSI
DATA VPCTXS+2*VPCTXS
DATA 1
DATA VPCTXSZ
ADDR VPCTXSA
EVEN

;START ON WORD BOUNDARY
;PTR TO CONSTR INSTR BLOCK
;STARTING ADDR. OF SCALARS
;ONE SCALAR
;SIZE
;CHAIN ANCHOR

THE FOLLOWING REGISTERS ARE PERMANENTLY USED BY THIS PROGRAM

BR1: ADDRESS OF VHAT(K)
BR2: ADDRESS OF S(K-1)
BR3: ADDRESS OF SHAT(K-T-1)
BV0: 1023
BV1: ADDRESS OF SHAT(K-1)
BV2: SD(K+N-1)
BV3: QUANTIZER OUTPUT ADDRESS - 1

INITIALIZATION

REGISTERS AFFECTED: BR0,BR2,BV3

INPUT SEQUENCE: BIT COUNT, BIT BUFFER SIZE, RMS, SIZE, RUN LENGTH,
PITCH REPETITION SIZE

SET(RA)

LOAD(BR0,SVT63S(1),L,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
LOAD(BR0,SVT118S(1),L,TF)
LOAD(BR0,[1])
SUB(BR2,MSS)
SUB(BR0,MSS)
MOVB(BV3,BR0)

;BITCOUNT
;BIT BUFFER SIZE
;RMS
;STATE VARIABLE
;RUN LENGTH
;O-BUFFER LIMIT
;O BUFFER

;
;ADDRESS POINTER OF Q BUFFER - 1

CHECK PITCH REPETITION

```

ADDRESS	INSTR	OPERAND	COMMENT
01492	*		
01493	*		
01494	*		
01495	*		
01496	*		
01497	START		
01498			
01499			
01500			
01501			
01502			
01503			
01504			
01505			
01506			
01507			
01508			
01509			
01510			
01511			
01512			
01513			
01514			
01515			
01516			
01517			
01518			
01519			
01520			
01521			
01522	*		
01523	*		
01524	*		
01525	*		
01526	*		
01527	*		
01528	*		
01529	VLOOP		
01530			
01531			
01532			
01533			
01534			
01535			



PAGE 41: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A47 #4012 9E004CEA (#1500)
A48 #4014 900046A8 (#1501)
A49 #4016 92200028 (#1502)
A4A #4018 940A000A (#1503)
A4B #401A 96004660 (#1504)
A4C #401C 980A000A (#1505)
A4D #401E 9A20002A (#1506)
A4E #4020 9C000010 (#1507)
A4F #4022 9E0A0002 (#1508)
A50 #4024 A0200029 (#1509)
A51 #4026 A20A0002 (#1500)
A52 #4028 A40055E4 (#1591)
A53 #402A A60A0002 (#1592)
A54 #402C A8005660 (#1593)
A55 #402E AA0A0004 (#1594)
A56 #4030 AC110013 (#1595)
A57 #4032 AE910000 (#1596)
A58 #4034 B1310039 (#1597)
A59 #4036 B2C20426 (#1603)
A5A #4038 B40A0002 (#1604)
A5B #403A B60A0002 (#1605)
A5C #403C B80A0002 (#1606)
A5D #403E BA120001 (#1607)
A5E #4040 BC040C00 (#1608)
A5F #4042 BE990000 (#1609)
A60 #4044 C0120001 (#1610)
A61 #4046 C20A0002 (#1611)
A62 #4048 C40E0400 (#1612)
A63 #404A C6090020 (#1613)
A64 #404C C8100011 (#1614)
A65 #404E CA990000 (#1615)
A66 #4050 CC120001 (#1616)
A67 #4052 CE440C00 (#1617)
A68 #4054 D0910011 (#1618)
A69 #4056 D291003A (#1619)
A6A #4058 D4C40C04 (#1620)
A6B #405A D6990000 (#1621)
A6C #405C D891003A (#1622)
A6D #405E DA120001 (#1623)

JUMPS(VQUAN2,AF2)
JUMPC(VQUAN1,AF0)
CLEAR(AFB)
ADD(BR0,10,TF)
JUMP(VQUAN1)
ADD(BR0,10,TF)
CLEAR(AF2)
JUMP(SHIFT)
ADD(BR0,2,TF)
CLEAR(AFI)
ADD(BR0,2,TF)
JUMPS(VNEGA,GB)
ADD(BR0,2,TF)
JUMP(VNEGA+1)
ADD(BR0,4,TF)
MOV8(BV1,BR1)
ANDB(BV1,BV0,TF)
ADDL(BV3,1,TE)

ADAPTION
REGISTERS AFFECTED: BR0,BR1,BV1

LOAD(BR0,SVT79S(1),L,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
SUB(BR1,1)
LOAD(BR0,3072(2),L,TF)
ANDB(BR1,BV0,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
LOAD(BR0,1024(3),S)
ADD(BR0,BR2)
MOV8(BV1,BR0,TF)
ANDB(BR1,BV0,TF)
SUB(BR1,1)
LOAD(BR0,3072(2),L)
MOV8(BV1,BR0,TF)
ADDL(BV1,2,TF)
LOAD(BR0,3076(2),L,TF)
ANDB(BR1,BV0,TF)
ADDL(BV1,2,TF)
SUB(BR1,1)

;ERROR > ALL T(K)
;WAIT FOR SIGNAL
;SEND T(K)
;SEND OUT(J)
;OUT(J)
;EXPN(J)
;B(K)
;VHAT(K) ADDRESS
;L ADDRESS

;AINV*(1/ALAD-1) **
;ALAD
;N-2.5
;NULL BITS
;GET ADDRESS POINTER FOR VHAT BUFFER
;STARTING ADDRESS OF A(I) **

;SHAT(K) ADDRESS
;VHAT(K-2) ADDRESS
;A(1) ADDRESS
;A(2) ADDRESS

```



```

PAGE 42: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

A6E 84068 DC8A8882 (81624) ADD(BR8,2,TF)
A6F 84062 DE998888 (81625) AND8(BR1,8W8,TF)
A78 84064 E891883A (81626) ADDL(BV1,2,TF)
A71 84066 E21A8885 (81627) ADD(BR1,5)
      (81628) *
      (81629) * END OF BUFFER ?
      (81630) *
      (81631) * FLAGS SENSED: G1,AF8,AF3
      (81632) *
A72 84068 E48823E8 (81633) VCHECK JUMPS(VLOOP,AF8)
A73 8406A E68875E8 (81634) JUMPS(VEND,AF3)
A74 8406C E88872A5 (81635) JUMPC(VCHECK,G1)
      (81636) *
      (81637) * END
      (81638) *
      (81639) * REGISTERS AFFECTED: BR8,BV1,8W3
      (81640) *
A75 8406E E8318839 (81641) VEND ADDL(BV3,1,TE)
A76 84078 ECC2842E (81642) LOAD(BR8,SVT83S(1),L,TF)
A77 84072 EE528484 (81643) LOAD(BR1,SVT63S(1),L)
A78 84074 F8918813 (81644) MOV8(BV1,8R1,TF)
A79 84076 F291883C (81645) ADDL(BV1,4,TF)
A7A 84078 F491883A (81646) ADD(BR8,2)
A7B 8407A F68A8882 (81647) MOV8(BV1,8R8,TE)
A7C 8407C F9118811 (81648) CLEAR(R1)
A7D 8407E FA288831 (81649) NOP
A7E 84088 FC888828 (81651) *
      (81652) VPCTXSA=0C
      (81653) *
      (81654) * END
      (81655) *
      (81656) * EVEN
      (81657) *
      (81658) * STORAGE BLOCK FOR CONSTRUCTED INSTRUCTIONS
      (81659) *
      (81660) VPCTXSI DATA IF'B.B'
      (81661) *
      (81662) VPCTXSZ=0L-VPCTXS
      (81663) *
      (81664) * CON3S=0L
      (81665) *
      (81666) * EJECT

```

```

;JUMP IF AF8 SET --- PARC LOOP NOT END
;JUMP IF BITCOUNT < 8
;WAIT FOR SIGNAL

```

```

;OUTPUT END CODE
;1./(2.*15)
;
;BITCOUNT
;RMS
;STATE VARIABLE
;
;# OF SAMPLES

```

```

;CHAIN ANCHOR

```

```

;COMPUTE MODULE SIZE

```

```

(01667) *
(01668) *
(01669) *
(01670) *
(01671) *
(01672) *
(01673) *
(01674) *
(01675) *
(01676) *
(01677) *
(01678) *
(01679) *
(01680) *
(01681) *
(01682) *
(01683) *
(01684) *
(01685) *
(01686) *
(01687) *
(01688) *
(01689) *
(01690) *
(01691) *
(01692) *
(01693) *
(01694) *
(01695) *
(01696) *
(01697) *
(01698) *
(01699) *
(01700) *
(01701) *
(01702) *
(01703) *
(01704) *
(01705) *
(01706) *
(01707) *
(01708) *
(01709) *
(01710) *

```

PITCH EXTRACTION ADAPTIVE RESIDUAL CODER  
P A R C  
RECEIVER

\* DESCRIPTION:

THIS IS A SPEECH CODING PROGRAM IN MAP-300 ARITHMETIC PROCESSOR  
FOR DIGITAL TRANSMISSION OF SPEECH AT A RATE OF 9600 BITS PER SECOND.  
THE ALGORITHM COMBINES PITCH EXTRACTION LOOP, PITCH COMPENSATING  
ADAPTIVE QUANTIZER, SEQUENTIALLY ADAPTIVE PREDICTOR.

1. THE SEQUENTIALLY ADAPTIVE PREDICTOR USING BACKWARD ADAPTION  
IS USED TO FORM AN ESTIMATE OF PITCH REDUCED SIGNAL.
2. THE ERROR OF THIS ESTIMATE IS RECONSTRUCTED BY INVERSE QUANTIZER.
3. THE REDUNDANCE OF THE CURRENT SAMPLE IS CALCULATED BY PITCH  
EXTRACTION LOOP.
4. THE RECONSTRUCTED SPEECH IS THE SUM OF THIS ERROR, THE ESTIMATE  
AND THE REDUNDANCE.

\* SYMBOLIC ABBREVIATIONS:

SHSRC --- THE LOCATION OF SHAT POINTER  
TSRC --- THE LOCATION OF PITCH PERIOD FOR RECEIVER  
VHSRC --- THE LOCATION OF WHAT POINTER  
INSRC --- THE LOCATION OF (PITCH REPETITION SIZE - 1)

\* BUFFERS:

1. Q BUFFER: IT CONTAINS INPUT QUANTIZING LEVELS.  
--- IN 16-BIT INTEGER\*2 FORMAT --- DOUBLE BUFFERS ---
2. WHAT BUFFER: IT CONTAINS RECONSTRUCTED REDUCED SPEECH.  
--- CIRCULAR BUFFER --- IN SHORT-REAL FORMAT ---
3. SHAT BUFFER: IT CONTAINS RECONSTRUCTED SPEECH.  
--- CIRCULAR BUFFER --- IN SHORT-REAL FORMAT ---
4. ADM BUFFER: IT CONTAINS UPSAMPLED SHAT DATA.  
--- DOUBLE BUFFER --- SHORT REAL FORMAT ---
5. PARAMETER BUFFER: IT CONTAINS THE PARAMETERS FOR INVERSE QUANTIZER.  
SEQUENCE : A(8),(ENPN(J),OUT(J)) --- IN LONG-REAL FORMAT ---

\* RESTRICTION:

1. THE ORDER OF THE PREDICTOR IS 4.
2. INITIALLY, THE SHAT BUFFER SHOULD BE IN FULL CONDITION.
3. THE LOCATIONS OF SOME ARRAYS ARE AS FOLLOWS:

SHAT BUFFER --- 2848(2) ... 3871(2)  
 VBAT BUFFER --- 2848(3) ... 3871(3)  
 AOM BUFFER --- 3584(2)-4895(2)  
 PARAMETER BUFFER --- 4896(2) ...  
 WHERE QUANTIZER LEVELS ARE DEFINED AS FOLLOWS:  
 FROM LOWEST ..... TO ..... HIGHEST  
 Q(N),Q(N-1),...,Q(N/2+2),Q(1),Q(2),...,Q(N/2+1)

\* CALL TO THIS FUNCTION:

MAP = PCRC(SA,U,V)  
 WHERE SA --- SCALAR LOCATION OF ENCD. BETA  
 U --- BUFFER # FOR INPUT Q BUFFER  
 V --- AOM BUFFER #

DISPATCH TABLE ENTRY

FCB243=243  
 #L=AFDTs\*3\*2\*(FCB243-128)  
 ADDR PCRCs(R7,1)  
 ADDR VPCRCs(R7,1)  
 ADDR CSPUSNOS(1,8)  
 APU & APS MODULE  
 #L=CON3S  
 APU MODULE  
 EVEN PCRCSSA  
 DATA PCRCSSZ  
 BEGIN APU(PCRC)  
 #M=3  
 #A=8

:FCB=243  
 :STARTING LOCATION OF AFDT FOR 243  
 :APU=PCRC  
 :APS=VPCRC  
 :NO CSPU SUPPORT  
 :START ON WORD BOUNDARY  
 :STARTING ADDRESS  
 :SIZE  
 :START OF APU MODULE

(81711) \*  
 (81712) \*  
 (81713) \*  
 (81714) \*  
 (81715) \*  
 (81716) \*  
 (81717) \*  
 (81718) \*  
 (81719) \*  
 (81720) \*  
 (81721) \*  
 (81722) \*  
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 (81749) \*  
 (81750) \*  
 (81751) \*  
 (81752) \*  
 (81753) \*  
 (81754) \*

888888F3  
 8888889A

8889A 881E4D86  
 8889C 881E4EC2  
 8889E 881821FC

88884D84

84D84 8888  
 84D85 889A

88888883  
 88888888

```

PAGE 45: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

(01755) *
(01756) *
(01757) *
(01758) *
(01759) *
(01760) *
(01761) *
(01762) *
(01763) *
(01764) PCRCSSA K(0.5)
A00 04D86 16601600 MOV(10A,A5) \ NOP
A01 04D88 08F50000 MOV(10A,A6) \ NOP
A02 04D8A 08F60000 MOV(M1),K(1)
A03 04D8C 16891600 MOV(10A,A2) \ NOP
A04 04D8E 08F20000 MOV(10A,A3) \ NOP
A05 04D90 08F00000 MOV(A7),MIN(A5,A6) \ MOV(R,A7)
A06 04D92 6D170000 MOV(A7),MAX(A5,A6) \ MOV(R,A7)
A07 04D94 66100000 MOV(10A,A1) \ NOP
A08 04D96 08F10000 MIN(A1,A5) \ NOP
A09 04D98 6D200000 MOV(A1),MAX(A1,A6) \ NOP
A0A 04D9A 66310000 MOV(R,EX0) \ NOP
A0B 04D9C 08980000 MOV(A1),ADD(A5,A1) \ NOP
A0C 04D9E 41110000 MOV(R,M7) \ MOV(EX1,EX0)
A0D 04DA0 08F00000 MUL(M1,M7) \ NOP
A0E 04DA2 84E00000 SUB(A2,A7) \ NOP
A0F 04DA4 4F000000 MOV(EX1,A5) \ NOP
A10 04DA6 08500000 MOV(P,00) \ NOP
A11 04DA8 088C0000 MOV(R,A2) \ MOV(EX1,00)
A12 04DAA 08920000 JUMPC(TRAN,T1)
A13 04DAC 901E0000

INITIALIZATION
(01785) *
(01786) *
(01787) *
(01788) *
(01789) *
(01790) *
(01791) *
(01792) *
(01793) *
(01794) *
(01795) *
(01796) *
(01797) *
(01798) *

REGISTERS AFFECTED:
ADM1: A0,A1,A2,M0,M1,M3,M5,M6,M7
ADM2: A0,A2,A3,A4,A6,A7,M0,M2,M6

INPUT SEQUENCE: ENCD,BETA,RMS,STATE VARIABLE,UB*2**15/HL,RMSMIN,N-2.5
ALAD,SMIN,UB,G,1-ALP,ALP,AINV*(1/ALAD-1),2**14,PITCH REP

ADM1 *****
ADM2 *****
ADM1 *****
ADM2 *****

MOV(10A,A1) \ NOP
;A1=ENCD. BETA

DATA TRANSFER FROM SHAT BUFFER TO ADM BUFFER

REGISTERS USED:
ADM1: A0,A1,A2,A5,A6,A7,M1,M7,EX0
ADM2: A0,A1,A7,M1,M7,EX0

INPUT SEQUENCE: 2047/16**3,-2048/16**3,TRANSFER SIZE/2-0.5,SHAT(K-1),SHA
OUTPUT SEQUENCE: (SHAT(K-1)*SHAT(K))/2,SHAT(K)

;A5=2047/(16**3)
;A6=-2048/(16**3)
;A2=TRANSFER SIZE/2-0.5
;SHAT(K-1)
;LIMITING
;LIMITING

;LOOPING

```

PAGE 44:

MAP MODULES FOR THE P A R C ALGORITHM

--- JAN. 38, 1988

```

(01711) *
(01712) *
(01713) *
(01714) *
(01715) *
(01716) *
(01717) *
(01718) *
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(01723) *
(01724) *
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(01739) *
(01740) *
(01741) *
(01742) *
(01743) *
(01744) *
(01745) *
(01746) *
(01747) *
(01748) *
(01749) *
(01750) *
(01751) *
(01752) *
(01753) *
(01754) *

      * RESTRICTION:
      1. THE ORDER OF THE PREDICTOR IS 4.
      2. INITIALLY, THE SHAT BUFFER SHOULD BE IN FULL CONDITION.
      3. THE LOCATIONS OF SOME ARRAYS ARE AS FOLLOWS:
          SHAT BUFFER --- 2048(2) ... 3071(2)
          VBAT BUFFER --- 2048(3) ... 3071(3)
          AOM BUFFER --- 3584(2)-4095(2)
          PARAMETER BUFFER --- 4096(2) ...
          WHERE QUANTIZER LEVELS ARE DEFINED AS FOLLOWS:
          FROM LOWEST ..... TO ..... HIGHEST
          Q(N),Q(N-1),...,Q(N/2+2),Q(1),Q(2),...,Q(N/2+1)

      * CALL TO THIS FUNCTION:
          MAP = PCRC(SA,U,V)
          WHERE SA --- SCALAR LOCATION OF ENCD. BETA
                U --- BUFFER # FOR INPUT Q BUFFER
                V --- AOM BUFFER #

DISPATCH TABLE ENTRY
FCB243=243
#L=AFDTS+3*2*(FCB243-128)
ADDR PCRC(R7,1)
ADDR VPCRC(R7,1)
ADDR CSPUSNOS(1,8)
APU & APS MODULE
#L=CON3S
APU MODULE
EVEN PCRCSSA
DATA PCRCSSZ
DATA PCRCSSZ
BEGIN APU(PCRC)
#N=3
#A=0
PCRC
(01751) PCRC
(01752)
(01753)
(01754)

      * START ON WORD BOUNDARY
      * STARTING ADDRESS
      * SIZE
      * START OF APU MODULE

```











```

PAGE 58:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 38, 1988

A86 84E92 888832A8 (81975)
A87 84E94 8888888F (81976)
A88 84E96 88888888 (81977)
A89 84E98 88888285 (81978)
A8A 84E9A 88888888 (81979)
A8B 84E9C 88888885 (81980)
A8C 84E9E 881F882C (81981)
      (81982) *
      (81983) *
      (81984) *
      (81985) *
      (81986) *
      (81987) *
      (81988) *
      (81989) *
      (81990) *
      (81991) *
      (81992) *
      (81993) *
      (81994) *
      (81995)
A8D 84EAB 28882848 (81995)
A8E 84EA2 88888888 (81996)
A8F 84EA4 88888888 (81997)
A90 84EA6 82888248 (81998)
A91 84EA8 889C889C (81999)
A92 84EAA 88888882 (82000)
A93 84EAC 88883A48 (82001)
A94 84EAE 8888889C (82002)
A95 84EB0 28322832 (82003)
A96 84EB2 88888888 (82004)
A97 84EB4 18888888 (82005)
      (82006) *
A98 84EB6 28492849 (82007) SIGNAL
A99 84EB8 18888885 (82008)
      (82009) *
      (82010)
      (82011)
      (82012) *
      (82013)
      84E8A

NOP \ NORM(A5)
NOP \ MOV(R,M7)
NOP \ MUL(M2,M7)
NOP \ MOV(A5),R(A5)
NOP \ MOV(R,NULL)
NOP \ MOV(P,A5)
JUMPC(PRE,T2)

END OF RECEIVER

FLAGS AFFECTED: AF3,RA

REGISTERS AFFECTED:

ADM1:
ADM2: A2,M3

INPUT SEQUENCE: 1/2**15
OUTPUT SEQUENCE: STATE VARIABLE,RMS,0 OF SAMPLES

SET(AF3)
NOP \ MOV(IGA,M3)
NOP \ MUL(M3,M4)
R(A4) \ R(A2)
MOV(R,OQ)
NOP \ MOV(P,A2)
NOP \ ALIGN(A2)
NOP \ MOV(R,OQ)
CLEAR(RA)
NOP
JUMP(B)

      (81975)
      (81976)
      (81977)
      (81978)
      (81979)
      (81980)
      (81981)
      (81982)
      (81983)
      (81984)
      (81985)
      (81986)
      (81987)
      (81988)
      (81989)
      (81990)
      (81991)
      (81992)
      (81993)
      (81994)
      (81995)
      (81996)
      (81997)
      (81998)
      (81999)
      (82000)
      (82001)
      (82002)
      (82003)
      (82004)
      (82005)
      (82006)
      (82007)
      (82008)
      (82009)
      (82010)
      (82011)
      (82012)
      (82013)

      M7=L
      CHECK END CODE
      A5=L
      JUMP IF NOT END CODE

      SIGNAL APS END OF RECEIVER
      M3=1./(2.**15)
      STATE VARIABLE
      RMS
      OUTPUT 0 OF SAMPLES
      CONTINUE

      SIGNAL APS NO PITCH REPETITION
      COMPUTE THE SIZE OF THIS MODULE

EJECT

```



PAGE 52: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A13 04EE0 27620000 (02058) * VPCRCSS LOAD(BR2,MSS(1),L,TE)
A14 04EEA 280A0002 (02059) *
A15 04EEC 280A0002 (02060) *
A16 04EEE 2C8A0002 (02061) *
A17 04EF0 2E8A0002 (02062) *
A18 04EF2 308A0002 (02063) *
A19 04EF4 328A0002 (02064) *
A20 04EF6 348A0002 (02065) *
A21 04EF8 368A0002 (02066) *
A22 04EFA 388A0002 (02067) *
A23 04EFB 3A8A0002 (02068) *
A24 04EFC 3C8A0002 (02069) *
A25 04EFD 3E8A0002 (02070) *
A26 04EFE 408A0002 (02071) *
A27 04EFF 428A0002 (02072) *
A28 04F00 448A0002 (02073) *
A29 04F02 468A0002 (02074) *
A30 04F04 488A0002 (02075) *
A31 04F06 4A8A0002 (02076) *
A32 04F08 4C8A0002 (02077) *
A33 04F0A 4E8A0002 (02078) *
A34 04F0C 508A0002 (02079) *
A35 04F0E 528A0002 (02080) *
A36 04F10 548A0002 (02081) *
A37 04F12 568A0002 (02082) *
A38 04F14 588A0002 (02083) *
A39 04F16 5A8A0002 (02084) *
A40 04F18 5C8A0002 (02085) *
A41 04F1A 5E8A0002 (02086) *
A42 04F1C 608A0002 (02087) *
A43 04F1E 628A0002 (02088) *
A44 04F20 648A0002 (02089) *
A45 04F22 668A0002 (02090) *
A46 04F24 688A0002 (02091) *
A47 04F26 6A8A0002 (02092) *
A48 04F28 6C8A0002 (02093) *
A49 04F2A 6E8A0002 (02094) *
A50 04F2C 708A0002 (02095) *
A51 04F2E 728A0002 (02096) *
A52 04F30 748A0002 (02097) *
A53 04F32 768A0002 (02098) *
A54 04F34 788A0002 (02099) *
A55 04F36 7A8A0002 (02100) *
A56 04F38 7C8A0002 (02101) *
A57 04F3A 7E8A0002 (02102) *
A58 04F3C 808A0002 (02103) *
A59 04F3E 828A0002 (02104) *
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A487 04FB6 BA8A0002 (02532) *
A488 04FB8 BC8A000
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PAGE 53: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

A2A 84F16 548834E9 (82182) *
A2B 84F18 56882AA7 (82183) *
A2C 84F1A 58488838 (82184) *
A2D 84F1C 5A3A8881 (82185) *
A2E 84F1E 5C318839 (82186) *
A2F 84F20 5E398888 (82187) *
A30 84F22 6889882A (82188) *
A31 84F24 62318888 (82189) *
A32 84F26 6481882A (82190) *
A33 84F28 66892D81 (82191) *
A34 84F2A 68288829 (82192) *
A35 84F2C 6A5E8888 (82193) *
A36 84F2E 6C887868 (82194) *
A37 84F30 6EC41888 (82195) *
A38 84F32 70288828 (82196) *
A39 84F34 72128881 (82197) *
A3A 84F36 74198888 (82198) *
A3B 84F38 7699882A (82199) *
A3C 84F3A 78128881 (82200) *
A3D 84F3C 7A8A8882 (82201) *
A3E 84F3E 7C198888 (82202) *
A3F 84F40 7E99882A (82203) *
A40 84F42 88128881 (82204) *
A41 84F44 828A8882 (82205) *
A42 84F46 84198888 (82206) *

; JUMP IF NO PITCH REPETITION
; WAIT FOR APU SIGNAL
; INIT PITCH REPETITION SIZE
; PITCH REPETITION SIZE
;
; SHAT(K-T)
; SHAT(K)
;
; LOOPING

; JUMPS(COUNT,AF1)
; JUMPC(BWAIT,G3)
; INSRC-0L+1
; LOAD(BR3,59)
; ADD(BR3,1)
; ADDL(BW3,1)
; AND8(BR3,BW8)
; ADD8(BR3,BW1,TF)
; AND8(BW3,BW8)
; ADD8(BW3,BW1,TF)
; SUBL(BR3,1),JUMPP(VLOP1)

INITIALIZATION

REGISTERS AFFECTED: BR1

FLAGS AFFECTED: AF1

CLEAR(AF1)
VHSRC-0L+1
LOAD(BR1,2848(3),S)
JUMP(ENDCK)

PRODUCING ADDRESSES FOR PREDICTOR WITH CIRCULAR BUFFER

REGISTERS AFFECTED: BR0,BR1

FLAGS AFFECTED: AF0

LOAD(BR0,4896(2),L,TF)
CLEAR(AF0)
SUB(BR1,1)
AND8(BR1,BW8)
ADD8(BR1,BW1,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
AND8(BR1,BW8)
ADD8(BR1,BW1,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
AND8(BR1,BW8)

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PAGE 54: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

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A45 04F4C 00A00002 (02148)
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A47 04F50 0E99002A (02150)
A48 04F52 001A0004 (02151)
A49 04F54 02190000 (02152)
A4A 04F56 0419002A (02153)
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      (02176) *
      (02177) *
      (02178) *
      (02179) *
      (02180) *
      (02181) *
      (02182) *
      (02183) *
      (02184) *
      (02185) *
      (02186) *
      (02187) *
      (02188) *
      (02189) *

A48 04F58 0644100A (02164)
A4C 04F5A 000001E9 (02165)
A4D 04F5C 0A004C08 (02166)
A4E 04F5E 0C200028 (02167)
A4F 04F60 0E0A0004 (02168)
A50 04F62 00004C60 (02169)
A51 04F64 020A0002 (02170)
A52 04F66 04200029 (02171)
A53 04F68 060A0002 (02172)
      (02173) *
      (02174) *
      (02175) *
      (02176) *
      (02177) *
      (02178) *
      (02179) *
      (02180) *
      (02181) *
      (02182) *
      (02183) *
      (02184) *
      (02185) *
      (02186) *
      (02187) *
      (02188) *
      (02189) *

A54 04F6A 003A0001 (02178)
A55 04F6C 0A390000 (02179)
A56 04F6E 0C09002A (02180)
A57 04F70 0E010013 (02181)
A58 04F72 00310039 (02182)
A59 04F74 02310000 (02183)
A5A 04F76 0401002A (02184)
      (02185) *
      (02186) *
      (02187) *
      (02188) *
      (02189) *

      ADD8(BR1,BV1,TF)
      SUB(BR1,1)
      ADD(BR0,2,TF)
      AND8(BR1,BV0)
      ADD8(BR1,BV1,TF)
      ADD(BR1,4)
      AND8(BR1,BV0)
      AND8(BR1,BV1)

      PRODUCING ADDRESSES FOR QUANTIZER

      CONTROLLED BY HANDSHAKE SIGNAL (AF0,AF1) FROM APU PROGRAM

      REGISTERS AFFECTED: BR0

      FLAGS AFFECTED: AF0,AF1
      FLAGS SENSED: AF0,AF1

      LOAD(BR0,4106(2),L)
      JUMPS(VQ3,AF1)
      JUMPC(VQ1,AF0)
      CLEAR(AF0)
      ADD(BR0,4)
      JUMP(VQ1)
      ADD(BR0,2,TF)
      CLEAR(AF1)
      ADD(BR0,2,TF)

      ADDRESSES OF SHAT(K-T),VHAT(K),SHAT(K)

      REGISTERS AFFECTED: BR3,BV2,BV3

      ADD(BR3,1)
      AND8(BR3,BV0)
      ADD8(BR3,BV1,TF)
      MOV8(BV2,BR1,TF)
      ADDL(BV3,1)
      AND8(BV3,BV0)
      ADD8(BV3,BV1,TF)

      ADAPTION

      USING CIRCULAR BUFFER

      ;ADDRESS OF EXPN(1) -6
      ;FIND CORRESPONDING QUANTIZING LEVEL
      ;WAIT FOR SIGNAL
      ;
      ;EXPN(3)
      ;OUT(3)
      ;SHAT(K-T)
      ;VHAT(K)
      ;
      ;SHAT(K)

```

PAGE 55: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(02190) *
(02191) *
A58 04F70 06C41000 (02192) VADAP
A5C 04F7A 00120001 (02193)
A5D 04F7C 00190000 (02194)
A5E 04F7E 0C90002A (02195)
A5F 04F80 0EA10011 (02196)
A60 04F82 00120001 (02197)
A61 04F84 020A0002 (02198)
A62 04F86 04190000 (02199)
A63 04F88 0690002A (02200)
A64 04F8A 00A1003A (02201)
A65 04F8C 0A120001 (02202)
A66 04F8E 0C0A0002 (02203)
A67 04F90 0E190000 (02204)
A68 04F92 0090002A (02205)
A69 04F94 02A1003A (02206)
A6A 04F96 04120001 (02207)
A6B 04F98 060A0002 (02208)
A6C 04F9A 00190000 (02209)
A6D 04F9C 0A90002A (02210)
A6E 04F9E 0CA1003A (02211)
A6F 04FA0 0E1A0005 (02212)
(02213) *
(02214) *
(02215) *
(02216) *
(02217) *
(02218) *
(02219) *
A70 04FA2 E12A0001 (02220) ENDCK
A71 04FA4 E2000020 (02221) VLOP2
A72 04FA6 E40037E0 (02222)
A73 04FA8 E60071A0 (02223)
(02224) *
(02225) *
(02226) *
(02227) *
(02228) *
(02229) *
(02230) *
A74 04FAA E8020464 (02231)
A75 04FAC EA200020 (02232)
A76 04FAE EC42044A (02233)

REGISTERS AFFECTED: BR0,BR1,BV2
LOAD(BR0,4096(2),L,TF) ; STARTING ADDRESS OF A(1)
SUB(BR1,1) ;
ANDB(BR1,BV0) ;
ADDR(BR1,BV1,TF) ; OUTPUT A(1)
MOVB(BV2,BR0,TF) ;
SUB(BR1,1) ;
ADD(BR0,2,TF) ;
ANDB(BR1,BV0) ;
ADDR(BR1,BV1,TF) ;
ADDL(BV2,2,TF) ;
SUB(BR1,1) ;
ADD(BR0,2,TF) ;
ANDB(BR1,BV0) ;
ADDR(BR1,BV1,TF) ;
ADDL(BV2,2,TF) ;
SUB(BR1,1) ;
ADD(BR0,2,TF) ;
ANDB(BR1,BV0) ;
ADDR(BR1,BV1,TF) ;
ADDL(BV2,2,TF) ;
ADD(BR1,5) ;
END OF RECEIVER ?
REGISTERS AFFECTED: BR2
FLAGS SENSED: AF0,AF3
ADD(BR2,1,TE) ; INPUT L
NOP ;
JUMPS(VPRE1,AF0) ; JUMP IF NOT FINISH
JUMPC(VLOP2,AF3) ; WAIT FOR APU SIGNAL
END OF RECEIVER ?
REGISTERS AFFECTED: BR0,BV3
FLAGS AFFECTED: AF3
LOAD(BR1,SVT111S(1),L,TF) ; 1./(2.**15)
CLEAR(AF3) ;
LOAD(BR0,SVT99S(1),L) ;

```

```

PAGE 56:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

A77 04F80 EEB10011 (02234)      MOV8(BV3,BR,TF)      ;STATE VARIABLE
A78 04F82 F0B10032 (02235)      SUBL(BV3,2,TF)      ;RMS
A79 04F84 F21A0002 (02236)      ADD(BR1,2)      ;# OF SAMPLES
A7A 04F86 F5310013 (02237)      MOV8(BV3,BR1,TE)
A7B 04F88 F6200031 (02239)      CLEAR(RI)
A7C 04F8A F8000020 (02239)      NOP
A7D 04F8C FAD00060 (02240)      JUMP(B)
      (02241)
      (02242) VPCRCSA=0C      ;CHAIN ANCHOR
      (02243)
      (02244)      END
      (02245)      EVEN
      (02246)
      (02247)
      (02248)      STORAGE BLOCK FOR CONSTRUCTED INSTRUCTIONS
      (02249)
      (02250) VPCRC51 DATA 2F'0.0'
      ...
      (02251)
      (02252) VPCRC52=0L-VPCRC5      ;COMPUTE MODULE SIZE
      (02253)
      (02254)      TOP OF EXEC
      (02255)
      (02256)      TOES=0L
      (02257)      0L=TOESPR
      (02258)      ADDR      TOES(.BUS1S)
      (02259)      END
      (02260)
      (02261)      EVEN
      (02262)      EJECT

```



PAGE 57: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

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(02302) *
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(02304) *
(02305) *
(02306) *

```

ARVIND S. ARORA

NAME: ENCLS FCB: 110

THIS PROGRAM TAKES A BLOCK OF QUANTIZER OUTPUTS FROM THE PARC ALGORITHM AND ENCODES THEM INTO A BIT STREAM FOR DIGITAL TRANSMISSION. EACH OUTPUT BLOCK HAS 189 BITS CONSISTING OF 1 SYNC BIT, 6 BITS FOR T, 7 BITS FOR BETA, 7 BITS FOR 'PHONEY' BETA IF APPLICABLE, 18 BITS FOR PARITY CHECK, AND THE REST (157 BITS) FOR QUANTIZER OUTPUT INFORMATION.

#### ENCODER CONSTRAINTS:

```

(02285) * 1. THE NUMBER OF QUANTIZER OUTPUTS IN THE INPUT BUFFER MUST GENERATE NO
(02286) * MORE THAN 196 BITS.
(02287) * 2. NONE OF THE BUFFERS IN THIS PROGRAM MUST OCCUPY MEMORY LOCATIONS
(02288) * HIGHER THAN 32K.
(02289) * 3. THERE ARE SEVERAL CONSTRAINTS ON THE SOURCE CODE:
(02290) * 1. THE CODE FOR LEVEL 1 IS 0.
(02291) * 2. THE CODE FOR 'PHONEY' BETA IS 000,000.
(02292) * 3. RUN LENGTH IS FIXED AT 14. (UNLESS LOCATION LSRUN IS MODIFIED)
(02293) * 4. THE CODE 111,111 IS AN ALTERNATE NULL CODE.
(02294) * 5. BECAUSE THE LSB OF THE CODE-WORD IS TRANSMITTED FIRST, THE RECEIVER
(02295) * GETS AN INVERTED CODE, EG. 110 --> 011. TO COMPENSATE FOR THIS,
(02296) * THE ENCODING TABLE MUST CONTAIN INVERTED CODES, RIGHT JUSTIFIED.
(02297) * 6. LOCATION 0 IN THE ENCODING TABLE CONTAINS THE CODE FOR RUN LENGTH.
(02298) * 7. LOCATION 2*12 IN THE ENCODING TABLE CONTAINS THE CODE FOR NULL CODE.
(02299) * 8. ALTHOUGH THE CODES FOR Q-LEVELS ARE INVERTED BY THE ALGORITHM, THE
(02300) * CODES FOR T, BETA, 'PHONEY' BETA ARE NOT.
(02301) * 9. THE VARIOUS INPUTS TO THIS PROGRAM NEED TO BE PROVIDED IN THE
(02302) * FOLLOWING FORMATS:
(02303) * 1. Q-LEVELS N*2 FIXED FORMAT (ENCODED T)
(02304) * 2. T 0<T<63 FIXED FORMAT (ENCODED T)
(02305) * 3. BETA 0<BETA<96 FIXED FORMAT (ENCODED BETA)
(02306) * 4. 'PHONEY' BETA -VE NO. FIXED FORMAT

```

PAGE 58: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

FIXED FORMAT

-VE 12

(#2307) ; 5. END CODE

(#2308) ;

(#2309) ;

(#2310)

EJECT

```

(02311) ;
(02312) ;
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(02353) ;
(02354) ;

```

THE FUNCTION CONTROL BLOCK IS AS FOLLOWS:

```

-----
|                                     |
| FCB # 110 | ISTB |
|-----|-----|
| OUTB | QHAT |
|-----|-----|
| BETA (TABLE) | ENCT (TABLE) |
|-----|-----|
| SCAL ID(RC UPDATE) |
|-----|
| INT SC ID(RC UPD) |
|-----|

```

\*\*\* NOTE: ENABLE LINES WITH \* IN COL. 1 TO ASSEMBLE THIS PROGRAM BY ITSELF.

--- SYMBOL DEFINITION TO INTERFACE WITH SNAP-11 EXEC. REL 3.05

```

BCTSBA=$502
FDT$UFCB=$8C4
ISVTS=$502
SVSSFLG=$1FFCE
TOESOLD=$5000
TOESPTR=$200
SVTS=$302
--- TOP OF MEMORY POINTER
*OL=TOESPTR
ADDR TOESNEW(,1)
--- DISPATCH TABLE ENTRIES
*OL=FDT$UFCB
ADDR ENCD$

```

PAGE 68: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

```

(2355) ;
(2356) ;---- CSPU MODULE FOR THE ENCODER
(2357) ;
(2358) ;OL=TOESOLD
(2359) ;---- I. BASE ADDRESS FOR 4 BUFFERS AND INDEX FOR T.BETA
(2360) ;
(2361) ;---- INDEX FOR T.BETA
(2362) ;
(2363) ENCD5 MOVW R2,R1,S0FF ;SID FOR T.BETA
(2364) MOVW R2,I1D5TB ;SAVE IN LOC I1D5TB
(2365) ;
(2366) ;---- UPDATE RECEIVER
(2367) ;
(2368) ; CALL R7,RCS
(2369) ;
(2370) ;---- ADDRESS FOR QHAT
(2371) ;
(2372) ;
(2373) ; INCR R1,1
(2374) MOVW R6,R1,S0FF ;BID FOR QHAT
(2375) CALL .BASES ;SUBROUTINE TO RETRIEVE BASE ADDR.
(2376) MOVW R4,ADSOHAT ;SAVE IN LOC ADSOQAT
(2377) ;
(2378) ;---- ADDRESS FOR OUTB
(2379) ;
(2380) MOVW R6,R1
(2381) LRS R6,8 ;BID FOR OUTB
(2382) CALL .BASES ;SUB. TO GET BASE ADDR.
(2383) MOVW R4,ADSOHAT ;SAVE IN LOC ADSOQAT
(2384) ADDR R5,S0FFD ;BASE ADDR + 189
(2385) MOVW R4,ADSOHAT ;SAVE IN LOC ADSOQAT
(2386) ;
(2387) ;---- ADDRESS FOR ENCT, INDEXED BY R1
(2388) ;
(2389) ; INCR R1,1
(2390) MOVW R6,R1,S0FF ;BID FOR ENCT
(2391) CALL .BASES ;SUBROUTINE TO GET BASE ADDR.
(2392) IORIR R4,S0FF2 ;INSERT INDEX REG.1
(2393) MOVW R4,ADSENCT ;SAVE IN LOC ADSENCT
(2394) ;
(2395) ;---- ADDRESS FOR BETA, INDEXED BY R1
(2396) ;
(2397) MOVW R6,R1

```

PAGE 61: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

BID FOR BETA  
SUBROUTINE TO GET BASE ADDR.  
INSERT INDEX REG 1  
SAVE IN LOC ADSBETA

--- II. INITIALIZE H-INDEX(R6), PARITY WORD(R7)

LR5 R6.8  
CALL .BASES  
IORIR R4,\$0002  
MOVRML R4,ADSBETA  
R6=1  
R7=0

--- III. SYNC BIT; VSSYN

CCR R5  
XORMR R5,VSSYN  
JMP ENS30,GEZ  
MOVIR R1,\$0001  
XORRR R7,R6  
SKP 0  
CLR R1  
MOVIR R1,0ADSOUTB  
MOVIR R5,VSSYN  
INCR R6,1  
INCM ADSOUTB+1

--- IV. OUTPUT T (MSB FIRST)

MOVIR R1,IIDSTB  
LLS R1,1  
MOVIR R5,SVTS(R1)  
MOVIR R4,\$0005  
R1  
5,R5  
R1,1  
R7,R6  
MOVIR R1,0ADSOUTB  
INCR R6,1  
INCM ADSOUTB+1  
LLS R5,1  
DJP R4,ENS40

--- V. CHECK FOR PHONEY BETA AND OUTPUT (MSB FIRST)

MOVIR R5,0ADSCHAT  
GET PHONEY BETA WORD

04FE3 3C68 (02398)  
04FE4 860050FF (02399)  
04FE6 96400002 (02400)  
04FE8 8440510C (02401)  
04FEA 98600001 (02402)  
04FEC 8D70 (02403)  
04FE4 98600001 (02404)  
04FEC 8D70 (02405)  
04FE4 98600001 (02406)  
04FEC 8D70 (02407)  
04FE4 98600001 (02408)  
04FEC 8D70 (02409)  
04FE4 98600001 (02410)  
04FEC 8D70 (02411)  
04FE4 98600001 (02412)  
04FEC 8D70 (02413)  
04FE4 98600001 (02414)  
04FEC 8D70 (02415)  
04FE4 98600001 (02416)  
04FEC 8D70 (02417)  
04FE4 98600001 (02418)  
04FEC 8D70 (02419)  
04FE4 98600001 (02420)  
04FEC 8D70 (02421)  
04FE4 98600001 (02422)  
04FEC 8D70 (02423)  
04FE4 98600001 (02424)  
04FEC 8D70 (02425)  
04FE4 98600001 (02426)  
04FEC 8D70 (02427)  
04FE4 98600001 (02428)  
04FEC 8D70 (02429)  
04FE4 98600001 (02430)  
04FEC 8D70 (02431)  
04FE4 98600001 (02432)  
04FEC 8D70 (02433)  
04FE4 98600001 (02434)  
04FEC 8D70 (02435)  
04FE4 98600001 (02436)  
04FEC 8D70 (02437)  
04FE4 98600001 (02438)  
04FEC 8D70 (02439)  
04FE4 98600001 (02440)  
04FEC 8D70 (02441)

## PAGE 62: MAP MODULES FOR THE P A R C ALGORITHM

--- JAN. 35, 1988

```

#5013 0020501F (#2442) JMP ENS51,GTZ
#5016 00400026 (#2443) MOVIR R4,S0006
#5017 0010 (#2444) CLR R1
#5018 00905108 (#2445) ENSS0
#501A 00005109 (#2446) MOVRR R1,0ADSOUTB
#501C 00405018 (#2447) INCM ADSOUTB+1
#501E 2667 (#2448) DJP R4,ENS50
#501F 00005107 (#2449) INCR R6,7
#5021 00005112 (#2450) INCM ADSQAT+1
#5023 3A51 (#2451) ENSS1
#5024 2652 (#2452) INCR R6,7
#5026 001A0382 (#2453) INCM ADSQAT+1
#5027 0000510C (#2454) ENSS1
#5029 00400006 (#2455) MOVRR R5,IIDSTB
#502C 2A6A (#2456) LLS R5,1
#502D 2811 (#2457) INCR R5,2
#502E 447C (#2458) MOVRR R1,SVTS(R5)
#502F 00905108 (#2459) MOVRR R5,0ADS0BETA
#5031 2661 (#2460) MOVIR R4,S0006
#5032 00005109 (#2461) CLR R1
#5033 3A51 (#2462) SRCL 6,R5
#5036 00405028 (#2463) INCR R1,1
#5037 2801 (#2464) XORRR R7,R6
#5038 2800 (#2465) MOVRR R1,0ADSOUTB
#5039 0030504A (#2466) INCR R6,1
#503D 0090510E (#2467) INCM ADS(UTB+1)
#503F 1010 (#2468) LLS R5,1
#5041 00905108 (#2469) DJP R4,ENS60
#5043 2661 (#2470) INCR R7,R6
#5044 00005109 (#2471) MOVRR R1,0ADSOUTB
#5046 0000510F (#2472) INCM ADSOUTB+1
#5048 0040503D (#2473) DJP R4,ENS70
#5037 2801 (#2474) NOP
#5038 2800 (#2475) MOVRR R4,VDEL
#5039 0030504A (#2476) JMP ENS00,LTZ
#503D 0090510E (#2477) MOVRR R1,0ADSOLD8
#503F 1010 (#2478) SKP EQZ
#5041 00905108 (#2479) XORRR R7,R6
#5043 2661 (#2480) MOVRR R1,0ADSOUTB
#5044 00005109 (#2481) INCR R6,1
#5046 0000510F (#2482) INCM ADSOUTB+1
#5048 0040503D (#2483) DJP R4,ENS70
#5037 2801 (#2484) NOP
#5038 2800 (#2485) MOVRR R4,VDEL
#5039 0030504A (#2486) JMP ENS00,LTZ
#503D 0090510E (#2487) MOVRR R1,0ADSOLD8
#503F 1010 (#2488) SKP EQZ
#5041 00905108 (#2489) XORRR R7,R6
#5043 2661 (#2490) MOVRR R1,0ADSOUTB
#5044 00005109 (#2491) INCR R6,1
#5046 0000510F (#2492) INCM ADSOUTB+1
#5048 0040503D (#2493) DJP R4,ENS70

```

>0, NO PHONEY BETA  
 PHONEY BETA -000,0000 (7 BITS)  
 CODE LENGTH - 1 (+VE INDEX)  
 R1=0  
 OUTPUT  
 INCREMENT O-INDEX  
 LOOP 7 TIMES

INCREMENT H-INDEX BY 7  
 INCREMENT I-INDEX

VI. OUTPUT BETA (MSB FIRST)

SID FOR BETA  
 VALUE OF BETA (0-98)  
 CODE FOR BETA  
 CODE LENGTH - 1 (+VE INDEX)

MSB OF BETA, SKIP IF 0  
 R1=1, IF MSB IS 1  
 PARITY UPDATE FOR 1  
 OUTPUT  
 INCREMENT H-INDEX  
 INCREMENT O-INDEX  
 NEXT BIT IN MSB

VII. FIRST, OUTPUT ANY EXTRA BITS FROM LAST BLOCK

GET DELTA VALUE  
 DEL<0, NO BITS LEFT OVER  
 GET OLD OUTPUT  
 PARITY UPDATE FOR 1  
 OUTPUT  
 INCR H-INDEX  
 INCREMENT O-INDEX  
 INCR OLD O-INDEX



ADDRESS	INSTR	OP	DATA	COMMENT
00000	182B	SKPL	LEZ	IF 57 INFO BITS, OUT 6 PARITY BITS
00001	86005DEF	CALL	.PAROUTS	NEXT BIT TO LSB
00002	3C51	LRS	R5,1	
00003	0C405B7D	DJP	R4,EN\$85	
00004				
00005	E6005107	INCH	ADSOHAT+1	INCR I-INDEX
00006	8000550A	JMP	EN\$86	
00007				
00008				
00009				
00010				
00011				
00012				
00013				
00014				
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PAGE 66: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(02617) ; - TO OUTPUT 6 PARITY BITS (MSB FIRST)
(02618) ; - INITIALIZE PARITY CHECK WORD (R7) TO 0
(02619) ; - INITIALIZE H-INDEX (R6) TO 1
(02620) ;
(02621) ; PAROUTS MOVIR R3,00005 TO MOVE OUT 6 BITS (+VE INDEX)
(02622) ; PAR51 MOVKR R6,R7,00020 6TH BIT TO R6
(02623) ; LRS R6,5 SHIFT BIT TO LSB
(02624) ; MOVRM R6,0ADSOUT8 OUTPUT
(02625) ; INCHM ADSOUT8+1 INCREMENT 0-INDEX
(02626) ; LLS R7,1 NEXT BIT TO 6TH POSITION
(02627) ; DJP R3,PAR51
(02628) ;
(02629) ; MOVIR R6,00001 INITIALIZE R6 TO 1
(02630) ; CLR R7 INITIALIZE R7 TO 0
(02631) ;
(02632) ; RETURN
(02633) ;
(02634) ;
(02635) ; --- SUBROUTINE BASES
(02636) ;
(02637) ; - TO GET BASE ADDR AND MEM BUS FOR BUFFER (NOT INDEX REGISTER)
(02638) ; - R6 = BID
(02639) ; - R4,R5 = BASE ADDRESS
(02640) ;
(02641) ; BASES R6,1 INDEX=BID*2
(02642) ; MOVML R4,BCT5BA(R6) GET BASE ADDR FROM BCT
(02643) ; ANDIR R4,00006 KEEP ONLY BUS ID
(02644) ; LLS R4,3 MOVE BUS ID TO BITS 4,5
(02645) ; RETURN
(02646) ;
(02647) ;
(02648) ; --- LEAVE SPACE FOR VARIOUS VARIABLES
(02649) ;
(02650) ;
(02651) ; AD50HAT F'0.0'
(02652) ; ADSOUTB DATA F'0.0'
(02653) ; AD5ENCT DATA F'0.0'
(02654) ; ADSBETA DATA F'0.0'
(02655) ; ADSOLDB DATA F'0.0'
(02656) ; ADSOUTT DATA 00000
(02657) ; ID5TB DATA 00001
(02658) ; V5SYN DATA 00001
(02659) ; V5DEL DATA 00001
(02660) ; L5RUN DATA 00000

```

PAGE 57: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1985

```

(02661) :
(02662) :
(02663) : --- UPDATE TOP OF MEMORY
(02664) :
(02665) : TOESNEV=0L
(02666) : END
(02667) : EVEN
(02668) : EJECT

```

PAGE 68: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1968

```
(#2669) ;
(#2670) ;
(#2671) ;
(#2672) ;
(#2673) ;
(#2674) ;
(#2675) ;
(#2676) ;
(#2677) ;
(#2678) ;
(#2679) ;
(#2680) ;
(#2681) ;
(#2682) ;
(#2683) ;
(#2684) ;
(#2685) ;
(#2686) ;
(#2687) ;
(#2688) ;
(#2689) ;
```

```
*****
*
* *** PROGRAM TRBUF ***
*
*****
```

```
PROG:TRSDC          ARVIND S. ARORA
FCB = #112
```

THIS PROGRAM TRANSFERS ELEMENTS FROM A DOUBLE BUFFER (109 LONG EACH) TO A CIRCULAR BUFFER (1024 LONG). THIS IS USEFUL IN TESTING THE PARC ALGORITHM WITHOUT THE USE OF THE IOS2. THIS PROGRAM ESSENTIALLY SIMULATES THE IOS2 IN THE CPU. SINCE THIS PROGRAM ADDS TO THE CPU TIME, WHICH IS ALREADY AT PREMIUM, THE SAMPLING RATE MUST BE LOWERED BY ABOUT 33 PERCENT.

EJECT

PAGE 69: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(B2698) ;
(B2699) ;
(B2700) ;
(B2701) ;
(B2702) ;
(B2703) ;
(B2704) ;
(B2705) ;
(B2706) ;
(B2707) ;
(B2708) ;
(B2709) ;
(B2710) ;
(B2711) ;
(B2712) ;
(B2713) ;
(B2714) ;
(B2715) ;
(B2716) ;
(B2717) ;
(B2718) ;
(B2719) ;
(B2720) ;
(B2721) ;
(B2722) ;
(B2723) ;
(B2724) ;
(B2725) ;
(B2726) ;
(B2727) ;
(B2728) ;
(B2729) ;
(B2730) ;
(B2731) ;
(B2732) ;
(B2733) ;

```

THE FUNCTION CONTROL BLOCK IS AS FOLLOWS:

```

-----
| |
| |
| FCB @ 112 | INIT
|-----
| DBUF2 | DBUF1
|-----
| | CBUF
|-----
| |
|-----
| |
|-----

```

\*\*\* NOTE: ENABLE LINES WITH \* IN COLUMN 1 TO ASSEMBLE THIS ROUTINE ALONE.

---- SYMBOL DEFINITION TO INTERFACE WITH SNAP-II EXEC. REL 3.05

```

      BCISBA=8582
      FOTSUCB=88C8
      ISVTS=8502
      SYSSFLGS=81FFCE
      TOESOLD=8518F
      TOESPTR=8288

      *OL-TOESPTR
      ADDR TOESNEW(.1)

      ---- DISPATCH TABLE ENTRY

      *OL-FOTSUCB
      ADDR TRSDC

      ---- CSPU MODULE FOR BUFFER TRANSFER, DOUBLE BUFF. --> CIRCULAR BUFF.

      *OL-TOESOLD

      ---- CHECK INIT. SCALAR SELECT

```

PAGE 78: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

05116 707200FF	(02734) :	MOVW	R7,R1,SEF		
05118 2611	(02735) :	MOVLM	\$27,SYSSFLGS		
05119 006E0502	(02736) :	INCR	R1,1		
0511B 00205135	(02737) :	MOVHR	R6,ISVTS(R7)		
0511D 0030512A	(02738) :	JMP	TR\$20,GTZ		
	(02739) :	JMP	TR\$10,LTZ		
	(02740) :				
	(02741) :				
	(02742) :				
0511F 0060	(02743) :	CCR	R6		
	(02744) :				
05120 2611	(02745) :	INCR	R1,1		
05121 0022	(02746) :	MOVHR	R2,R1		
05122 3A21	(02747) :	LLS	R2,1		
05123 C0440502	(02748) :	MOVHRL	R4,BCT\$BA(R2)		
05125 E050514F	(02749) :	MOVHR	R5,ADOUT		
	(02750) :				
05127 CC00515F	(02751) :	MOVZM	IND\$OUT		
05129 2711	(02752) :	DECR	R1,1		
	(02753) :				
	(02754) :				
0512A 0060	(02755) :	NEG	R6		
0512B E06E0502	(02756) :	MOVHR	R6,ISVTS(R7)		
	(02757) :				
0512D 0072	(02758) :	MOVHR	R7,R1		
0512E 3C77	(02759) :	LRS	R7,7		
0512F C04E0502	(02760) :	MOVHRL	R4,BCT\$BA(R7)		
05131 E050514C	(02761) :	MOVHR	R5,ADIN		
05133 0000513F	(02762) :	JMP	TR\$25		
	(02763) :				
	(02764) :				
	(02765) :				
05135 0060	(02766) :	NEG	R6		
05136 E06E0502	(02767) :	MOVHR	R6,ISVTS(R7)		
	(02768) :				
05138 707200FF	(02769) :	MOVW	R7,R1,SEF		
0513A 3A71	(02770) :	LLS	R7,1		
0513B C04E0502	(02771) :	MOVHRL	R4,BCT\$BA(R7)		
0513D E050514C	(02772) :	MOVHR	R5,ADIN		
	(02773) :				
	(02774) :				
0513F F0705160	(02775) :	MOVHR	R7,SIZES		
05141 2771	(02776) :	DECR	R7,1		
	(02777) :				

TIMING INSTRUCTION  
 >0,NORMAL OPERATION BUF 1  
 <0,NORMAL OPERATION BUF 2  
 :=0,INITIALIZATION  
 SET SCALAR SELECT TO -1  
 GET BASE ADDR FOR CIRC. BUFF  
 SAVE ADDR  
 SET SID SELECT  
 SAVE  
 GET BID FOR DOUBLE BUFF 1  
 GET BASE ADDR  
 SAVE BASE ADDR  
 COMPLEMENT SID SELECT  
 SAVE  
 GET BID FOR DOUBLE BUFF 2  
 GET BASE ADDR  
 SAVE BASE ADDR  
 GET BUFFER SIZE  
 SET UP COUNTER



PAGE 72: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 31, 1981

(#2822) 1  
 (#2823) \*  
 (#2824) \*  
 (#2825)  
 (#2826)

TOESNEV=0L  
 END  
 EVEN  
 EJECT

08161 0000



PAGE 73: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(02827) ;
(02828) ;
(02829) ;
(02830) ;
(02831) ;
(02832) ;
(02833) ;
(02834) ;
(02835) ;
(02836) ;
(02837) ;
(02838) ;
(02839) ;
(02840) ;
(02841) ;
(02842) ;
(02843) ;
(02844) ;
(02845) ;
(02846) ;
(02847) ;
(02848) ;
(02849) ;
(02850) ;
(02851) ;
(02852) ;
(02853) ;
(02854) ;
(02855) ;
(02856) ;
(02857) ;
(02858) ;
(02859) ;
(02860) ;
(02861) ;
(02862) ;
(02863) ;
(02864) ;
(02865) ;
(02866) ;
(02867) ;

```

ARVIND S. ARORA

NAME: DCDRS FCB: 111

THIS PROGRAM TAKES FRAMES OF 189 BITS (LSB IN THE 16 BIT WORDS  
OUTPUT BY THE IOS2), SYNCHRONIZES ON THE FRAME, AND DECODES THE BITS  
INTO A BLOCK OF QUANTIZER LEVELS TO BE USED BY THE RECEIVER OF THE  
PARC ALGORITHM.

DEPENDENT ON THE VALUES OF 2 FUNCTION SELECT INDICATORS, IT SELECTS  
EITHER TO DECODE, OR SYNCHRONIZE, OR INITIALIZE AND SYNCHRONIZE. IT  
ALSO DECIDES WHICH OF THE TWO Q-OUT BUFFERS TO FILL UP.

THE Q-OUT BUFFER HAS THE FOLLOWING FORMAT: PONEY BETA INDICATOR  
(-1 MEANS PONEY BETA PRESENT), QUANTIZER LEVELS (1 TO 11, AND A RUN-  
LENGTH CODE TO BE DECODED TO 14 LEVEL 1 OUTPUTS), AND AN END-OF-BLOCK  
CODE (-VE 12).

EACH TIME THE PROGRAM IS STOPPED, THE MODULE MUST BE RE-LOADED  
OR LOCATIONS PSBASE,LSRUN RESET TO ENSURE PROPER INITIALIZATION.

THIS PROGRAM ALSO SIMULATES THE STATE OF THE SHAT BUFFER IN THE  
RECEIVER TO ENSURE THE BUFFER DOES NOT UNDER-FLOW OR OVER-FLOW.

#### CONSTRAINTS:

- 1) THE CONSTRAINTS ON THE SOURCE CODE ARE THE SAME AS THOSE ON THE ENCODER.
- 2) THE OUTPUT OF THE DECODER HAS THE SAME FORM AS THE INPUT OF THE ENCODER.
- 3) THE INPUT OF THIS PROGRAM IS A CIRCULAR BUFFER OF LENGTH 1024.
- 4) ALL THE BUFFERS USED IN THIS PROGRAM MUST RESIDE ON BUS 1.

EJECT

PAGE 74:

MAP MODULES FOR THE P A R C ALGORITHM ---- JAN. 30, 1980

```

(02868) 1
(02869) 1
(02870) 1
(02871) 1
(02872) 1
(02873) 1
(02874) 1
(02875) 1
(02876) 1
(02877) 1
(02878) 1
(02879) 1
(02880) 1
(02881) 1
(02882) 1
(02883) 1
(02884) 1
(02885) 1
(02886) 1
(02887) 1
(02888) 1
(02889) 1
(02890) 1
(02891) 1
(02892) 1
(02893) 1
(02894) 1
(02895) 1
(02896) 1
(02897) 1
(02898) 1
(02899) 1
(02900) 1
(02901) 1
(02902) 1
(02903) 1
(02904) 1
(02905) 1
(02906) 1
(02907) 1
(02908) 1
(02909) 1
(02910) 1
(02911) 1

```

THE FUNCTION CONTROL BLOCK HAS THE FOLLOWING FORMAT:

```

-----
FCB # 111 I ISELECT I
-----
OQB2 I OQB1 I
-----
ITB2 I ITB1 I
-----
DECT (TABLE) I DECB (TABLE) I
-----
ICAP I ICB I
-----

```

\*\*\* NOTE: ENABLE ALL LINES WITH \* IN COLUMN TO ASSEMBLE THIS PROGRAM ALONE.

--- SYMBOL DEFINITION TO INTERFACE WITH SNAP-II EXEC. REL 3.05

```

BCTSA-S502 BASE OF SCALAR TABLE
FOTSUFCE-S8C6 FCB # 111
ISVTS-S502 BASE OF INTEGER SCALAR TABLE
NOSMAX-S9 (NO OF WORDS IN SYNC CORR. COMPUTATION)
SYSSFLG-S1FFCE SYSTEM FLAG LOCATION
TOESOLD-S5200 OLD TOP OF MEMORY
TOESPTR-S200 TOP OF MEMORY POINTER
SVTS-S382 BASE OF SCALAR TABLE

--- TOP OF MEMORY POINTER
*OL=TOESPTR
ADDR TOESNEW(.1)

```

```

PAGE 78: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30. 1988

      (B2912) : --- DISPATCH TABLE ENTRIES
      (B2913) :
      (B2914) : OL=FDTSUFCB
      (B2915) :
      (B2916) : ADDR DCDRS
      (B2917) :
      (B2918) :
      (B2919) : --- CSPU MODULE FOR THE DECODER
      (B2920) :
      (B2921) : OL=TOESOLD
      (B2922) :
      (B2923) : FIRST DECIDE WHICH OPERATIONS ARE TO BE DONE
      (B2924) :
      (B2925) : DCDRS MOVNR R1,BASFCB STACK FCB POINTER
      (B2926) : NOP 2 SAVE SPACE FOR TIMING INSTRUCTION

      (B2927) :
      (B2928) : --- USE FUNCTION SELECT INDICATOR TO DECIDE OPERATION
      (B2929) :
      (B2930) : MOVNR R2,R1,SBFF GET SID OF ISL
      (B2931) : MOVNR R2,SIDSL SAVE SID
      (B2932) : MOVNR R3,ISVTS(R2) GET ISL1
      (B2933) : JMP DECS,GTZ ISL1 > B, DECODER
      (B2934) : JMP SYNC,LTZ ISL1 < B, SYNCHRONIZE
      (B2935) :
      (B2936) : ISL1 = B, INITIALIZE & SYNCHRONIZE
      (B2937) :
      (B2938) :
      (B2939) :
      (B2940) :
      (B2941) : 1) SET ISL1 TO -1
      (B2942) :
      (B2943) : EVEN
      (B2944) : CCR R3 SET R3=-1
      (B2945) : MOVNR R3,ISVTS(R2) SET ISL1 TO -1
      (B2946) :
      (B2947) : 2) SET MAX CORRELATION INDEX WORDS (1B) TO -1
      (B2948) :
      (B2949) : CCR R5 R5=-1
      (B2950) : MOVNR R4,MOSMAX INDEX=9 (FOR 1B WORDS)
      (B2951) : MOVNR R5,PSMAX(R4) MAX CORR WORD = -1
      (B2952) : DJP R4,INS2B
      (B2953) :
      (B2954) : 3) GET BASE ADDRESS OF Q-BUFFER1 & SAVE IN BASQOB

```

```

PAGE 76: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1968

( #2955 ) ;
( #2956 ) ;
( #2957 ) ;
( #2958 ) ;
( #2959 ) ;
( #2960 ) ;
( #2961 ) ;
( #2962 ) ;
( #2963 ) ;
( #2964 ) ;
( #2965 ) ;
( #2966 ) ;
( #2967 ) ;
( #2968 ) ;
( #2969 ) ;
( #2970 ) ;
( #2971 ) ;
( #2972 ) ;
( #2973 ) ;
( #2974 ) ;
( #2975 ) ;
( #2976 ) ;
( #2977 ) ;
( #2978 ) ;
( #2979 ) ;
( #2980 ) ;
( #2981 ) ;
( #2982 ) ;
( #2983 ) ;
( #2984 ) ;
( #2985 ) ;
( #2986 ) ;
( #2987 ) ;
( #2988 ) ;
( #2989 ) ;
( #2990 ) ;
( #2991 ) ;
( #2992 ) ;
( #2993 ) ;
( #2994 ) ;
( #2995 ) ;
( #2996 ) ;
( #2997 ) ;
( #2998 ) ;

( TO BE USED FOR STORING SYNC CORRELATION VALUES )
( INDEXED BY R2 )

INCR R1,1
MOVW R2,R1,SBFF BID OF OOB1
LLS R2,1 BID*2
MOVW R3,BCTSSA(R2) GET BASE ADDR WORD FOR OOB1
MOVW R3,S14 BUS 1, IND REG R2
MOVW R3,BASOQB SAVE BASE ADDR

--- UPDATE PROGRAM LOCATIONS REFERRING TO OOB
MOVW R4,OOB1B
MOVW R4,OOB11
MOVW R4,OOB12
MOVW R4,OOB13
MOVW R4,OOB14
MOVW R4,OOB15

4) INITIALIZE OOB BUFFER TO 0
MOVW R2,S18F R2=399
CLR R5
OQB1B=0L+1
INS4B MOVW R5,BAS4B(R2) INIT OOB TO 0
DJP R2,INS4B

5) GET BASE ADDR OF INPUT CIRCULAR BUFFER, IND REG R3, SIZE=1024
INCR R1,3
MOVW R2,R1,SBFF BID OF ICB
LLS R2,1 BID*2
MOVW R3,BCTSSA(R2) GET BASE ADDR WORDS FOR ICB
MOVW R3,S16 BUS 1, IND REG R3
MOVW R3,BAS1CB SAVE BASE ADDR

--- MODIFY PROGRAM LOCATIONS REFERRING TO ICB
MOVW R4,ICB1B
MOVW R4,ICB11
MOVW R4,ICB12
MOVW R4,ICB13
MOVW R4,ICB14

```

PAGE 77: MAP MODULES FOR THE P A R C ALGORITHM ---- JAN. 30, 1980

```

061A8 E0405355 (02999)      MOVHM R4,ICB2F
061A9 E0405353 (03000)      MOVHM R4,ICB21
061AA E0405351 (03001)      MOVHM R4,ICB22
061AB E0405349 (03002)      MOVHM R4,ICB23
061AC E0405347 (03003)      MOVHM R4,ICB24
061AD E0405345 (03004)      MOVHM R4,ICB25
061AE E0405343 (03005)      MOVHM R4,ICB26
061AF E0405341 (03006)      MOVHM R4,ICB27
                                ; 6) SAVE GAP SIZE
                                ; (03007)
                                ; (03008)
                                ; (03009)
                                ; (03010)
061B0 6022      MOVHM R2,R1
061B1 3C20      LRS R2,8
061B2 E0205405      MOVHM R2,VSGAP
                                GET GAP SIZE
                                SAVE GAP SIZE

                                *** SYNCHRONIZATION ***

                                ; 1) SHIFT MAX CORR. INDEX WORDS BACK ONE
                                ; I.E. P(I-1)=P(I)
                                ; (03011)
                                ; (03012)
                                ; (03013)
                                ; (03014)
                                ; (03015)
                                ; (03016)
                                ; (03017)
                                ; (03018)
                                ; (03019)
                                ; (03020)
                                ; (03021)
                                ; (03022)
                                ; (03023)
                                ; (03024)
                                ; (03025)
                                ; (03026)
                                ; (03027)
                                ; (03028)
                                ; (03029)
                                ; (03030)
                                ; (03031)
                                ; (03032)
                                ; (03033)
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

061B8 0000      EVEN R1,NOSMAX
061B9 00100009      MOVHM R1,1
061BA 00200009      MOVHM R2,NOSMAX
061BB F0420488      MOVHM R4,PSMAX(R1)
061BC 00200009      MOVHM R4,PSMAX(R2)
061BD 00200009      DEC R2,1
061BE 00200009      DJP R1,SCS1F
                                R1, INDEX P(I)
                                R2, INDEX P(I-1)
                                MOV P(I) TO P(I-1)

                                ; 2) UPDATE SYNC HISTOGRAM FOR CURRENT FRAME
                                ; (03031)
                                ; (03032)
                                ; (03033)
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

061C0 00300000      MOVHM R3,8BC
061C1 FC300488      ADDHM R3,PSBASE
061C2 00300000      ANDIR R3,03FF
061C3 00400000      CLR R4
061C4 00400000      CLR R5
061C5 002000179      MOVHM R2,$179
061C6 F01004CF      MOVHM R1,VSSYNC
                                R3=188
                                CURRENT BASE IND + 188
                                MAX CORR INDEX THIS BLOCK
                                MAX CORR VALUE
                                HISTOGRAM INDEX R2=377
                                SYNC BIT VALUE TO R1

```

PAGE 70: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

```

05108 9A100001 (03043) ANDIR R1,00001 MASK LSB
05109 9A100001 (03044) READY TO MOVE IN BIT 1
0510A 9A700001 (03045) SCS20 MOVIR R7,01
0510B 9A700001 (03046) ICB15=OL+1
0510C 9A700001 (03047) ANDMR R7,BAS1CB(R3) MOVE LSB OF INPUT WORD
0510D 9A700001 (03048) KORRR R7,R1 RESULT OF CORR. OF SYNC WITH INFO BIT
0510E 9A700001 (03049) JMP SCS22,GTZ ;SAME = 0, DIFFERENT = 1
0510F 9A700001 (03050) JUMP FOR DIFFERENT
0510G 9A700001 (03051) ;--- FOR MATCH WITH SYNC BIT
0510H 9A700001 (03052) ;--- FOR MATCH WITH SYNC BIT
0510I 9A700001 (03053) ;--- FOR MATCH WITH SYNC BIT
0510J 9A700001 (03054) OOB11=OL+1
0510K 9A700001 (03055) MOVMR R6,BAS00B(R2) R6=SYNC COR VAL FOR CURRENT BIT
0510L 9A700001 (03056) INCR R6,1 ADD 1 TO IT
0510M 9A700001 (03057) CMPRR R6,R5 CMPR WITH MAX SO FAR (R6-R5)
0510N 9A700001 (03058) JMP SCS21,LTZ THIS VALUE < MAX SO FAR
0510O 9A700001 (03059) MOVRR R5,R6 IF MAX, UPDATE MAX VALUE
0510P 9A700001 (03060) MOVRR R4,R2 UPDATE MAX INDEX
0510Q 9A700001 (03061) OOB12=OL+1
0510R 9A700001 (03062) SCS21 MOVRR R6,BAS00B(R2) SAVE NEW CORR VALUE
0510S 9A700001 (03063) DECR R2,1 DECR HIST INDEX
0510T 9A700001 (03064) JMP SCS24
0510U 9A700001 (03065) ;--- FOR NO MATCH WITH SYNC BIT
0510V 9A700001 (03066) ;--- FOR NO MATCH WITH SYNC BIT
0510W 9A700001 (03067) ;--- FOR NO MATCH WITH SYNC BIT
0510X 9A700001 (03068) SCS22 DECR R2,1 DECR HIST INDEX
0510Y 9A700001 (03069) OOB13=OL+1
0510Z 9A700001 (03070) MOVMR R6,BAS00B(R2) SYNC CORR VAL TO R6
0510A 9A700001 (03071) INCR R6,1 (R6-R5)
0510B 9A700001 (03072) CMPRR R6,R5 THIS VAL NOT MAX
0510C 9A700001 (03073) JMP SCS23,LTZ IF MAX, UPDATE MAX VAL
0510D 9A700001 (03074) MOVRR R5,R6 UPDATE MAX INDEX
0510E 9A700001 (03075) MOVRR R4,R2
0510F 9A700001 (03076) OOB14=OL+1
0510G 9A700001 (03077) SCS23 MOVRR R6,BAS00B(R2) SAVE NEW CORR VAL
0510H 9A700001 (03078) ;--- MERGE HERE BOTH CASES, MATCH OR NO-MATCH
0510I 9A700001 (03079) ;--- MERGE HERE BOTH CASES, MATCH OR NO-MATCH
0510J 9A700001 (03080) ;--- MERGE HERE BOTH CASES, MATCH OR NO-MATCH
0510K 9A700001 (03081) SCS24 DECR R3,1 INP IND
0510L 9A700001 (03082) ANDIR R3,003FF MOD 1/24
0510M 9A700001 (03083) DJP R2,SCS20 DEC HIST IND & LOOP
0510N 9A700001 (03084) ;--- IF NOT SYNC IN 10 SECONDS, REINITIALIZE
0510O 9A700001 (03085) ;--- IF NOT SYNC IN 10 SECONDS, REINITIALIZE
0510P 9A700001 (03086) ;--- IF NOT SYNC IN 10 SECONDS, REINITIALIZE

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PAGE 79:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

(03007) ;      CMPMR R5,TSLIM      CMPR IN TERMS OF NO OF ITERATIONS
(03008) ;      JMP SC808,GTZ      >10 SECS. REINIT.
(03009) ;
(03010) ;      3) IF PRESENT MAX INDEX NOT THE SAME AS LAST TIME'S, CHECK IT OUT
(03011) ;      JMP SC831      (NOTE: SKIP OVER THIS CHECK. TEMPI
(03012) ;      MOVMR R2,PSMAX      PREV MAX IND.
(03013) ;      CMPRR R2,R4      (R2-R4)
(03014) ;      JMP SC831,EQZ      IF SAME JUMP
(03015) ;      ;IF NOT,
(03016) ;      OOBIS=OL+1      GET OLD MAX VAL
(03017) ;      MOVMR R6,BASO0B(R2)      (PAST VAL-PRESENT VAL)
(03018) ;      CMPRR R6,R5      IF PAST VAL LESS,JMP
(03019) ;      JMP SC831,LEZ      IF PAST VAL LESS,JMP
(03020) ;      MOVRR R4,R2      SAVE NEW MAX INDEX
(03021) ;      MOVRR R4,PSMAX
(03022) ;      SC831
(03023) ;      4) CHECK IF SYNCHRONIZATION ACHIEVED
(03024) ;      IF ALL 10 PREV VALS OF MAX IND ARE THE SAME, WE HAVE SYNC
(03025) ;      MOVIR R2,NOSMAX
(03026) ;      CMPMR R4,PSMAX(R2)      CMPR CURRENT & PREV VAL
(03027) ;      JMP SC870,NEZ      NOT EQUAL, NOT SYNC
(03028) ;      DJP R2,SC841
(03029) ;      5) SYNCHRONIZED. SET UP FOR RETURNING TO RECEIVER
(03030) ;      ;--- SET UP 2 BLOCKS SYNC VAL. (NOT NEXT)
(03031) ;      SRBCL R,R4      CHECK IND, EVEN OR ODD
(03032) ;      JMP SC851      ODD-CURRENT SYNC BIT RIGHT, LEAVE
(03033) ;      MOVIR R7,SO001      EVEN-CURRENT SYNC BIT IS WRONG
(03034) ;      XORRR R7,VSSYNC      INVERT FOR 2 BLOCKS AWAY
(03035) ;      NOP 1
(03036) ;      SC851
(03037) ;      ;--- UPDATE BASE OF CURRENT FRAME POINTER
(03038) ;      MOVMR R3,PSBASE
(03039) ;      ADDR R3,SBD
(03040) ;      ANDIR R3,SO3FF
(03041) ;      MOVRR R3,PSBASE
(03042) ;      ;--- SET UP BIT-1 POINTER
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PAGE 91:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 35, 1985

#5258 9A2#FFF (#3175)      ANDIR  R2,FFF
#5252 3A21  (#3176)      LLS      R2,1
#5253 C#44#582  (#3177)      MOVHRL R4,BCT$BA(R2)      ADDR OF NEXT Q-OUT BUFF
#5255 9#4#514  (#3179)      MOVIR  R4,$14      BUS 1, IND REG R2
#5257 844#54AE (#3181)      MOVHRL R4,BASOQB      SAVE
#5259 E#5#5262 (#3184)      MOVHRL R5,OQB#1
#5258 E#5#526A (#3185)      MOVHRL R5,OQB#2
#525D 9#2#57E  (#3188)      MOVIR  R2,$7E      Q-LEVEL 1*2
#525F 9#5#5262 (#3189)      MOVIR  R6,$2
#5261 E#6454AE (#3191)      MOVHRL R5,BASOQB(R2)      126 1'S TO OQB
#5263 8C2#5261 (#3192)      SC$52      DJP      R2,SC$52
#5265 9#2#57F  (#3194)      MOVIR  R2,$7F
#5267 9#6#FFF4 (#3195)      MOVIR  R6,$FFF4      END CODE= -12
#5269 E#6454AE (#3197)      MOVHRL R6,BASOQB(R2)
#5268 F#6#5406 (#32#1)      MOVHRL R6,SZ$SHAT
#526D 266F  (#32#2)      INCR    R6,16
#526E E#6#5487 (#32#3)      MOVHRL R6,P$SHAT
#527# F#1#5484 (#32#5)      MOVHRL R1,BASFCB
#5272 2613  (#32#6)      INCR    R1,3
#5273 7#22#FFF (#32#9)      MOVHRL R2,R1,$$FFF
#5276 3A21  (#321#)      LLS      R2,1
#5278 C#44#582 (#3211)      MOVHRL R4,BCT$BA(R2)      R4,R5=BASE ADDR WORDS
#5279 9#4#51E  (#3212)      MOVIR  R4,$$1E      BUS1, IND REG R7
#527A 844#5482 (#3213)      MOVHRL R4,BASDEC$
#527C E#5#526E (#3217)      MOVHRL R5,DEC$1#
#527D 844#5482 (#3218)      MOVHRL R5,BASDEC$

```



PAGE 03: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

052AC 2631      (03263)      INCR   R3.1      MOD 1024
052AD 9A3003FF  (03264)      ANDIR  R3.003FF
052AE 00000000  (03265)      !
052AF 89A052A5  (03266)      !    IJN   R4.0C054
052B0 00000000  (03267)      !
052B1 0270      (03268)      !---- CHECK TO SEE IF ANY ERRORS
052B2 001052BE  (03269)      !    TEST  R7
052B3 00000000  (03270)      !    JMP   SC0541.EQZ
052B4 2771      (03271)      !    DECR  R7.1
052B5 F0305489  (03272)      !    MOVHR R3.P081T1
052B6 4C3E      (03273)      !    ADDR  R3.R7
052B7 9A3003FF  (03274)      !    ANDIR R3.003FF
052B8 90500001  (03275)      !    MOVIR R5.00001
052B9 F00054AC  (03276)      !    XORRM R5.00001
052BA 00000000  (03277)      !
052BB 00000000  (03278)      !---- DECODE VALUE OF NEXT T (IMP BUFF MUST CONTAIN MSB FIRST)
052BC 00000000  (03279)      !
052BD F0305489  (03280)      !    MOVHR R3.P081T1
052BE 2631      (03281)      !    INCR  R3.1
052BF 9A3003FF  (03282)      !    ANDIR R3.003FF
052C0 90500001  (03283)      !    MOVIR R4.00001
052C1 00000000  (03284)      !    CLR   R7
052C2 00000000  (03285)      !
052C3 3A71      (03286)      !    LLS   R7.1
052C4 F00052C8  (03287)      !    MOVHR R1.00000(R3)
052C5 F01054AC  (03288)      !    IOKR  R7.R1.00001
052C6 56720001  (03289)      !    INCR  R3.1
052C7 9A3003FF  (03290)      !    ANDIR R3.003FF
052C8 00000000  (03291)      !
052C9 0C4052C6  (03292)      !    DJP   R4.0C055
052CA 00000000  (03293)      !
052CB 00000000  (03294)      !    MOVHR R7.VST
052CC 00000000  (03295)      !
052CD 00000000  (03296)      !---- VALUE OF NEXT BETA, PHONEY BETA
052CE 00000000  (03297)      !
052CF 00000000  (03298)      !
052D0 00700001  (03299)      !    MOVIR R7.S1
052D1 00700001  (03300)      !    MOVHR R7.VSPHB
052D2 00000000  (03301)      !    MOVIR R2.S1
052D3 00000000  (03302)      !
052D4 00000000  (03303)      !    CLR   R7
052D5 00000000  (03304)      !    MOVIR R4.S6
052D6 3A71      (03305)      !    LLS   R7.1
052D7 00000000  (03306)      !
052D8 00000000  (03307)      !
052D9 00000000  (03308)      !
052DA 00000000  (03309)      !
052DB 00000000  (03310)      !
052DC 00000000  (03311)      !
052DD 00000000  (03312)      !
052DE 00000000  (03313)      !
052DF 00000000  (03314)      !
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052E1 00000000  (03316)      !
052E2 00000000  (03317)      !
052E3 00000000  (03318)      !
052E4 00000000  (03319)      !
052E5 00000000  (03320)      !
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052E7 00000000  (03322)      !
052E8 00000000  (03323)      !
052E9 00000000  (03324)      !
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052EB 00000000  (03326)      !
052EC 00000000  (03327)      !
052ED 00000000  (03328)      !
052EE 00000000  (03329)      !
052EF 00000000  (03330)      !
052F0 00000000  (03331)      !
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052F9 00000000  (03340)      !
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052FC 00000000  (03343)      !
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0548D 00000000  (03744)      !
0548E 00000000  (03745)      !
0548F 00000000  (
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PAGE 87: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

#5350 8D70 (M3438) CLR R7
#5351 9A400005 (M3439) MOVIR R4,000005
#5353 3A71 (M3440) DCS31 R7,1
#5355 9A400005 (M3441) ICB22=OL+1
#5354 F8684AC (M3442) MOVHR R6,BASICB(R3)
#5356 567C0001 (M3443) IORRR R7,R6,000001
#5358 2631 (M3444) ;
#5359 9A30003FF (M3445) INCR R3,1
#5358 8C405353 (M3446) ANDIR R3,003FF
#5358 8C405353 (M3447) ;
#5358 8C405353 (M3448) DJP R4,DCS31
#5358 8C405353 (M3449) ;
#5358 8C405353 (M3450) ; --- PARITY CHECK ON 57 BITS
#5358 8C405353 (M3451) ;
#5358 8C405353 (M3452) MOVRR R3,R5
#5358 8C405353 (M3453) MOVIR R4,000038
#5358 8C405353 (M3454) CLR R6
#5358 8C405353 (M3455) ;
#5358 8C405353 (M3456) DCS32 INCR R6,1
#5358 8C405353 (M3457) ICB21=OL+1
#5358 8C405353 (M3458) MOVHR R1,BASICB(R3)
#5358 8C405353 (M3459) SRBC R1
#5358 8C405353 (M3460) XORRR R7,R6
#5358 8C405353 (M3461) ;
#5358 8C405353 (M3462) INCR R3,1
#5358 8C405353 (M3463) ANDIR R3,003FF
#5358 8C405353 (M3464) ;
#5358 8C405353 (M3465) DJP R4,DCS32
#5358 8C405353 (M3466) ;
#5358 8C405353 (M3467) ; --- CORRECT ANY ERROR
#5358 8C405353 (M3468) ;
#5358 8C405353 (M3469) TEST R7
#5358 8C405353 (M3470) JMP DCS33,EQZ
#5358 8C405353 (M3471) DECR R7,1
#5358 8C405353 (M3472) MOVRR R3,R5
#5358 8C405353 (M3473) ADDR R3,R7
#5358 8C405353 (M3474) ANDIR R3,003FF
#5358 8C405353 (M3475) MOVIR R1,000001
#5358 8C405353 (M3476) ICB22=OL+1
#5358 8C405353 (M3477) XORRR R1,BASICB(R3)
#5358 8C405353 (M3478) ;
#5358 8C405353 (M3479) DCS33 DJP R2,DCS30
#5358 8C405353 (M3480) ;
#5358 8C405353 (M3481) ; 4) UPDATE FOR SYNC MONITOR

```

COUNTER FOR 6 BITS

NEXT PARITY BIT  
LOAD TO LSB OF PARITY WORD

INP INDEX

SET UP INP INDEX  
COUNTER 56 - 0

INFO WORD  
MASK BIT 1  
PARITY UPDATE FOR 1

INP IND

SET UP ERROR IND

LOOP FOR 3 H-FRAMES

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PAGE 88:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

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      (M337C 9B1B8B81)
      (M337E F41B54CF)
      (M338B 9A1B8B81)
      (M338C 8B8B5383)
      (M3382 F41B64AC)
      (M3384 2A82)
      (M3386 3B71)
      (M3388 1B8B)
      (M3387 3A72)
      (M3388 E87B54D3)
      (M338A 2B3E)
      (M338B 8B8B53A2)
      (M338D F87B5488)
      (M338F 9C7B8B8D)
      (M3391 9A7B83FF)
      (M3393 E87B5488)
      (M3395 F87B5486)
      (M3397 B06B)
      (M3398 E86E85B2)
      (M339A 2671)
      (M339B F86E85B2)
      (M339D B86B)
      (M339E E86E85B2)
      (M33A8 8B8B54A6)

      V(I+1)=RIGHT SHIFT 1 [V(I)], IF CORRELATED
      V(I+1)=LEFT SHIFT 2 [V(I)], NOT CORRELATED
      BIT 11 CLEAR ==> SYNC LOST
      MOVRR R3,R5 POINT TO NEXT SYNC BIT
      MOVRR R7,VSPAR GET SYNC VARIABLE
      MOVIR R1,8B8B1 CHECK CORR. IN THIS FRAME
      XORRR R1,VSSYNC
      ANDIR R1,8B8B1
      ICB23=OL+1
      XORRR R1,BASICB(R3) 1 - MATCH , 0 - NO MATCH
      SRBCL R,R1
      ARS R7,1 CORRELATED
      SKP R,1
      LLS R7,2 UNCORRELATED
      MOVRR R7,VSPAR SAVE NEW VALUE
      SRBCL 11,R7 IF BIT 11 CLEAR, SYNC LOST
      JMP DC55B SYNC RETAINED, GO TO DECODE
      ---- IF SYNC LOST, SET UP FOR SYNC ACQUISITION NEXT TIME
      MOVRR R7,PSBASE
      ADDIR R7,8BD UPDATE BASE OF FRAME POINTER
      ANDIR R7,8B3FF
      MOVRR R7,PSBASE
      ---- UPDATE FUNCTION SELECT FLAGS AND RETURN
      ISL1=B
      ISL2=-ISL2
      MOVRR R7,SIDISL
      CLR R6
      MOVRR R6,ISVTS(R7)
      INCR R7,1
      MOVRR R6,ISVTS(R7)
      NEG R6
      MOVRR R6,ISVTS(R7)
      ---- GO FOR XMTR UPDATE
      JMP DC59B JUMP FOR XMTR UPD

```



```

PAGE 89:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

      (R3526) ;
      (R3527) ;
      (R3528) ; 5) MOV T,BETA,PH BETA TO THEIR LOCATIONS
      (R3529) ;
      (R3530) ; --- MOVE T TO INTEGER SCALAR TABLE
      (R3531) ;
      (R3532) ; DC 50
      (R3533) ; MOVHR R7,SIDSTB
      (R3534) ; LLS R7,1
      (R3535) ; MOVHR R6,VST
      (R3536) ; MOVHR R6,SVTS(R7)
      (R3537) ; --- MOVE BETA TO ITS LOCATION IN INTEGER SCALAR TABLE
      (R3538) ;
      (R3539) ; INCR R7,2
      (R3540) ; MOVHR R6,VSBETA
      (R3541) ; MOVHR R6,SVTS(R7)
      (R3542) ;
      (R3543) ; --- NOW MOVE PHONEY BETA TO LOCATION IN OUTPUT BUFFER
      (R3544) ;
      (R3545) ; MOVHR R1,BASOQB+1
      (R3546) ; MOVHR R6,VSPHB
      (R3547) ;
      (R3548) ; --- UPDATE SHAT BUFFER POINTER IF PHONEY BETA
      (R3549) ;
      (R3550) ; JMP DC551,GTZ
      (R3551) ; MOVHR R7,VSGAP
      (R3552) ; ADDR R7,PSHAT
      (R3553) ;
      (R3554) ; DC551
      (R3555) ; PUSHX1 R1,R6
      (R3556) ;
      (R3557) ; 6) DECODE NEXT T,BETA, PH BETA (R3,R5 STILL HAV LOC FOR NEXT FRAME)
      (R3558) ; --- FIRST T
      (R3559) ;
      (R3560) ; INCR R3,1
      (R3561) ; ANDIR R3,SB3FF
      (R3562) ;
      (R3563) ; MOVHR R4,RS
      (R3564) ; CLR R7
      (R3565) ;
      (R3566) ; DC560
      (R3567) ; LLS R7,1
      (R3568) ; IS24=0L+1
      (R3569) ; MOVHR R6,BASICB(R3)
      (R3570) ; IORR R7,R6,SB551

```

POINT TO 1ST BIT (MSB) OF T



PAGE 31: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1968

```

      (73614) ;
      (73615) ;
      (73616) ;
      (73617) ;
      (73618) ;
      (73619) ;
      (73620) ;
      (73621) ;
      (73622) ;
      (73623) ;
      (73624) ;
      (73625) ;
      (73626) ;
      (73627) ;
      (73628) ;
      (73629) ;
      (73630) ;
      (73631) ;
      (73632) ;
      (73633) ;
      (73634) ;
      (73635) ;
      (73636) ;
      (73637) ;
      (73638) ;
      (73639) ;
      (73640) ;
      (73641) ;
      (73642) ;
      (73643) ;
      (73644) ;
      (73645) ;
      (73646) ;
      (73647) ;
      (73648) ;
      (73649) ;
      (73650) ;
      (73651) ;
      (73652) ;
      (73653) ;
      (73654) ;
      (73655) ;
      (73656) ;
      (73657) ;

      MOVHR R3,PSINFO
      MOVHR R2,PSBIT1
      SUBRR R3,R2
      ANDIR R3,803FF
      MOVIR R4,838
      SUBRR R4,R3

      MOVHR R3,PSINFO
      MOVIR R2,82
      CLR R7
      JMP DC871

      MOVIR R4,838
      DC878

      LLS
      MOVHR R6,BASIC8(R3)
      TORR R7,R6,81

      INCR R3,1
      ANDIR R3,803FF

      MOVHR R6,BASDECT(R7)
      JMP DC872,LTZ
      JMP DC873,GTZ

      DJP R4,DC871
      JMP DC875

      ;--- NULL OR RUN LENGTH CODE
      CMPHR R6,V8THR
      JMP DC881,GTZ

      MOVHR R7,LSRUN
      MOVIR R6,82
      ADDR R1,R7
      RPT R7

      INITIALIZE LOOP COUNTER
      IMP INDEX
      LOOP COUNTER
      CODE ACCUMULATOR

      <# NULL OR RUN LENGTH
      ># CODE WORD
      ; -# NOT YET CODE WORD
      LOOP BACK FOR NEXT IMP

      END OF H-FRAME PROCESSING

      +VE NULL CODE
      COUNTER FOR 14 1'S
      GONNA OUTPUT LEVEL 1*2
      SET UP OUT POINTER
      OUTPUT TO BUFFER

```

PAGE 92: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

0041A 0020000 (03650) MOVHM R6,B(R1)
0041C 0070 (03659) ;
0041D FC100110 (03660) CLR R7
0041F 2012 (03661) ADDHM R1,LSRUN
(03662) INCR R1,2
00420 0C4003FE (03663) ;
(03664) DJP R4,DCS71
00422 00000420 (03665) ;
(03666) JMP DCS75
(03667) ;
(03668) ;---- CODE WORD
(03669) ;
00424 341C (03670) DCS73 PUSHX1 R1,R6
00426 0070 (03671) CLR R7
(03672) ;
00428 0C4003FE (03673) DCS74 DJP R4,DCS71
(03674) ;
(03675) ;---- AT THE END OF EACH H-FRAME
(03676) ;
00420 2636 (03677) DCS75 INCR R3,6
00429 9A3003FF (03678) ANDIR R3,S03FF
(03679) ;
0042B 0C2003FC (03680) DCS76 DJP R2,DCS70
(03681) ;
(03682) ;---- END OF 3 H-FRAMES I.E. ONE INFO FRAME OF 189 BITS
(03683) ;
0042D 403A (03684) MOVHR R3,R5
(03685) ;
(03686) ;
0042E 0260 (03687) TEST R6
0042F 00200464 (03688) JMP DCS84,GTZ IF FRAME COVERED EXACTLY QUIT
(03689) ;
00431 90400000A (03690) MOVIR R4,SA LAST LEVEL, 11 MORE BITS
(03691) ;
00433 3A71 (03692) DCS77 LLS R7,1
(03693) IC827=0L+1
00434 F00004AC (03694) MOVHR R6,BASICB(R3)
00436 00700001 (03695) IORRR R7,R6,S0001
(03696) ;
00438 2631 (03697) INCR R3,1
00439 9A3003FF (03698) ANDIR R3,S03FF
(03699) ;
0043B 0000043C (03700) DECT21=0L+1
0043D F0000400 (03701) MOVHR R6,BASDECT(R7)

```

FOR NEXT CODE WORD  
SET UP OUT POINTER AFTER  
RPT INSTR HAS DECR IT BY LRUN+2

LOOP FOR NEXT INP

END OF H-FRAME PROCESSING

LOOP FOR 3 H-FRAMES

AT THE END OF 189 FRAME  
UPDATE TO NEXT INFO BIT

PAGE 93: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

08430 0010844E (03702)      JMP      DC879, EQZ      NOT YET CODE
0843F 00208462 (03703)      JMP      DC808, GTZ      CODE WORD
                                !LTZ, NULL OR RUN LENGTH
                                !---- NULL CODE
08441 F2008404 (03706)      CMPMR    R6, V8THR      THRESHOLD--16
08443 00208464 (03707)      JMP      DC804, GTZ      >THR, NULL CODE
                                !<THR, RUN LENGTH
                                !---- RUN LENGTH CODE, OUTPUT 14 1'S
08445 F0708110 (03711)      MOVMR    R7, LSRUN      COUNTER FOR 14 1'S
08447 00608002 (03712)      MOVIR    R6, S2      LEVEL 1*2
08449 341C      DC870      PUSHX1   R1, R6      OUTPUT TO BUFFER
0844A 0C708449 (03717)      DJP      R7, DC870
                                !
0844C 00008464 (03719)      JMP      DC884
0844E 0C408433 (03721)      DJP      R4, DC877
08450 00008464 (03722)      JMP      DC884
                                !
                                !---- LAST CODE WORD
08452 341C      DC880      PUSHX1   R1, R6
08453 00008464 (03729)      JMP      DC884
08455 403A      DC801      MOVRR    R3, R5
                                !
                                !---- AFTER A NULL CODE, PUT IN 5 EXTRA LEVEL 1'S
                                ! ONLY IF 0 SAMPLES OUT = 126
08456 0060807F (03736)      MOVIR    R6, S7F      126*1
08458 4062      SUBRR    R6, R1      126-(ADDR+N)
08459 FC0084AF (03738)      ADDMR    R6, BASOQB*1      126-(BASE ADDR+N)+BASE ADDR
0845B 01108464 (03739)      JMP      DC884, NEZ      N .NE. 126, NO EXTRA SAMPLES
                                !
0845D 00708004 (03741)      MOVIR    R7, S4      COUNTER FOR 5 1'S
0845F 00608002 (03742)      MOVIR    R6, S2      LEVEL 1*2
08461 341C      DC883      PUSHX1   R1, R6      OUTPUT LEVEL 1'S
08462 0C708461 (03745)      DJP      R7, DC883

```

```

PAGE 94: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

(03746) ;
(03747) ;
(03748) ; --- CHECK RECEIVER BUFFER FULL
(03749) ;
(03750) DCS84
(03751) MOVNR R7, SZSSHAT
(03752) MOVNR R6, PSSSHAT
(03753) SUBIR R6, 57F
(03754) SUBMR R1, BASOQB+1
(03755) ADDR R6, R1
(03756) CHPR R6, R7
(03757) JMP DCS86, LEZ
(03758) SUBRR R6, R7
(03759) SUBRR R1, R6
(03760) MOVNR R6, R7
(03761) JMP DCS89
(03762) ;
(03763) ; --- CHECK RECEIVER BUFFER EMPTY CONDITION
(03764) DCS86
(03765) CHPR R6, 58
(03766) JMP DCS89, GEZ
(03767) ;
(03768) MOVIR R7, 52
(03769) OQB26=OL+1
(03770) DCS87
(03771) MOVNR R7, BASOQB(R1)
(03772) INCR R1, 1
(03773) IJN R6, DCS87
(03774) ;
(03775) CLR R6
(03776) DCS89
(03777) MOVNR R6, PSSSHAT
(03778) ; --- NULL CODE
(03779) ;
(03780) MOVIR R6, 5C
(03781) NEG R6
(03782) OQB27=OL+1
(03783) MOVNR R6, BASOQB(R1)
(03784) ;
(03785) ; 5, UPDATE FOR NEXT OPERATION OF DECODER
(03786) ;
(03787) ; --- NEXT INFO BIT POINTER
(03788) MOVNR R3, PSINFO
(03789) ;

GET REC BUFFER SIZE
REC BUFFER POINTER
SAMPLES REMOVED FROM BUFF. 126+1
COMPUTE # SAMPLES OUTPUT
SAMPLES ADDED TO SHAT BUFF.
(BUFF. POINTER - BUFF. SIZE)
NOT FULL. JMP AND PROCEED
NO. OF EXTRA SAMPLES
DELETE THE EXTRA SAMPLES
SHAT POINTER = 1024
GO FOR END CODE

(BUFF POINTER - 0)
NOT EMPTY, PROCEED
IF EMPTY, FILL WITH LEVEL 1'S
LEVEL 1*2

OUTPUT LEVEL 1
OUT IND

SHAT POINTER = 0
SAVE NEW SHAT POINTER

NULL CODE = -12

```

PAGE 95: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(03798) ;--- NEXT BIT1 POINTER
(03791) ;
0540A F05054B9      MOVMR R5,PSBIT1
0540C 9C500000      ADDIR R5,SBD
0540E 9A5003FF      ANDIR R5,S03FF
05490 E05054B9      MOVMR R5,PSBIT1
(03796) ;
(03797) ;--- NEXT BASE OF FRAME
(03798) MOVMR R3,PSBASE
05494 9C300000      ADDIR R3,SBD
05496 9A3003FF      ANDIR R3,S03FF
05498 E03054B8      MOVMR R3,PSBASE
(03802) ;
(03803) ;--- NEXT SYNC VALUE
(03804) MOVMR R7,S0001
0549A 90700001      XORRM R7,VSSVNC
0549C F07054CF      ;
(03806) ;
(03807) ;--- FUNCTION LIST SELECTOR ISL2
(03808) MOVMR R2,SIDSISL
0549E F02054B6      INCR R2,1
054A0 2621          MOVMR R3,ISVTS(R2)
054A1 F0340502      NEG R3
054A3 0030         MOVMR R3,ISVTS(R2)
054A4 E0340502      ;
(03813) ;
(03814) ;--- ALL DONE. SO RETURN
(03815) ;
(03816) ;
(03817) ;--- UPDATE XMTR BEFORE RETURNING
(03818) ;
054A6 0E70         RETURN
(03819) DCS90      MOVMR R1,SIDSISL
(03821) DCS90      INCR R1,2
054A7 2612          ADDIR R1,ISVTS
054A8 9C100502      JMR TXS
054AA 00004036      ;
(03824) ;
(03825) ;--- LEAVE SPACE FOR VARIOUS VARIABLES
(03826) ;
(03827) ;
(03828) BAS1CB      DATA F'0.0.'
054AC 00000000      BASOQB      DATA F'0.0.'
054AE 00000000      BASDECT     DATA F'0.0.'
054B0 00000000      BASDECB     DATA 00
054B2 00000000      BASFCB      DATA 00
054B4 0000         SIDSTB      DATA 00
054B6 0000

```

SID FOR FUNC SEL.  
POINT TO IFSEL3  
COMPUT ADDR FOR IFSEL3  
GO TO XMTR UPDATE MODULE

```

PAGE 96:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 35, 1988

85486 8888      (83834) SIDISL      SS
85487 8888      (83835) PSSHAT     SS
85488 8888      (83836) PSBASE     SSSSS
85489 8888      (83837) PSBIT1     SS
8548A 8888      (83838) PSINFO     SS
8548B 888888888 (83839) PSMAX      10F'.B.'
      ...
854CF 8881      (83848) VSSYNC      S1
854D0 8888      (83841) VST        SS
854D1 8888      (83842) VSBETA     SS
854D2 8888      (83843) VSPH8      SS
854D3 4888      (83844) VSPAR      S4888
854D4 FFE8      (83845) VSTHR      DATA $FFEE
854D5 8858      (83846) VSCAP      SS
854D6 F388      (83847) SZSSHAT     DATA $388
854D7 8858      (83848) TSLIM      DATA $58
      ...
      (83849) *LSRUN      DATA SD
      (83850) ;
      (83851) ;
      (83852) ; --- UPDATE TOP OF MEMORY
      (83853) ;
      8888854D8 (83854)      TOESNEW=0L
      88888288 (83855)      #L=TOESPRT
      88288 881854D8 (83856)      ADDR TOESNEW(.BUS18)
      8828A      (83857)      END

```

;SIZE=944





PAGE 98: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

DC821:	MS33E (M3484) (M3421)	
DC828:	MS347 (M3431) (M3479)	
DC831:	MS353 (M3448) (M3448)	
DC832:	MS361 (M3456) (M3456)	
DC833:	MS377 (M3478) (M3478)	
DC838:	MS3A2 (M3503) (M3532)	
DC851:	MS388 (M3558) (M3554)	
DC860:	MS38F (M3566) (M3574)	
DC861:	MS3D1 (M3584) (M3584)	
DC862:	MS3D4 (M3587) (M3595)	
DC863:	MS3E8 (M3608) (M3608)	
DC878:	MS3FC (M3629) (M3688)	
DC871:	MS3FE (M3627) (M3631)	(M3644) (M3664) (M3673)
DC872:	MS418 (M3641) (M3658)	
DC873:	MS424 (M3642) (M3678)	
DC874:	MS426 (M3673)	
DC875:	MS428 (M3646) (M3666)	(M3677)
DC876:	MS428 (M3688)	
DC877:	MS433 (M3692) (M3722)	
DC878:	MS448 (M3716) (M3717)	
DC879:	MS44E (M3782) (M3722)	
DC888:	MS482 (M3783) (M3727)	
DC881:	MS488 (M3681) (M3731)	
DC882:	MS486 (M3736)	
DC883:	MS481 (M3744) (M3745)	
DC884:	MS484 (M3688) (M3788)	(M3728) (M3723) (M3729) (M3739) (M3758)
DC886:	MS478 (M3756) (M3764)	
DC887:	MS478 (M3789) (M3771)	
DC889:	MS481 (M3768) (M3765)	(M3775)
DC890:	MS4A6 (M3348) (M3373)	(M3525) (M3819)
DC893:	MS182 (M8877) (M2928)	
DEC818:	MS2E6 (M3217) (M3316)	
DEC828:	MS3DF (M3219) (M3697)	
DEC88:	MS314 (M2933) (M3383)	
DEC728:	MS487 (M3232) (M3639)	
DEC721:	MS43C (M3233) (M3788)	
DMY8:	MS794 (M8436) (M8918)	(M8911) (M8913) (M8914)
EN8188:	MS8CD (M2586)	
EN8181:	MS8D5 (M2592) (M2688)	
EN8182:	MS8E4 (M2588) (M2588)	(M2684)
EN8111:	MS8E2 (M2597) (M2688)	
EN838:	MS8FF6 (M2412) (M2416)	
EN848:	MS885 (M2429) (M2437)	
EN858:	MS818 (M2446) (M2448)	

--- JAN. 30, 1988

MAP MODULES FOR THE P A R C ALGORITHM

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```

EN851: 0001F (02442) (02451)
EN852: 00020 (02451) (02459)
EN853: 00030 (02476) (02483)
EN854: 0004A (02478) (02486) (02505) (02535)
EN855: 00054 (02480) (02491) (02549)
EN856: 00066 (02492) (02502)
EN857: 00068 (02489) (02509)
EN858: 0006E (02511) (02516)
EN859: 0007D (02522) (02532)
EN860: 00092 (02515) (02539)
EN861: 00095 (02541) (02547)
EN862: 000A3 (02513) (02553)
EN863: 000A6 (02555) (02562)
EN864: 000B2 (02498) (02566)
EN865: 000BC (02572) (02582)
EN866: 000C2 (00076) (02363)
EN867: 0007B (02126) (02228)
EN868: 00081 (00063)
EN869: 0006E (00074) (00078)
EN870: 000FB (00462) (00463)
EN871: 000F2 (01040) (01041)
EN872: 000F3 (01734) (01735)
EN873: 000C4 (00058) (00075)
EN874: 000A2 (01381) (01486) (01488)
EN875: 0002A (00047)
EN876: 0006F (00098) (00953)
EN877: 00028 (01831) (01833)
EN878: 000BC (01118) (01112)
EN879: 0010D (02993) (03046)
EN880: 00297 (02994) (03245)
EN881: 002A9 (02995) (03289)
EN882: 002C8 (02996) (03287)
EN883: 002D0 (02997) (03387)
EN884: 00355 (02999) (03441)
EN885: 00363 (03000) (03457)
EN886: 00376 (03001) (03476)
EN887: 00383 (03002) (03494)
EN888: 003C1 (03003) (03567)
EN889: 00306 (03004) (03588)
EN890: 00408 (03005) (03632)
EN891: 00435 (03006) (03693)
EN892: 00112 (02364) (02424) (02455) (02657)
EN893: 00176 (02951) (02952)
EN894: 00193 (02979) (02988)

```

PAGE 100: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1968

```

INCSZ: 04A0F (00277) (00070)
INCSZ: 04A0F (00279) (00095)
INFSB: 04A0B (00275) (00081)
INFTM: 04A07 (00273) (00034)
INCSZ: 04AF1 (00281) (00055)
INCSZ: 04AF1 (00271) (00029)
INCSZ: 04AF1 (00284) (02107)
INRC: 04F10 (00284) (02107)
INRX: 04C01 (00282) (01500)
INI: 0004A (00090) (00090)
IN2: 00047 (00094) (00054)
IN4: 00043 (00090) (00092)
IN8: 0615E (02017)
IN8: 0615F (02761) (02709)
IN8: 0406C (00081) (00269)
IN18: 05170 (02944)
IN18: 05170 (00059)
IN18: 05170 (02738) (02756)
IN18: 05170 (03367) (03369)
IN18: 05170 (00064) (00136)
IN18: 05170 (00065) (00138)
IN18: 05170 (00066) (00147)
IN18: 05170 (00067) (00152)
IN18: 05170 (00068) (00200)
IN18: 05170 (00295) (02509)
IN18: 05170 (00506) (00619)
IN18: 05170 (00544) (00583)
IN18: 05170 (00490) (00511)
IN18: 05170 (00720) (00754)
IN18: 05170 (00730) (00751)
IN18: 05170 (00591) (00600)
IN18: 05170 (00612) (00621)
IN18: 05170 (00625) (00633)
IN18: 05170 (00655) (00678)
IN18: 05170 (00435) (00707)
IN18: 05170 (02009) (02090)
IN18: 05170 (00062) (00201)
IN18: 05170 (00134) (00355)
IN18: 05170 (00202) (00206)
IN18: 05170 (01206) (01433)
IN18: 05170 (00036) (00038)
IN18: 05170 (02097) (02098)
IN18: 05170 (00039) (00067)
IN18: 05170 (01404)
IN18: 05262 (03104) (03190)

ISVT18: 05170 (00065) (00066) (00067) (00068) (00130) (00203) (00270) (00347)
ISVT28: 05170 (02767) (02784) (02932) (02945) (03141) (03143) (03145) (03347)
ISVT38: 05170 (03386) (03517) (03519) (03521) (03810) (03812) (03822)
ISVT48: 05170 (00286) (00272)
ISVT58: 05170 (00219) (00274) (00350)
LSRUN: 05170 (02539) (02553) (02660) (03653) (03661) (03713)
LOOP0: 05170 (00634)
LOOP1: 05170 (00756)
LOOP2: 05170 (00756)
LOOP3: 05170 (00756)
LOOP4: 05170 (00756)
LOOP5: 05170 (00756)
LOOP6: 05170 (00756)
LOOP7: 05170 (00756)
LOOP8: 05170 (00756)
LOOP9: 05170 (00756)
N00: 05170 (00788) (00930) (01407) (01408) (01557) (02044) (02045) (02059)

MSK08VT: 05170 (00269) (00346)
N0RC: 05170 (00456) (00457)
N0TX: 05170 (00455)
NEGA: 05170 (01206) (01433)
NEXT1: 05170 (00036) (00038)
N0MAX: 05170 (02097) (02098)
N0PTR: 05170 (00039) (00067)
NULL1: 05170 (01404)
O0001: 05262 (03104) (03190)

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PAGE 181: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1985

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OQB2: 0526A (03105) (03196)
OQB3: 05194 (02967) (02978)
OQB11: 051E2 (02968) (03054)
OQB12: 051EA (02969) (03061)
OQB13: 051FB (02970) (03069)
OQB14: 051F8 (02971) (03076)
OQB15: 05206 (02972) (03098)
OQB26: 0547C (03422) (03768)
OQB27: 05487 (03423) (03781)
PBASE: 05488 (02299) (03036) (03125) (03128) (03358) (03361) (03587) (03518) (03798) (03881)
      (03836)
PBB17: 05489 (03135) (03238) (03255) (03272) (03288) (03429) (03618) (03792) (03795) (03837)
PBI10: 0548A (03331) (03617) (03624) (03788) (03838)
PSMAX: 0548B (02951) (03026) (03027) (03094) (03183) (03189) (03839)
PSMAT: 05487 (03283) (03852) (03751) (03775) (03835)
PAR81: 050F1 (02622) (02627)
PAROUT8: 050EF (02588) (02638) (02546) (02561) (02588) (02598) (02621)
PCRC8: 04086 (01737) (01751)
PCRC8SA: 05088 (01748) (01764) (02818)
PCRC8SZ: 0509A (01749) (02818)
PCTX8: 0508B (01054) (01057) (01444)
PCTX8SA: 0508C (01055) (01444)
PCTX8SZ: 0508D (00476) (00493) (00788)
PERIOD: 05029 (00538) (00566)
PICH38: 040A6 (00485) (00479) (00788)
PICH38SA: 0508B (00477) (00788)
PICH38SZ: 0508C (00479) (01081)
PRE1: 0502C (01849) (01981)
PRE2: 0503F (01071) (01077)
PRE3: 05011 (01105) (01113) (01136) (01382)
OCKP: 0501D (01147) (01149) (01897)
QUAN: 05046 (01092) (01093) (01268)
QUAN1: 05052 (01272) (01273)
QUAN2: 0506D (01283) (01442)
QUAN3: 05065 (01294) (01439)
QUAN4: 05075 (01381) (01311)
QUAN5: 05078 (01318) (01314) (01317)
QUAN6: 0508F (01278) (01441)
RC8: 04088 (00879) (00126)
RCIN18: 04098 (00982) (00346)
RCPI1: 050AF (01197) (01198) (01422)
RECORD: 05068 (00691) (00942)
RESET: 050A9 (00782) (00788)

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PAGE 182: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

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SSTX:      04A1D (00213) (00222) (00289) (00789)
SC81B:     051C8 (03026) (03029)
SC82B:     051DA (03048) (03083)
SC821:     051E9 (03088) (03082)
SC822:     051EE (03088) (03088)
SC823:     051F7 (03073) (03077)
SC824:     051F9 (03064) (03081)
SC831:     0520B (03092) (03096) (03101)
SC841:     0520F (03109) (03111)
SC851:     0521C (03118) (03121)
SC852:     05261 (03191) (03192)
SC853:     05298 (03244) (03250)
SC854:     052AB (03257) (03266)
SC8541:    052BE (03270) (03280)
SC855:     052C6 (03296) (03293)
SC856:     052D8 (03303) (03321)
SC857:     052D8 (03306) (03314)
SC858:     052EF (03318) (03327)
SC859:     052F8 (03345)
SC87B:     052FD (03110) (03353)
SH8RC:     04F0F (00141) (00151)
SHIFT:     00051 (01007) (01008)
SI081SL:   054B6 (02931) (03139)
SI087B:    054B5 (03403) (03417)
SIGNAL:     00090 (01029) (02007)
SIZES:     05160 (02775) (02819)
START:     00008 (01497)
SVT8:      00302 (00060) (00120) (00442) (02426) (03161) (03165) (03535) (03541)
SVT111B:   00464 (00454) (00486) (02231)
SVT115B:   00468 (00457) (00458) (02038)
SVT117B:   0046C (00488) (00489) (00784)
SVT118B:   0046E (00489) (01485) (00783)
SVT50B:    003E6 (00442) (00443) (00047)
SVT51B:    003EE (00444) (00445) (00076)
SVT54B:    003F2 (00445) (00446) (00924)
SVT55B:    00404 (00446) (00447) (01480) (01643)
SVT60B:    0040E (00447) (00448) (01506)
SVT70B:    00412 (00448) (00449) (01529)
SVT74B:    0041A (00449) (00450) (01558)
SVT79B:    00426 (00450) (00451) (01583)
SVT83B:    0042E (00451) (00452) (01642)
SVT90B:    00446 (00452) (00453) (02048)
SVT99B:    0044A (00453) (00454) (02233)

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PAGE 183: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1968

SYNCS:	551C8 (52934) (53823)		
SV38FLGS:	1FFCE (55561) (55143)	(55146) (55215) (55218) (55353)	
SZSSHAT:	554D6 (53281) (53755)	(53847)	
TSLIM:	554D7 (53848)		
TSRC:	54F13 (55132) (52895)		
TOESNEW:	554D8 (53854) (53856)		
TOESPRAT:	55208 (55438) (53855)		
TR918:	5512A (52745) (52755)		
TR825:	55135 (52739) (52766)		
TR825:	5513F (52762) (52775)		
TR838:	55148 (52795) (52804)		
TR8DC:	55116 (55078) (52735)		
TRAN:	55058 (51772) (51783)		
TX8:	54836 (55085) (55251)	(53823)	
VSBETA:	554D1 (53327) (53545)	(53658) (53842)	
VSDCL:	55114 (55297) (52474)	(52659)	
VSCAP:	554D5 (53512) (53551)	(53846)	
VSPAR:	554D3 (53336) (53489)	(53551) (53844)	
VSPHB:	554D2 (53355) (53319)	(53546) (53581)	(53652) (53843)
VSSYN:	55113 (52411) (52418)	(52658)	
VSSYNC:	554CF (53842) (53125)	(53354) (53492) (53845)	
VST:	554D5 (53295) (53534)	(53576) (53841)	
VSTHR:	554D4 (53655) (53757)	(53845)	
VADAP:	55558 (52192)		
VCHECK:	55572 (51555)	(51521) (51633) (51635)	
VCONT1:	55545 (51567) (51568)	(51578)	
VEND:	55575 (51634) (51641)		
VGAP:	5551A (51513) (51525)		
VH8RC:	54F2D (55133) (55145)	(55348) (52124)	
VH8TX:	54A25 (55259) (55212)	(55288) (55795)	
VLOOP:	55523 (51529) (51633)		
VLOOP1:	55535 (55865) (55866)		
VLOOP2:	5555E (55799) (55811)		
VLOOP3:	5551A (55798) (55811)		
VLOOP4:	5551C (55813) (55816)		
VLOP1:	5552D (52189) (52118)		
VLOP2:	55571 (52221) (52223)		
VNEGA:	55555 (51591) (51593)	(51594)	
VPCRC8:	54EC2 (51738) (52519)	(52526) (52252)	
VPCRC9A:	54F56 (52522) (52242)		
VPCRC81:	54F5E (52518) (52255)		
VPCRC85:	55513 (52519) (52559)		
VPCRC8Z:	55155 (52521) (52252)		
VPCTX8:	54C84 (51844) (51453)	(51459) (51662)	

PAGE 184: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1985

VPCTH8A: B4C92 (B1486) (B1682)  
 VPCTH8I: B4B02 (B1482) (B1668)  
 VPCTH8S: B0030 (B1483) (B1687)  
 VPCTH8Z: B0109 (B1488) (B1682) (B0773) (B0969)  
 VPICH38: B4A8E (B0486) (B0767)  
 VPICH38A: B4A16 (B0778) (B0968)  
 VPICH38I: B4AF6 (B0766) (B0967)  
 VPICH38S: B0060 (B0767) (B0930)  
 VPICH38Z: B00EA (B0769) (B0969)  
 VPRE1: B0037 (B2134) (B2222)  
 VQ1: B004C (B2166) (B2166) (B2169)  
 VQ3: B0061 (B2165) (B2178) (B1584)  
 VQUARI: B0046 (B1579) (B1581)  
 VQUAH2: B004C (B1587) (B1588)  
 VQUAH3: B004F (B1579) (B1588)  
 VTRAR: B000D (B2047) (B2052)  
 WAIT: B0086 (B0630) (B0631)  
 WRD4: B0003 (B0009) (B0126)  
 WRD6: B0004 (B0078) (B0129)

LINE WITH ERRORS: B (MAP VERSION 000101.10) E- B



PAGE 10

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      *** IOSDC ***
      ARVIND S. ARORA
      FEB 11, 1968

      IOS-2 PROGRAM TO INTERFACE THE BITSTREAM FROM THE PARC ALGORITHM
      TO THE MODEN. THE SOURCE CODER AT THE TRANSMITTER STORES THE OUTPUT
      IN A DOUBLE BUFFER, AND THE DECODER REQUIRES ITS INPUT TO BE IN A
      CIRCULAR BUFFER. THIS PROGRAM OUTPUTS THE CONTENTS OF THE DOUBLE
      BUFFERS THROUGH THE IOS2 TO THE DIGITAL INTERFACE, AND INPUTS THE
      RECEIVED BITSTREAM OF THE DIGITAL INTERFACE TO THE CIRCULAR BUFFER.
      THE PROGRAM OPERATES IN FULL DUPLEX FOR COMPATIBILITY WITH THE
      RS-423 MODEN USED IN THE PRESENT SYSTEM.

      REGISTER & FLAG USAGE:
      RB: XMTR BUFFER SWITCH, RB=ADSTX TO INDICATE BUFFER 1
      R1: XMTR BUFFER ADDRESS POINTER
      R2: RCVR BUFFER ADDRESS POINTER
      F1: FLAG TO INDICATE MODE OF OPERATION,
          F1-CLEAR TO INDICATE INITIALIZE
          F1-SET TO INDICATE NORMAL OPERATION
      P1: FLAG SET INDICATES RECEIVER DATUM AVAILABLE
      P2: FLAG SET INDICATES XMTR READY FOR NEXT DATUM

      ----- IOS-2 MODULE
      ---
      SYMBOL DEFINITIONS
      ADSTXA=D'25700'
      ADSTXB=D'27700'
      SZSTX =D'100'
      ENDSTXA=ADSTXA+SZSTX-1
      ENDSTXB=ADSTXB+SZSTX-1
      AD8RC=D'29000'
      SZ8RC=D'1024'
      END8RC=AD8RC+SZ8RC-1
      CLCRATE=8000

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PAGE 4:

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ADDRCC: 07140 (00040) (00042) (00061) (00100) (00092)
ADSTXA: 06464 (00034) (00037) (00060) (00091) (00082)
ADSTXB: 06C34 (00035) (00038) (00073) (00081) (00082)
CLCRATE: 06C04 (00044) (00063)
ENDSRCC: 07547 (00042) (00099)
ENDSTXA: 06520 (00037) (00070)
ENDSTXB: 06C00 (00038) (00080)
IOSINIT: 00004 (00060) (00060) (00093) (00099) (00101)
IOSLOOP: 00007 (00066) (00070) (00080) (00080) (00101)
IOSSTOP: 00020 (00100)
IOSDCS: 00000 (00063)
RCC: 00010 (00067) (00097)
SZSRC: 00400 (00041) (00042)
STXTX: 00000 (00036) (00037) (00038)
TXS: 00000 (00066) (00072)
TXAS: 00000 (00077)
TXS: 00017 (00073) (00087)

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LINES WITH ERRORS: 0 (MAP VERSION 000101.10) E- 0